

# CNC ROTARY TABLE SERIES





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■Please give your order to the following agent

D.RA.1

Specifications are subject to change without notice.

# Made in Japan, Made by

NIKKEN is the manufacturers of CNC rotary tables that designs and manufactures in-house the key components of its rotary tables in order to realize the exceptional performance for customer requirements.

#### ■Spirit of Innovation In pursuit of exceptional performance

Our name "NIKKEN" means "Doing research & study every day", and this expresses the spirit of our company. This spirit is alive in every component of our CNC rotary tables. To achieve unmatched high precision, high rigidity, and durability, we utilize a variety of key components incorporating our own innovative ideas, rather than relying on off-the-shelf parts.

#### Long Life Concept In-house design and manufacturing for secure environment

Although our products are highly durable, it is naturally to replace parts occasionally. Since the key components are manufactured in-house, our customers avoid the risk of not being able to perform product repairs due to being discontinued off-the-shelf parts. You can continue to rely on our high-precision products under secure environment over the long term.

#### The Heart of NIKKEN CNC Rotary Table

#### Carbide Worm Screw System •



#### ■ Carbide Worm Screw

Carbide worm screw (Material: V grade carbide), hard and strong against high speed rotation, is used with ultra heavy duty, maintaining the high accuracy semi-permanently.

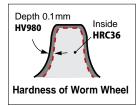
Comparing with the traditional worm system (steel worm screw and phosphor/aluminum bronze worm wheel), wearing of worm wheel is largely reduced

and rotary table can be used for longer years, resulting in great cost-down. For better impact capability, the special alloy steel worm screw is used for the worm system of the small tooth module.



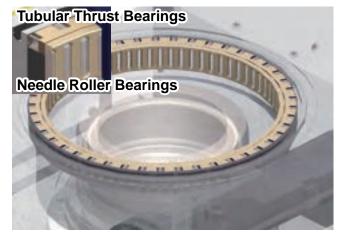
#### Harden Worm Wheel

The material used for the NIKKEN worm wheel is custom made steel, specially hardened and ion-nitrided on the teeth to eliminate the friction and gear wear.



Unique "Bearing system"

#### Independent Double Thrust and Radial Bearing System ●



NIKKEN bearing system allow for more points of contact versus conventional cross roller bearings, resulting in smooth and accurate rotation.

#### ■Thrust:Tubular Roller Bearings

Tubular thrust bearings are pre-loaded for rigidity, and dampen vibration.

#### ■ Radial: Needle Roller Bearings

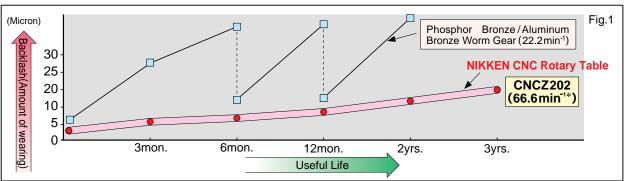
"Hand picked and matched" needle roller bearings between rotary table body and table spindle are implemented for the high accuracy and rigidity.

# NIKKEN.

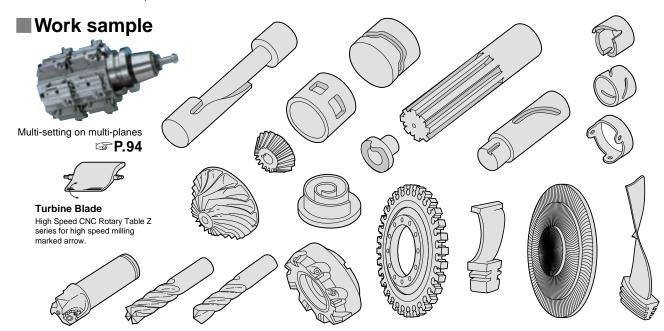




Our thoroughgoing passion for high rigidity and high precision results in products of excellent durability that retain their precision even after long-term use. This boosts the operating ratio and cuts maintenance costs, contributing to a substantial reduction in costs overall.



\*It is the value of motor 3,000min<sup>-1</sup>.



## NIKKEN CNC rotary table extensive





COMPACT P7 - P10 CNC105, 180, 202, 205





LARGE P15 - P16 CNC1000, 1200, 1201, 1600



TOP SIDE MOTOR MOUNTED P17 - P20 CNC202T, 260T, 302T 321T, 401T, 501T, 601T



BACK SIDE MOTOR MOUNTED P21 - P22 CNC180B, 202B, 260B 302B, 321B, 401B



BIG BORE P23 - P24 CNCB350, B450, B630



CNC100-2W, 3W, 4W, 180-2W, 202-2W, 260-2W





COMPACT P27 - P32 NCT200, NCT200E









### **NIKKEN**

## lineup to match your own applications.





COMPACT P37 - P40 5AX-100, 130, 201



5AX-230, 250, 350, 550



LARGE P45 - P46 5AX-800, 1200



5AX-2MT-105, 4MT-105

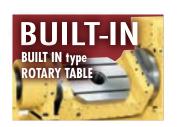




Notes on the Use of DD TABLES



DD P51 - P54 DD180, 251, 400











Servo Motor List • Relation between Unbalancing load and Servo Motor • Flow Chart of the Addtional Axis Control







TECHNICAL INFORMATION P75 - P78

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# TEC TECHNICAL INFORMATION Accuracy Standard P99 – P100 Description of Specifications, Recommended lubricating Oil and Quantity P101 – P102 Assessment P103 Load Calculation, Indexing Time, Comparaison, Durability P104 Technical Information P105

CLAMPING DEVICE and T-NUT · · · · · · · · · P85 - P86

NET WORLD	OWIDE NETWORK
Overseas Sales & Servic Worldwide Sales Branch	P107 e Network····P108 – P110 P111 Specifications of CHC Rotary Table··P117 P118

### **How to Select Your Best CNC Rotary Table**



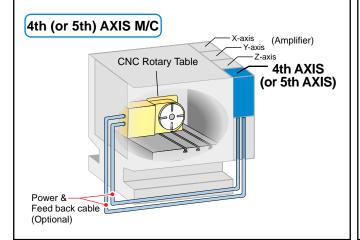
#### 1 How CNC Rotary Table is Controlled

#### Additional Axis

You can choose additional axis when the machine has 4th or 5th axis.

CNC rotary table can be controlled by machine in this case.

- 1. 4th or 5th amplifier is required for the machine. It should be used exactly the same one used for X, Y and Z axis. Install same type of servomotor(s) used for X, Y and Z axis.
- 2. The capacity of the servomotor or amplifier is defined by the types of rotary table.
- 3. Decide who supplied the servomotor.
- 4. External dimensions and specifications depend on the type of servomotor.
- 5. Parameter configuration, hydraulic connection, wiring and installation of amplifiers should be provided by machine tool

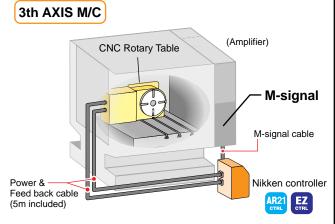


#### **NIKKEN Controller (M-signal)**

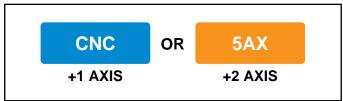
You can choose NIKKEN Controller when the machine doesn't have additional axis.

Note: at least one M-signal code is required.

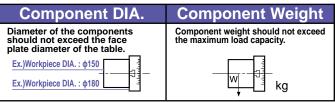
- 1. At least one M-Signal is required on the machine.
- 2. Input M-signal as "index start" command on the machine, high accuracy indexing, equally divided indexing (2-9999), or lead operation is allowed.
- 3. Control unit, servo-motor and all cables will be supplied by NIKKEN.



#### 2 Select +1 AXIS or +2 AXIS

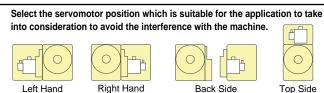


#### 3 Select Face Plate Diameter



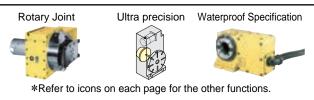
#### 4 Select the Servomotor Position 🚨 🦺 🛄 🖺 5 High Speed or Standard?

Top Side









#### 7 Select Accessories

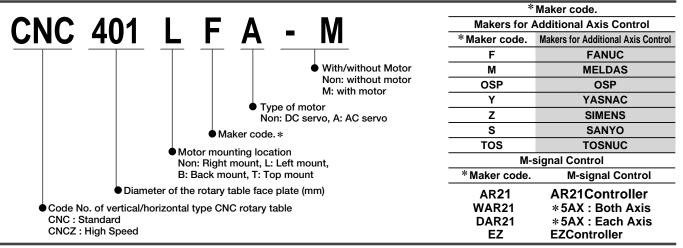


8 Icon list (In this catalog, table Specifications, accessories, and opion are displayed as icons.)

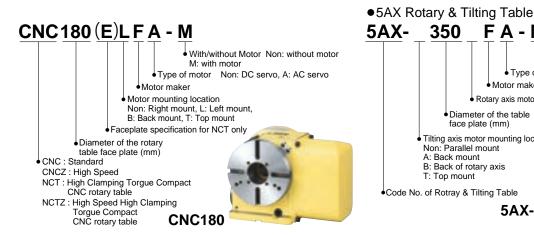


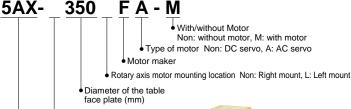
### **How to Read Product Code**





Servomotors for Brother **SPEEDIO** is exclusive. EX.)NCT □ 200 □ SA-BR3 The last part of the product code must be "SA-BR2".

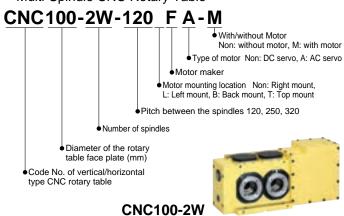




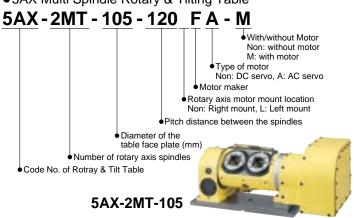
- Tilting axis motor mounting location Non: Parallel mount A: Back mount B: Back of rotary axis T: Top mount
- Code No. of Rotray & Tilting Table

5AX-350

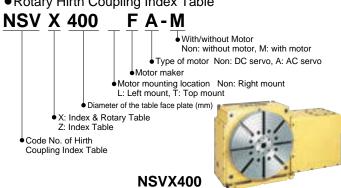
Multi-Spindle CNC Rotary Table



●5AX Multi Spindle Rotary & Tilting Table



Rotary Hirth Coupling Index Table



Manual Tilting CNC Rotary Table



### **COMPACT CNC ROTARY TABLE**





**CNC105** and accessories

- Wide application can be offered from small drilling press to M/C
- Suitable for indexing/leads cutting of small size work pieces
- Various kinds of the work chucking attachments can be offered from 5C collet fixtures to the air/hyd. chuck

#### Option **Accessories** ACCURACY ADD. ROTARY ULTRA SCROLL POWER CLAMP T-NUT **AXIS** JOINT STOCK CHUCK P.89 P.79 P.83 P.84 P.85 P.86

#### Specifications

#### ( ):High Speed CNC ROTARY Table Z series

Item / Code No.		CNC105 CNCZ105	CNC180 CNCZ180	CNC202 CNCZ202
Diameter of Table ¢mm		105	180	200
Diameter of S	pindle Hole	Ф60нт Ф30	Ф60нт Ф40	Ф60н7 Ф40
Center Height	mm	105	135	135
Width of T Slo	ot mm	Ф10H7 Pin hole	12 +0.018	12 +0.018
Clamping Sys	tem	Pneumatic*4	Pneumatic*4	Pneumatic*4
Clamping Tore		205	303	303
Table Inertia at M	lotor Shaft (GD <sup>2</sup> /4) kg·m <sup>2</sup> ×10 <sup>-3</sup>	0.06	0.08	0.09
Servo Motor	r/min	α iF1⋅3000	α iF2·3000	α iF4•3000
MIN. Increme	nt	0.001°	0.001°	0.001°
Rotation Spee	ed*5 r/min	33.3(66.6)	33.3(66.6)	33.3(66.6)
Total Reduction	on Ratio	1/90(1/45)	1/90(1/45)	1/90(1/45)
Indexing Accu	iracy sec	±30	±20	±20
Net Weight	kg	32	45	55
MAX. Work Load	Vertical kg	30	100	100
on the Table	Horizontal kg	60	200	200
MAX.	N N	8800	18000	18000
Thrust Load applicable on the	*1 F×L N·m	275	542	542
Table	FXL N·m	220	690	690
Guide Line of MAX. Unbalancing Load	e of MAX. *2		30	50
MAX. Work Inertia	Vertical $\left(\frac{GD^2}{4}\right)$ kg·m <sup>2</sup>	0.04(0.02)	0.4(0.2)	1.0(0.5)
Driving Torque	*3 N·m	36(27)	72(54)	144(115)

- \*1 This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.
- \*2 The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer to P.57 for more detail.
- \*3 Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.
- \*4 Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. 🖙 P.95
- \*5 The table rotation speed when the motor rotates at 3000r/min. Depending on the application(unbalance of the jig,work) and the motor specification, the motor may not be able to rotate at 3000r/min. ★ ⟨xiF4/5000 motor can be mounted on CNC180.



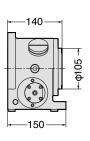
# CNC105, 180, 202

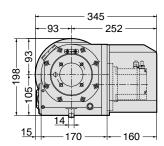


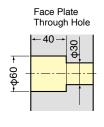
External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### **CNC105, CNCZ105**















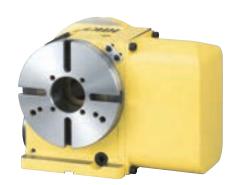


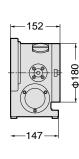


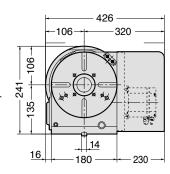


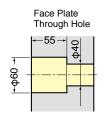
Air purge function is provided inside the motor cover as standard.

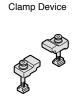
#### CNC180, CNCZ180

















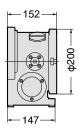


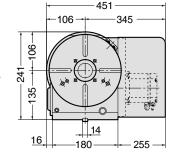


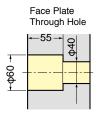
Air purge function is provided inside the motor cover as standard.

### **CNC202, CNCZ202**





















Air purge function is provided inside the motor cover as standard.

### **COMPACT CNC ROTARY TABLE**





Ultra Slim Model for Trunnion Application

# **CNC205**



### 380Nm

Air-hydraulic Unit Provided as Standard Equipment

Astoundingly powerful clamping capability in spite of the slim body

For machines with no hydraulic power source, the air-hydro unit provides powerful hydraulic supply functionality using only an air supply. In spite of its slim body, it delivers an astounding 380 Nm of clamping power, enabling a variety of applications, such as use of a cradle jig.

### **Ultra-Slim 98mm**

**Ultrathin Specification to Maximize Machining Space** 

Demonstrates the true worth of a compact machining center with limited machining space.

The body thickness of 98mm is 54mm slimmer than previous models. Allows enlargement of the cradle jig work mounting area on machines with limited machining space, such as the BT30 compact machining center.

## High Speed

Z Type is also Available

Reducing cycle time enhances productivity

The lineup also includes the highly rotatable Z type that further reduces machining cycle time. By setting the speed reduction ratio to 1/2 that of the standard type, 200% speedup is achieved.

# **Built-in Rotary Joint**

**Supports Mounting of Built-in Rotary Joints** 

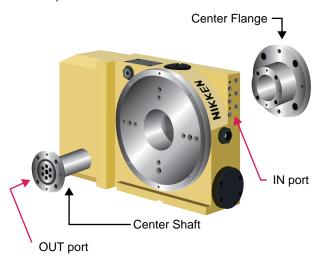
Automated component mounting/unmounting with minimal increase in size.

The rotary table body is already provided with IN ports, so the rotary joint specification can be changed with minimal increase in the body dimensions.

### **Ultra-slim Support**

Ultrathin Support Table is also Available.

Contributes to a further expansion of machining area when used with the CNC205.



Ultrathin Support Table with Clamping System

Ex.)
Trunnion Application with
CNC205L and a Support Table

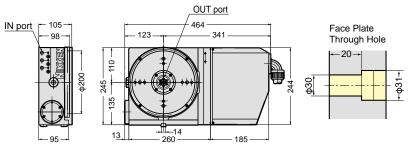












Rotary joint shown in photo is optional.

\*Rotary joint is included in the layout with AR21 controller.

#### Specifications

Iter	n / Code No.	Standard	High Speed
Right Hand	Mounted Moter	CNC205	CNCZ205
Left Hand M	ounted Moter	CNC205L	CNCZ205L
Diameter of T	able	200	200
Diameter of S	pindle Hole	ф30н7	Ф30н7
Center Height	t mm	135	135
Width of T Slo	ot mm	_	_
Clamping Sys	stem	Air Hydraulic Booster Built-in type	Air Hydraulic Booster Built-in type
Clamping Tor	·	380	380
Table Inertia at	Motor Shaft $(\frac{GD^2}{4})$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	0.15	0.15
Servo Motor	r/min	α iF2∙3000	α iF2•3000
MIN. Increme		0.001°	0.001°
Rotation Spec	ed*4 r/min	33.3	66.6
Total Reduction	on Ratio	1/90	1/45
Indexing Accu	ıracy sec	±20	±20
Net Weight	kg	45	45
MAX. Work Load	Vertical kg	100 (with suppart)	100 (with suppart)
on the Table	Horizontal kg	_	_
MAX. Thrust Load	*1 FXL N·m	670	670
applicable on the Table	FXL N·m	690	690
Guide Line of MAX. Unbalancing Load	*2 N·m	30	30
MAX. Work Inertia	Vertical $\int \frac{GD^2}{4} + (\frac{GD^2}{4}) \text{ kg·m}^2$	0.40	0.20
Driving Torque	*3 N·m	72	54

<sup>\*1</sup> This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

<sup>\*2</sup> The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer to P.57 for more detail.

<sup>\*3</sup> Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.

<sup>\*4</sup> The table rotation speed when the motor rotates at 3000r/min. Depending on the application(unbalance of the jig,work) and the motor specification, the motor may not be able to rotate at 3000r/min.

### STANDARD CNC ROTARY TABLE





- The rotary table can be used vertically or horizontally depending on the application
- Best match for a medium-size machining center
- Standard model with motors mounted on the body side

Option Accessories ACCURACY ROTARY ULTRA **POWER** T-NUT **AXIS** SPEC. **JOINT** CHUCK DEVICE P.89 P.87 P.84 P.86

#### Specifications

#### ):High Speed CNC ROTARY Table Z series

Iter	n / Code No.	CNC260 CNCZ260	CNC260P CNCZ260P	CNC302*5 CNCZ302	CNC302P CNCZ302P	CNC321*5 CNCZ321	CNC401 CNCZ401
Diameter of Ta	able ¢m	m 260	260	300	300	320	400
Diameter of S	pindle Hole	<b>м</b> ф80н7	ф80н7	ф80н7	ф80н7	ф105н7	ф105н7
Center Height	: m	m 170	170	170	170	230	230
Width of T Slo	ot m	m 12 <sup>+0.018</sup>	12 +0.018	12 +0.018	12 +0.018	12 +0.018	14 <sup>+0.018</sup>
Clamping Sys	tem* <sup>7</sup>	Hydraulic	Pneumatic	Hydraulic	Pneumatic	Hydraulic	Hydraulic
Clamping Tore	•	m 1568	1430	1568	1430	1760	1760
Table Inertia at M	lotor Shaft (GD²/4) kg·m²X1	0.33	0.33	0.33	0.33	2.8	2.8
Servo Motor	r/m	$\alpha$ iF4•3000	αiF4•3000	αiF4•3000	αiF4•3000	αiF12•2000	αiF12•2000
MIN. Increme	nt	0.001°	0.001°	0.001°	0.001°	0.001°	0.001°
Rotation Spee	ed*6 r/m	in 25.0(50.0)	25.0(50.0)	25.0(50.0)	25.0(50.0)	22.2(44.4)	22.2(44.4)
Total Reduction	on Ratio	1/120(1/60)	1/120(1/60)	1/120(1/60)	1/120(1/60)	1/90(1/45)	1/90(1/45)
Indexing Accu	iracy s	ec 20	20	20	20	15	15
Net Weight		kg 115	115	120	120	200	230
MAX. Work Load	Vertical	175	175	175	175	250	250
on the Table	Horizontal	350 kg	350	350	350	500	500
MAX.	Į.	42480 N	42480	42480	42480	53100	53100
Thrust Load applicable	*1 F	≺L 1442 m	1442	1442	1442	2648	2648
on the Table	F) N	<l 2320="" m<="" td=""><td>2320</td><td>2320</td><td>2320</td><td>3840</td><td>3840</td></l>	2320	2320	2320	3840	3840
Guide Line of MAX. Unbalancing Load	*2   W N	50	50	50	50	100	100
MAX. Work Inertia	Vertical $\int \frac{GD^2}{4} + \left(\frac{GD^2}{4}\right) kg^{-1}$	3.2(1.6)	3.2(1.6)	3.2(1.6)	3.2(1.6)	6.4(3.2)	6.4(3.2)
Driving Torque	*3 N	192(153)	192(153)	192(153)	192(153)	432(345)	432(345)

- \*1 This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.
- \*2 The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer to P.57 for more detail.
- \*3 Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.
- \*5 CNC302,321 is semi-standard model. \*6 The table rotation speed when the motor rotates at 3000r/min. Depending on the application(unbalance of the jig,work) and the motor specification, the motor may not be able to rotate at 3000r/min.
- \*7 The air brake version of the existing CNC260(302) has been discontinued, so please select the new CNC260P(302P).
- ★The air-hydraulic booster is available, when the rotary table with hydraulic clamping system is used on the M/C without hydraulic source, please refer to ☞P.95.
- ★ **X**iF8/4000 motor can be mounted on **CNC260**, **302**, **CNC260P**, **302P**.



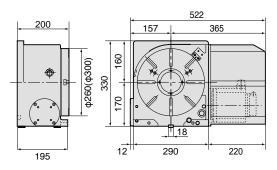
### CNC260, 260P, 302, 302P, 321, 401

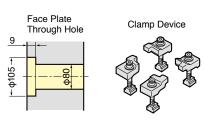


External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### CNC260, CNCZ260, CNC302, CNCZ302















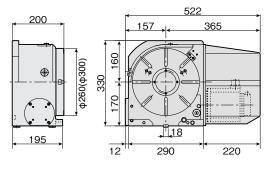


):Figures is for CNC302, CNCZ302.

### 

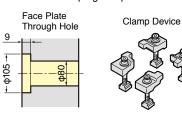








Powerful Clamping Torque:1430N·m











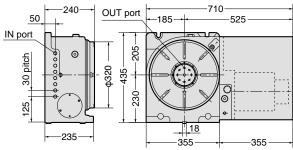


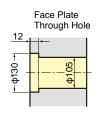
):Figures is for CNC302P.

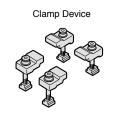
Air purge function is provided inside the motor cover as standard.

#### CNC321, CNCZ321















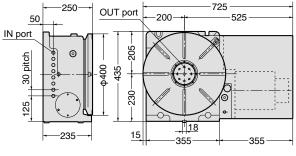


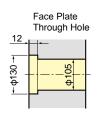
Rotary joint shown in layout is optional.

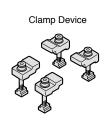
#### CNC401, CNCZ401

Rotary joint shown in photo & layout is optional.











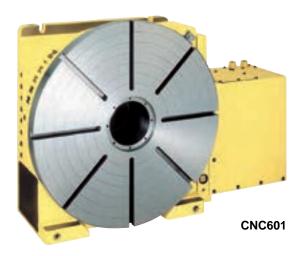






### STANDARD CNC ROTARY TABLE





- Dividing and lead cutting for large size work piece is suitable
- Large through hole and powerful clamping system
- Ideal for deep cutting of highly rigid material

Option

ADD. ACCURACY SPEC. P.57 P.99















#### Specifications

Specifi	cations				
lter	n / Code No.	CNC501	CNC601	CNC803	CNC1003
Diameter of Ta	able	500	600	800	1000
Diameter of S	pindle Hole	Ф130н7	Ф130н7	Ф230н7	Ф230н7
Center Height	mm	310	310	550	550
Width of T Slo	ot mm	14 +0.018	14 +0.018	22H7*4	22H7*4
Clamping Sys	tem	Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamping Tord	que N·m	4655	4655	7000	7000
Table Inertia at M	lotor Shaft $(\frac{GD^2}{4})$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	6.8	4.9	6.2	6.3
Servo Motor	r/min	αiF12•2000	αiF12•2000	αiF30•2000	αiF30·2000
MIN. Increme	nt	0.001°	0.001°	0.001°	0.001°
Rotation Spee	ed r/min	16.6	11.1	5.5	5.5
Total Reduction	on Ratio	1/120	1/180	1/360	1/360
Indexing Accu	iracy sec	15	15	15	15
Net Weight	kg	470	500	2070	2210
MAX. Work Load	Vertical kg	400	400	2000	2000
on the Table	Horizontal kg	800	800	4000	4000
MAX. Thrust	N N	150000	150000	281250	281250
Load applicable on the	*1 FXL N·m	5709	5709	20067	20067
Table	FXL N·m	16650	16650	42190	42190
Guide Line of MAX. Unbalancing Load	*2 N·m	200	200 300		300
MAX. Work Inertia	Vertical $(\frac{GD^2}{4})$ kg·m²	19.4	37	234	234
Driving Torque	*3 N·m	576	864	3168	3168

<sup>\*1</sup> This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

<sup>\*2</sup> The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer to P.57 for more detail.

<sup>\*3</sup> Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.

<sup>\*4</sup> Standard large rotary tables are without T slot. T slot is available as an option, please specify the width of the T slot.

<sup>★</sup>Total reduction ratio of 1/180 is also available for CNC501. ★ αiF22/4000 motor can be mounted on CNC501, 601.

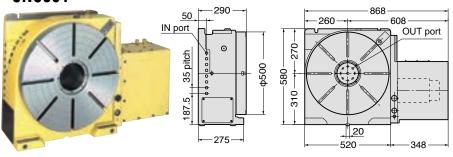


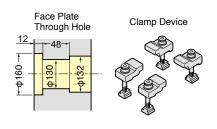
### CNC501, 601, 803, 1003



External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### **CNC501**







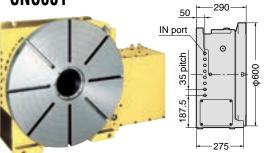


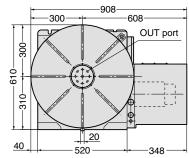


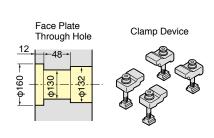


Rotary joint shown in layout is optional.

#### **CNC601**









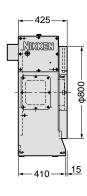


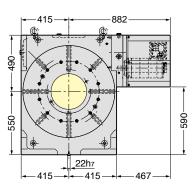


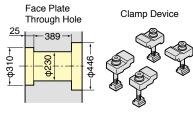
Rotary joint shown in layout is optional.

#### **CNC803**













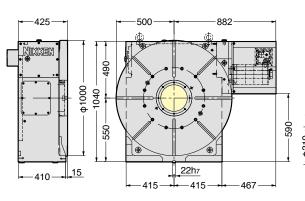


#### **CNC1003**



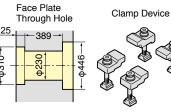






#### **CNC803B**

CNC803 : the servomotor is mounted at back side, suitable for the application for pallet on Horizontal machines.

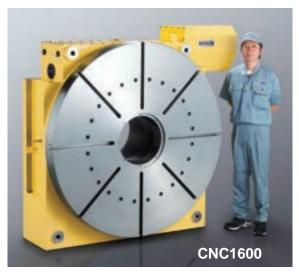






### **LARGE CNC ROTARY TABLE**





- Ideal for indexing and lead cutting of large work pieces
- Tooth thickness module 10 and ultrahigh rigidity among best in class.(CNC1600)
- Ideal for aircraft- and energy-related parts

	—— Орі	tion —				– Acces	sories —		
ADD. AXIS	ACCURACY SPEC.	ROTARY JOINT	ULTRA PRECISIO	SUPPORT TABLE	TAIL STOCK	SCROLL CHUCK	POWER CHUCK	CLAMP DEVICE	T-NUT
P.57	P.99	P.89	P.87	P.79	P.81	P.83	P.84	P.85	P.86

#### Specifications The specification will be varied according to your application. Please contact us.

Iter	m / Code No.		CNC1000*1	CNC1200*1	CNC1201*1	CNC1600*1
Diameter of T	able	фmm	1000	1200	1200	1600
Diameter of Spindle Hole *2 \$\phi\$mm		Ф300н7	Ф300н7	Ф300н7	Ф400н7	
Center Height	t	mm	Horizontal	Horizontal	650	850
Width of T Slo	ot *4	mm	22H7*4	22H7*4	22H7*4	28H7*4
Clamping Sys	stem		Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamping Tor	que	N·m	18000	18000	18000	35000
Servo Motor		r/min	αiF22	2•2000	αiF30•200	00
MIN. Increme	nt		0.001°	0.001°	0.001	0.001
Rotation Spec	ed	r/min	5.5	5.5	2.7	2.7
Total Reduction	on Ratio* <sup>5</sup>		1/360	1/360	1/720	1/720
Indexing Accu	uracy	sec	15	15	15	15
Indexing Accur	acy of Ultra Precision	sec	±3	±3	±3	±3
Net Weight		kg	1700	1850	3500*6	5250*6
MAX. Work Load	Vertical	kg			6500	10000
on the Table	Horizontal	kg	7000	7000	13000	30000
MAX.	F	N	281250	375000	1333330	2000000
Thrust Load applicable on the Table	*7	F×L N·m	24080	24080	79025	111952
on the rable	- F	F×L N·m	42190	67500	240000	510000
MAX. Work Inertia	Vertical	kg·m²	1300	1300	2300	6400
Driving Torque	*3	- N·m	3168	3168	8640	8640

- \*1 CNC1000, 1200, 1600 is semi-standard model.
- \*2 The diameter of the spindle hole is restricted for the ultra precision type with Heidenhain rotary encoder.
- \*3 Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.
- \*4 Standard large rotary tables are without T slot. T slot is available as an option, please specify the width of the T slot.
- \*5 Total reduction ratio and motor can be changed according to your application, please contact us.
  \*6 Net weight of the rotary table is for horizontal application. The weight of the back support for vertical application is not included.
  \*7 This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

### CNC1000, 1200, 1201, 1600

50



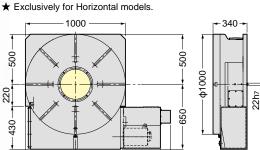
External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

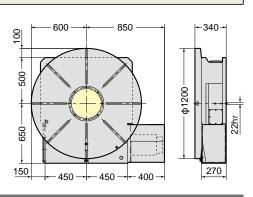
100

270



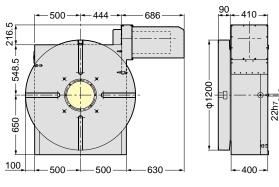






#### **CNC1201** PAT.

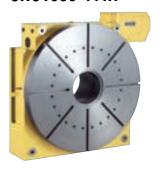


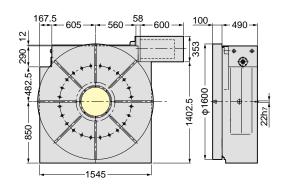




 $\bigstar$  Please contact us about the back support for vertical use.

#### **CNC1600** PAT.









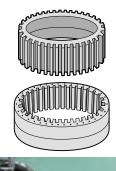


 $\bigstar$  Please contact us about the back support for vertical use.

#### **Application of the Large Rotary Table**

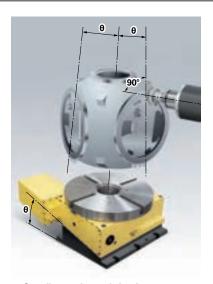
Machining of the gears with large module







Hobbing of the gears with large module



Configuration of the large rotary table on the horizontal M/C to machine a propeller hub of the windmill.

### TOP SIDE MOTOR MOUNTED CNC ROTARY TABLE

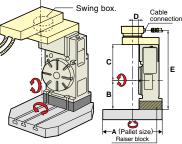




Ideal for automation of small parts by mounting of jig holder

Also ideal for B-axis of generalpurpose horizontal machining center. Figure at right shows example of pallet mounting.

Please specify A, B, C, D and E.



# ADD. ACC

P.57















#### Specifications

Specifi	cations			
Iter	n / Code No.	CNC202T	CNC260T	CNC302T *5
Diameter of T	able	200	260	300
Diameter of S	pindle Hole	ф60н7 ф40	ф80н7	ф80н7
Center Height	t mm	150	170	170
Width of T Slo	ot mm	12 +0.018	12 +0.018	12 +0.018
Clamping Sys	stem	Pneumatic*4	Pneumatic*4 / Hydraulic	Pneumatic*4 / Hydraulic
Clamping Tor	que N·m	303	588 / 1568	588 / 1568
Table Inertia at I	Motor Shaft $\left(\frac{\text{GD}^2}{4}\right) \text{ kg} \cdot \text{m}^2 \times 10^{-3}$	1.0	1.5	1.5
Servo Motor	r/min	αiF4•3000	αiF4•3000	αiF4•3000
MIN. Increme	nt	0.001°	0.001°	0.001°
Rotation Spee	ed*6 r/min	25.0	25.0	25.0
Total Reduction	on Ratio	1/120	1/120	1/120
Indexing Accu	uracy sec	±20	20	20
Net Weight	kg	70	160	165
MAX. Work Load	Vertical	100	175	175
on the Table	Horizontal kg			
MAX.	N N	18000	42480	42480
Thrust Load applicable on the	*1 FXL N·m	542	1442	1442
Table	FXL N·m	690	2320	2320
Guide Line of MAX. Unbalancing Load	*2 N·m	50	60	60
MAX. Work Inertia	Vertical $(\frac{GD^2}{4}) \text{ kg·m}^2$	1.0	3.2	3.2
Driving Torque	*3 N·m	192	192	192

- \*1 This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.
- \*2 The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer to P.57 for more detail.
- \*3 Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.
- \*4 Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. P.95 \*5 CNC302T is semi-standard model.
- \*6 The table rotation speed when the motor rotates at 3000r/min. Depending on the application(unbalance of the jig,work) and the motor specification, the motor may not be able to rotate at 3000r/min.

### CNC202T, 260T, 302T



External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### CNC202T

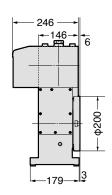


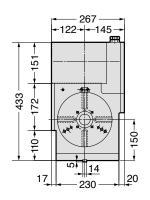


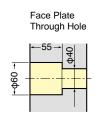














Air purge function is provided inside the motor cover as standard.

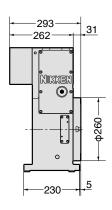
#### CNC260T

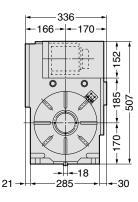


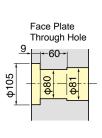


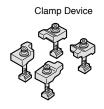










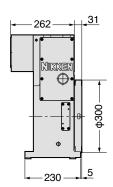


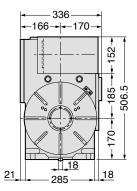
For the rotary table with pneumatic clamping, air purge function is provided inside the motor cover as standard.

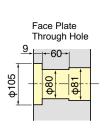
#### CNC302T



Center socket shown in photo is optional.









TOP SIDE







For the rotary table with pneumatic clamping, air purge function is provided inside the motor cover as standard.

#### Specification of the Top Side Mounted CNC Rotary Table



Photo with **CNC302T** without T slot.



Synchronors movement of 2 off CNC401T

Tubular roller bearing is installed against the thrust load. Therefore, when 2 rotary tables are faced on both side to synchronise movement, the system can be run without affecting the heat expansion of the rotary table.



**CNC401T** is installed on the pallet of the horizontal M/C.



CNC401T is installed on CNC600.



**CNCB450T** is used for the tilting axis table of **5AX**-tilting rotary table.

### TOP SIDE MOTOR MOUNTED CNC ROTARY TABLE



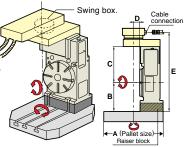


Ideal for automation of small parts by mounting of jig holder

Also ideal for B-axis of generalpurpose horizontal machining center. Figure at right shows example of pallet mounting.

Please specify A, B, C, D and E.

P.89



ADD. AXIS P.57













#### Specifications

Iten	n / Code No.	CNC321T*4	CNC401T	CNC501T	CNC601T
Diameter of Table ¢mm		320	400	500	600
Diameter of S	pindle Hole	ф105н7	ф105н7	ф130н7	ф130н7
Center Height	mm	240	240	310	310
Width of T Slo	ot mm	12 +0.018	14 <sup>+0.018</sup> 14 <sup>+0.018</sup>		14 +0.018
Clamping Sys	tem	Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamping Tor	que N·m	1760	1760	4655	4655
Table Inertia at I	Motor Shaft $\left(\frac{GD^2}{4}\right)$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	2.0	2.0	9.0	8.8
Servo Motor	r/min	αiF12•2000	αiF12•2000	αiF22•2000	αiF22•2000
MIN. Increme	nt	0.001°	0.001°	0.001°	0.001°
Rotation Spee	ed r/min	16.6	16.6	16.6	11.1
Total Reduction	on Ratio	1/120	1/120	1/120	1/180
Indexing Accu	iracy sec	15	15	15	15
Net Weight	kg	220	245	495	525
MAX. Work Load	Vertical kg	250	250	400	400
on the Table	Horizontal kg				
MAX.	N	53100	53100	150000	150000
Thrust Load applicable	*1 FXL N·m	2648	2648	5709	5709
on the Table	FXL N·m	3840	3840	16650	16650
Guide Line of MAX. Unbalancing Load	*2 N·m	100	100	200	200
MAX. Work Inertia	Vertical $(\frac{GD^2}{4})$ kg·m <sup>2</sup>	8.0	8.0	19	37
Driving Torque	*3 N·m	576	576	576	864

<sup>\*1</sup> This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

<sup>\*2</sup> The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application.

The guide line figure will be different according to the servo motor, please refer to F.57 for more detail.

<sup>\*3</sup> Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied. \*4 CNC321T is semi-standard model.

<sup>★</sup> αiF22/4000 motor can be mounted on CNC321T, 401T. ★Total reduction ratio of 1/180 is also available for CNC501T.



### CNC321T, 401T, 501T, 601T

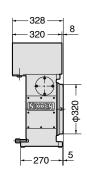


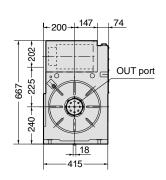
External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

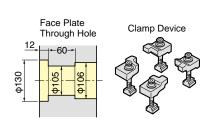
#### CNC321T







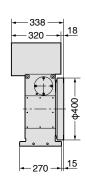


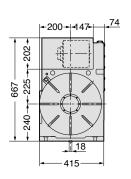


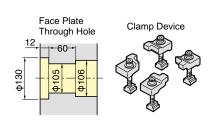
Rotary joint shown in layout is optional. In ports are located in back side.

#### **CNC401T**









★ Built-in type rotary joint can be mounted on CNC401 refer \$\opinsptext{P.89}\$

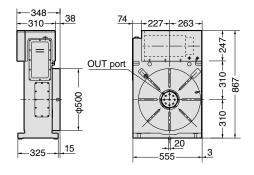


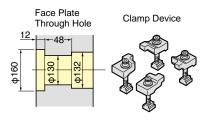
Center socket shown in photo is optional. In ports are located in back side.

#### CNC501T









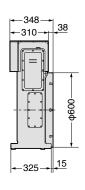
Rotary joint shown in layout is optional. In ports are located in back side.

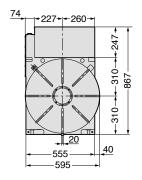
#### CNC601T

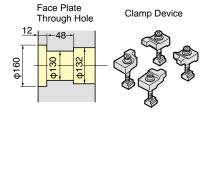












In ports are located in back side.

### BACK SIDE MOTOR MOUNTED CNC ROTARY TABLE **NIKKEN**





CNC260B

- Suitable for the machine which does not have so wide space for Y axis, such as the gantory type M/C or the M/C with sprash guard
- Also compatible with rotary joints
- Select among pneumatic, hydraulic, and air-hydro clamping systems



#### **Specifications**

Item	Item / Code No.		CNC180B	CNC202B	CNC260B	CNC302B*5	CNC321B*5	CNC401B
Diameter of T	able	фmm	180	200	260	300	320	400
Diameter of S	pindle Hole	Фmm	ф60н7 ф40	ф60н7 ф40	ф80н7	ф80н7	ф105н7	ф105н7
Center Height	t	mm	180	180	170	170	230	230
Width of T Slo	ot	mm	12 <sup>+0.018</sup>	12+0.018	12+0.018	12+0.018	12+0.018	14 <sup>+0.018</sup>
Clamping Sys	tem		Pneumatic*4	Pneumatic*4	Pneumatic*4 / Hydraulic	Pneumatic*4 / Hydraulic	Hydraulic	Hydraulic
Clamping Tor	que	N·m	303	303	588/1568	588/1568	1760	1760
Table Inertia at I	Motor Shaft $(\frac{GD^2}{4})$ k	g·m²×10-³	0.4	0.4	1.7	1.8	7.0	7.0
Servo Motor		r/min	αiF2•3000	αiF4•3000	αiF4•3000	αiF4•3000	αiF12•2000	αiF12•2000
MIN. Increme	nt		0.001°	0.001°	0.001°	0.001°	0.001°	0.001°
Rotation Spee	ed <sup>*6</sup>	r/min	33.3	33.3	25.0	25.0	22.2	22.2
Total Reduction	on Ratio		1/90	1/90	1/120	1/120	1/90	1/90
Indexing Accu	ıracy	sec	±20	±20	20	20	15	15
Net Weight		kg	56	60	145	150	240	270
MAX. Work Load	Vertical kg		100	100	175	175	250	250
on the Table	Horizontal	kg	_	_			_	
MAX.		N	18000	18000	42480	42480	53100	53100
Thrust Load applicable on the	*1	F×L N·m	542	542	1442	1442	2648	2648
Table		F×L N·m	690	690	2320	2320	3840	3840
Guide Line of MAX. Unbalancing Load	*2	N·m	30	50	50	50	100	100
MAX. Work Inertia	Vertical	<sup>GD²</sup> √ kg·m²	0.4	1.0	3.2	3.2	6.4	6.4
Driving Torque	*3	N·m	72	144	192	192	432	432

<sup>\*1</sup> This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

<sup>\*2</sup> The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table. The guide line figure will be different according to the servo motor, please refer to \$\infty\$P.57 for more detail.

<sup>\*3</sup> Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.

<sup>\*4</sup> Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. 🖙 P.95

<sup>\*5</sup> CNC302B, CNC321B is semi-standard model.

<sup>\*6</sup> The table rotation speed when the motor rotates at 3000r/min. Depending on the application(unbalance of the jig,work) and the motor specification, the motor may not be able to rotate at 3000r/min. ★ α iF4/5000 motor can be mounted on CNC180B.

<sup>★</sup> XiF8/4000 motor can be mounted on CNC260B, 302B.

<sup>★</sup>The air-hydraulic Booster is available, when the rotary table with hydraulic clamping system is used on the M/C without hydraulic source, please refer 🐷 P.95.

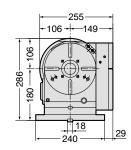
### CNC180B, 202B, 260B, 302B, 321B, 401B

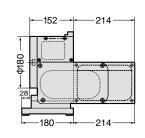


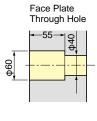
External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### CNC180B















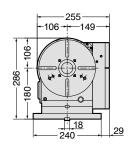


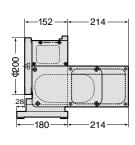


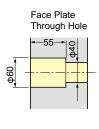
Air purge function is provided.

#### CNC202B











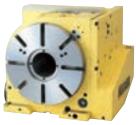




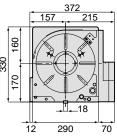


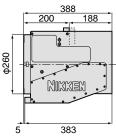
Air purge function is provided.

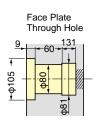
#### CNC260B













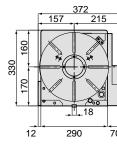


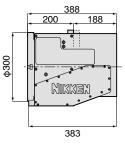


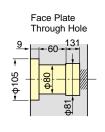
For the rotary table with pneumatic brake, air purge function is provided inside the motor cover as standard.

#### CNC302B













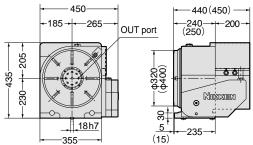


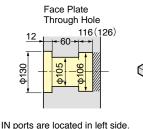


For the rotary table with pneumatic brake, air purge function is provided inside the motor cover as standard.

### CNC321B, CNC401B











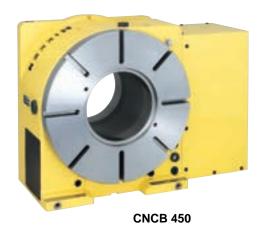


Center socket shown in photo & layout is optional.

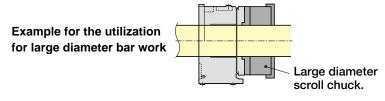
):CNC401B

### **BIG BORE CNC ROTARY TABLE**





- Ideal for machining boring pipes for oil or natural gas
- Capable of cutting through-holes in work pieces
- Supports up to 20 + 1P rotary joint ports

















#### Specifications

BIG BORE CNC Rotary Tables are all semi-standard models. Please contact us.

			,,	
Item	n / Code No.	CNCB350	CNCB450	CNCB630
Diameter of Ta	able	350	450	630
Diameter of S	pindle Hole	ф154н7	ф205н7	ф345н7
Center Height	mm	230	280	380
Width of T Slo	ot mm	14	14	14
Clamping Sys	tem	Hydraulic	Hydraulic	Hydraulic
Clamping Tord	que N·m	3331	3870	6550
Table Inertia at I	Motor Shaft $\left(\frac{\text{GD}^2}{4}\right) \text{ kg·m}^2 \times 10^{-3}$	2.9	2.8	4.8
Servo Motor	r/min	αiF12•2000	αiF12•2000	αiF22•2000
MIN. Increme	nt	0.001°	0.001°	0.001°
Rotation Spee	ed r/min	22.2	16.6	11.1
Total Reduction	on Ratio	1/90	1/120	1/180
Indexing Accu	iracy sec	15	15	15
Net Weight	kg	245	330	750
MAX. Work Load	Vertical kg	250	350	400
on the Table	Horizontal kg	500	700	800
MAX.	, N	5300	63720	250000
Thrust Load applicable	*1 FXL N·m	2648	3531	5297
on the Table	FXL N·m	3840	5990	33000
Guide Line of MAX. Unbalancing Load	*2 N·m	100	150	300
MAX. Work Inertia	Vertical $(\frac{GD^2}{4})$ kg·m²	6.4	17.0	40.0
Driving Torque	*3 N·m	432	576	1584

<sup>\*1</sup> This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

<sup>\*2</sup> The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer to ☞ P.57 for more detail.

<sup>\*3</sup> Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.

<sup>★</sup>Total reduction ratio of 1/180 is also available for CNCB450. ★ α iF22/4000 motor can be mounted on CNCB350, 450.



### CNCB350, 450(T), 630

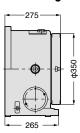


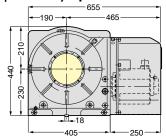
External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

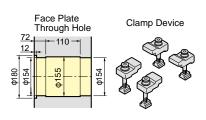
#### CNCB350



# Ultra Big Bore ( $\phi$ 154mm) Specification









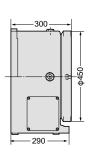


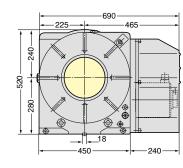


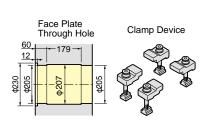
#### **CNCB450**



#### Ultra Big Bore (\$\phi\$205mm) Specification







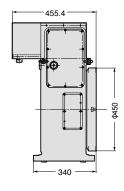


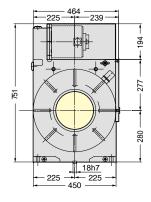


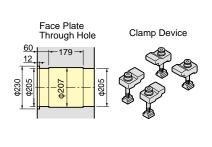




#### Ultra Big Bore (\$\phi\$205mm) Specification



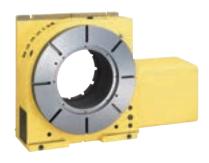


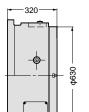


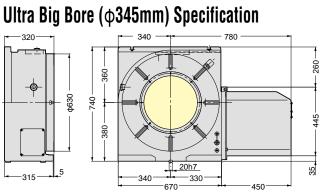


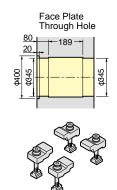


#### CNCB630









Clamp Device







### **MULTI-SPINDLE CNC ROTARY TABLE**





CNC100-2W

- Multi-Spindle (2, 3 & 4 spindles) CNC rotary table series for rationalization of machining of small size work pieces  $(\phi 3 \sim 100 \text{mm})$
- Max. number of spindles CNC100: 4 spindles, CNC180: 4 spindles, CNC202: 4 spindles, CNC260: 2 spindles. Please contact us
- Ideal for small items and mass-produced parts

Option ·

ACCURACY ADD. AXIS













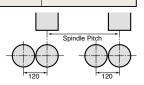




#### Specifications Multi-Spindle CNC Rotary Tables are all semi-standard models. Please contact us. ( ):High Speed type Please contact us.

Iten	n / Code No.	CNC100-2W,-3W,-4W		CNC180-2W	CNC202-2W	CNC260-2W	
Diameter of T	able		105		180	200	260
Diameter of S	pindle Hole		60н7 30		60н7 40	60H7 40	80н7
Number of sp	indles (Pitch) mm		2,3,4×120		2×250	2×250	2×350
Center Height	t mm		105		175	175	220
Width of T Slo	ot mm		16 <sup>+0.018</sup>		12 +0.018	12 <sup>+0.018</sup>	12 <sup>+0.018</sup>
Clamping Sys	stem		Pneumatic*3	3	Pneumatic*3	Pneumatic*3	Pneumatic*3 / Hydraulic
Clamping Tor	que N·m		147		303	303	588/1568
Table Inertia at I	Motor Shaft $\left(\frac{GD^2}{4}\right)$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	0.13	0.16	0.2	0.12	0.13	0.7
Servo Motor	r/min	αiF2•2000	(αiS4·2000)	αiF4•2000	αiF4•2000	α iF8•2000	αiF8•2000
MIN. Increme	nt		0.001°		0.001°	0.001°	0.001°
Rotation Spec	ed r/min		11.1 (44.4)		22.2	22.2	16.6
Total Reduction	on Ratio		1/180(1/45)		1/90	1/90	1/120
Indexing Accu	Indexing Accuracy sec		±30 ±45		±20	±20	20
Net Weight	kg	70	90	120	115	120	320
MAX. Work Load	Vertical kg		15		100	100	175
on the Table	Horizontal kg		30		200	200	350
MAX.	N N		3920		18000	18000	42480
Thrust Load applicable	*1 FXL N·m		275		542	542	1442
on the Table	FXL N·m		98		690	690	2320
MAX. Work Inertia	Vertical $\left(\frac{GD^2}{4}\right) \text{ kg·m}^2$	0.01	9 (0.07Horizo	ontal)	0.5	0.5	1.9
Driving Torque	*2 N·m		72		72	144	192

<sup>\*1</sup> This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.



<sup>\*2</sup> Driving torque means the torque at MAX. rotation speed after acceleration.

Driving torque is almost constant and independent from the load except unbalancing load is applied. \*3 Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. ☞ P.95
★ Min. pitch between spindles CNC100 : 120mm, CNC180 : 250mm, CNC202 : 250mm,

CNC260: 320mm. Please contact us when the different pitch is required.

<sup>★ 4</sup> spindles table to suit 2 spindles M/C is available.

<sup>★ 5</sup> or 6 spindles CNC rotary table is also available.

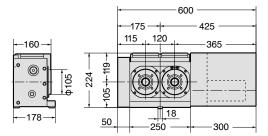
### CNC100-2W, 3W, 4W, CNC180-2W, CNC202-2W, CNC260-2W

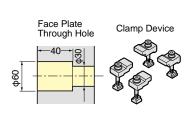


External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### CNC100-2W













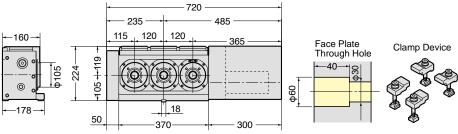


Air purge function is provided inside the motor cover as standard.

If you need a knock hole for positioning or a key way on the table surface, please contact us.

#### CNC100-3W











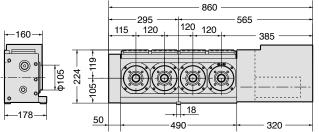


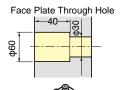
Air purge function is provided inside the motor cover as standard.

If you need a knock hole for positioning or a key way on the table surface, please contact us.

#### CNC100-4W



















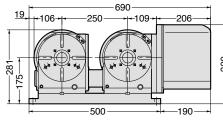
Air purge function is provided inside the motor cover as standard.

If you need a knock hole for positioning or a key way on the table surface, please contact us. Clamp Device

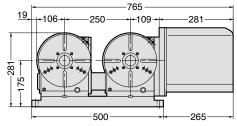
#### CNC180-2W, CNC202-2W



CNC202-2W



CNC180-2W CNC202-2W













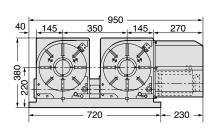


Air purge function is provided inside the motor cover as standard.

#### CNC260-2W

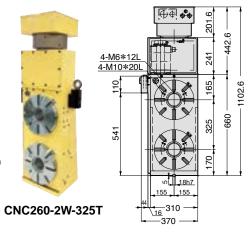
#### Pneumatic Clamping Torque UP 588Nm

CNC260-2W

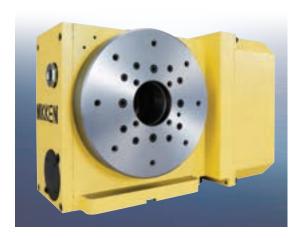


For the rotary table with pneumatic clamping, air purge function is provided inside the motor cover as standard.

#### CNC260-2W-325T



# NCT CNC ROTARY TABLE New high clamping torque compact cnc rotary table



# Small but Strong NCT200



### 900Nm

**Super-high Clamping System** 

#### Reliable indexing accuracy enhances profitability

Super-high Clamping torque 900Nm can be generated by air supply only. Strong clamping torque and better indexing accuracy enhance productivity.

### 25%UP

**High Rigidity of New Driving System** 

### Maintain high accuracy over the long term Reduce the total maintenance cost

Redesigning the driving system, the rigidity increases 25%. High durability of the mechanism is allowed to maintain high accuracy and to accomplish high precision machining operation over the long term.

## High Speed

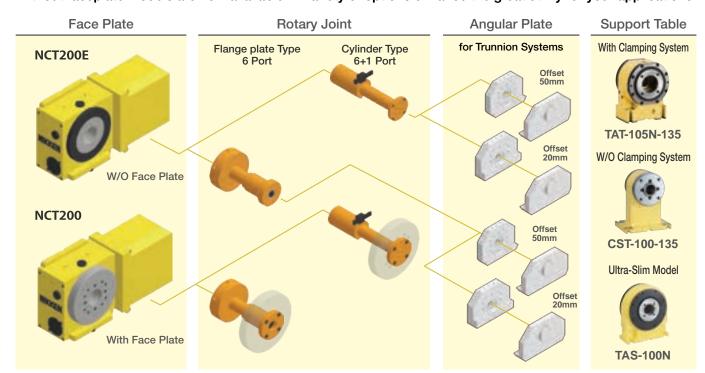
Z Type is also Available

#### Reducing cycle time enhances productivity

High speed Z type is also available. Setting up gear ratio 1/2 is allowed rotation speed to be double.

#### **Great Customization**

#### Without faceplate models are now available. A variety of options enhance the great utility for your applications.







#### Specifications

Marry / Carla Na		With Fa	ce Plate	W/O Face Plate			
Ite	m / Code No.	Standerd	High Speed	High Speed Standerd			
Right Hand	Mounted Moter	NCT200	NCTZ200	NCT200E	NCTZ200E		
Left Hand M	ounted Moter	NCT200L	NCTZ200L	NCT200EL	NCTZ200EL		
Diameter of T	able	200	200	130	130		
Diameter of S	pindle Hole	ф60н7 ф40	ф60н7 ф40	ф60н7 ф40			
Center Height	t mm	135	135	135	135		
Clamping Sys	stem	Pnematic*4	Pnematic*4 Pnematic*4		Pnematic*4		
Clamping Tor	que N·m	900	900	900			
Table Inertia at	Motor Shaft kg·m²X10 <sup>-3</sup>	0.1	0.1	0.1 0.1			
Servo Motor	$(\frac{GD^2}{4})$ r/min	αiF4•3000	αiF4·3000	αiF4·3000	αiF4·3000		
MIN. Increme	nt	0.001	0.001	0.001	0.001		
Rotation Spec	ed*5 r/min	33.3	66.6	33.3	66.6		
Total Reduction	on Ratio	1/90	1/45	1/90	1/45		
Indexing Accu	ıracy sec	±20	±20	±20	±20		
Net Weight	kg	65	65	62	62		
MAX. Work Load	Vertical kg	100	100	100	100		
on the Table	Horizontal kg	200	200	200	200		
MAX.	N N	18000	18000	18000	18000		
Thrust Load applicable on the Table	*1 FXL	677	677	677	677		
	FXL N·m	690	690	690	690		
Guide Line of MAX. Unbalancing Load	*2 N·m	60	30	60	30		
MAX. Work Inertia	Vertical $0 = \frac{1}{4} + \left(\frac{GD^2}{4}\right) \text{ kg} \cdot \text{m}^2$	1.1	0.5	1.1	0.5		
Driving Torque	*3 N·m	151	121	151	121		

- \*1 This is the strength of the worm wheel without face plate clamping. It is applied against dynamic cutting thrust.
- \*2 The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer \$\sigma\$P.57 for more detail.

<sup>\*3</sup> Driving torque means the torque at MAX. rotation speed after acceleration. Driving torque is almost constant and independent from the load except unbalancing load is applied.

<sup>\*4</sup> Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. P.95

<sup>\*5</sup> The table rotation speed when the motor rotates at 3000r/min. Depending on the application(unbalance of the jig,work) and the motor specification, the motor may not be able to rotate at 3000r/min.

<sup>★</sup>Standard faceplate is without T slot. T slot is available as an option. Please contact us.

<sup>★6&</sup>quot; (Chuck plate : **X-6B**) and 7" (Chuck plate : **X-7A**) can be mounted for Face Plate with T slots.

### **DIMENSIONS OF NCT200**

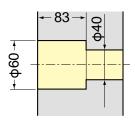


#### **NCT200 (With Face Plate)**

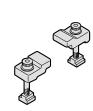


(Photo) NCT200FA

#### Face Plate Through Hole



**Clamp Device** 





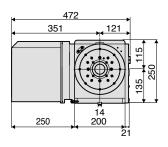


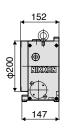




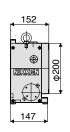


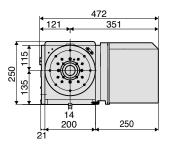
#### Left Hand : NCT200LFA





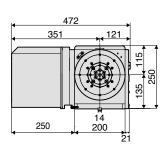
#### Right Hand : NCT200FA

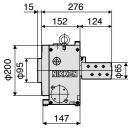




#### Left Hand: With Cylinder type Rotary Joint

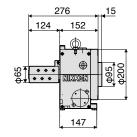
NCT200L+Clinder type Rotary Joint(6+1 Ports)
RT-NC200SD-6+1-L\*1

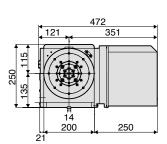




#### Right Hand: With Cylinder type Rotary Joint

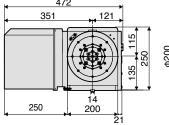
NCT200+Clinder type Rotary Joint(6+1 Ports)
RT-NC200SD-6+1-R\*1

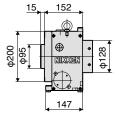




#### Left Hand: With Flange Plate type Rotary Joint

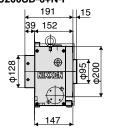
NCT200L+Flange Plate type Rotary Joint(6 Ports) RN-NC200SD-6+N-F\*1

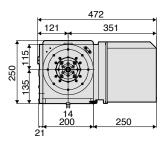




#### Right Hand: With Flange Plate type Rotary Joint

NCT200+Flange Plate type Rotary Joint(6 Ports) RN-NC200SD-6+N-F\*1





External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

### **DIMENSIONS OF NCT200E**

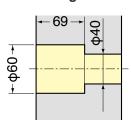


#### **NCT200E (W/O Face Plate)**

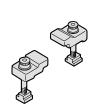


(Photo) NCT200EFA

#### **Face Plate Through Hole**









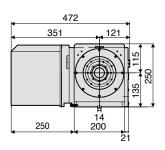


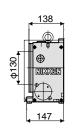






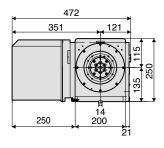
#### Left Hand : NCT200ELFA

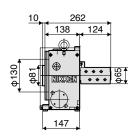




#### Left Hand: With Cylinder type Rotary Joint

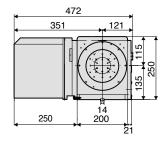
NCT200EL+Clinder type Rotary Joint(6+1 Ports) RT-NC20ESD-6+1-L\*1

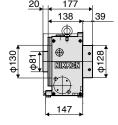




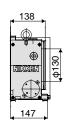
#### Left Hand: With Flange Plate type Rotary Joint

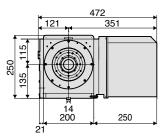
NCT200EL+Flange Plate type Rotary Joint(6 Ports) RN-NC20ESD-6+N-F\*1





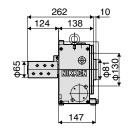
#### Right Hand : NCT200EFA

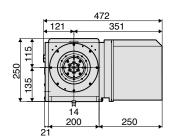




#### Right Hand: With Cylinder type Rotary Joint

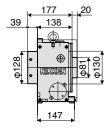
NCT200E+Clinder type Rotary Joint(6+1 Ports) RT-NC20ESD-6+1-R\*1

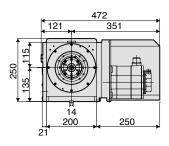




#### Right Hand: With Flange Plate type Rotary Joint

NCT200E+Flange Plate type Rotary Joint(6 Ports) RN-NC20ESD-6+N-F\*1

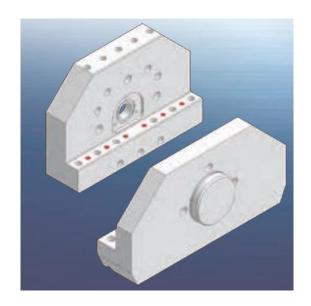




External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### **ANGULAR PLATE FOR NCT200E**

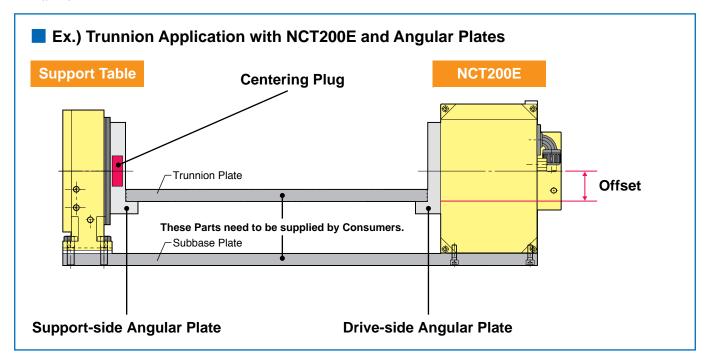




Model without faceplate: Custom Angular plates for use with the NCT200E. When combined with the NCT200E, they enable configuration of compact trunnion applications that maximize space inside the machine.

# Trunnion Applications Utilize the NCT's High Rigidity and Powerful Clamping Capability for More Efficient Utilization of Limited Space.

The NCT200 series, which can reliably drive trunnion applications with its powerful clamping capability and high rigidity exceeding the norm for this product class, is now provided with angle plates as a standard accessory. When combined with the NCT200E without faceplate, they allow application configuration that utilizes space inside the machine to the maximum.



# Lineup Of Two Types for Internal or External Rotary Joints

A lineup of two types of drive-side angle plate is available for use in combination with the NCT200E to match the rotary joint specification. Specify the type of angle plate you require according to the components or applications.

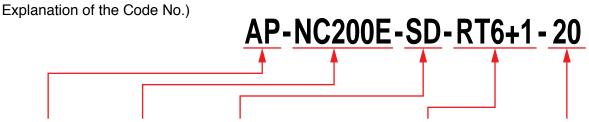
#### 20 mm / 50 mm Selectable Offset

In addition, a lineup of two offset specifications is available for both the drive-side Angular plate and support-side Angular plate. This allows you to configure the optimal application to match the component size.



### SPECIFICATION OF ANGULAR PLATE FOR NCT200E NIKKEN





Code No. SP... Special

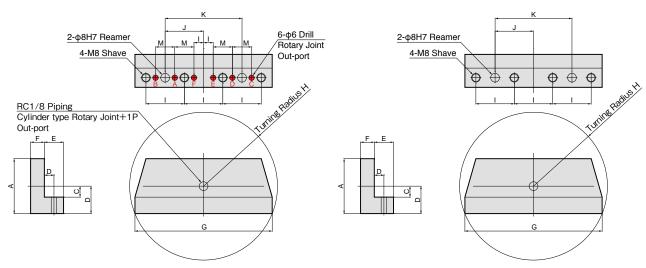
Angular Plate Product SD... Standard Number of Ports of Rotary Joint Offset

RT... Cylinder type ... 20mm RN··· Flange Plate type ... 50mm **50** 

N ... Non (Support-side Only)

#### Drive-side

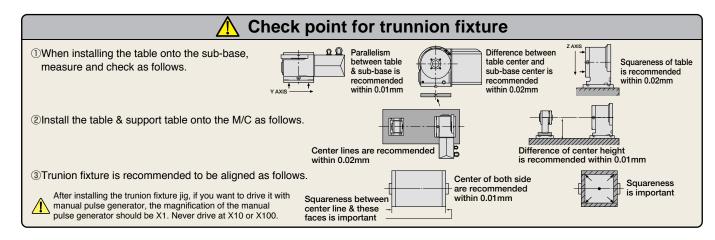
#### Support-side



#### **Specifications**

Subject Models		type	Offset	Code No.	А	В	С	D	Е	F	G	Н	-1	J	К
Drive-side	NCT200E	Cylinder type Rotary Joint Ports Including	20mm	AP-NC200E-SD-RT6+1-20	133	53	20	11 20		25 20 35	200	107	60	60±0.01	120±0.01
			50mm	AP-NC200E-SD-RT6+1-50	150	70	50		20			114			
		Flange Plate type Rotary Joint Ports Including	20mm	AP-NC200E-SD-RN6-20	133	53	20		20			113			
			50mm	AP-NC200E-SD-RN6-50	150	70	50					114			
Support-side	TAS-100N	with Centering Plug	20mm	AP-TAS100-SD-N-20	105	53	20	16 2	25	20	200	113	60	60±0.01	120±0.01
			50mm	AP-TAS100-SD-N-50	122	70	50					114			
	TAT-105N-135	with Centering Plug	20mm	AP-TAT105-SD-N-20	105	53	20					113			
			50mm	AP-TAT105-SD-N-50	122	70	50					114			

The rotary joint is not included in the set of the angular plate. Please order both angular plate and rotary joint.



# **NSV** ROTARY HIRTH COUPLING INDEX



- Ideal for deep cutting of highly rigid material
- Indexing Accuracy : ±2"
- No Lifting up of Table at Indexing Time. (Built-in 3 pieces of Hirth Coupling) JAPAN: PAT.

Option ACCURACY ADD. ROTARY ULTRA AXIS SPEC. JOINT PRECISIO P.57 P.99 P.89 P.87

TAIL TABLE STOCK

P.79

Accessories SCROLL POWER **CHUCK** CHUCK P.83 P.84

CLAMP DEVICE P.85



#### Specifications

Iten	n / Code No.		NSVZ180	NSVZ300	NSVX400	NSVX500	NSVX400T	
Diameter of	Diameter of Table		180	300	400	500	400	
Diameter of Spindle Hole ¢mm		Ф60н7 Ф30	Ф60н7 Ф52	Ф80н7	Ф80н7	Ф80н7		
Center Height mm		135	170	240 310		240		
Width of T S	Width of T Slot mm		12 +0.018	12 +0.018	14 +0.018	14 <sup>+0.018</sup>	14 <sup>+0.018</sup>	
Clamping Sy	Clamping System			Hydraulic	Hydraulic	Hydraulic	Hydraulic	
Clamping To	orque	N·m	910	2155	2155 5880 5880		5880	
Table Inertia a	t Motor Shaft (GD²/4) kg⋅m²	<sup>2</sup> ×10 <sup>-3</sup>	0.11	0.16	2.9	3.9	2.9	
Servo Motor		r/min	α iF2•2000	α iF4•2000	α iF12•2000	α iF12·2000	α iF12·2000	
MIN. Increme	ent		1°	1°	1°*/0.001°	1°*/0.001°	1°*/0.001°	
Rotation Spe	eed	r/min	11.1	11.1	22.2	16.6	16.6	
Total Reduct	Total Reduction Ratio		1/180	1/180	1/90	1/120	1/120	
Indexing Acc	curacy	sec	±3	±2	±2*	±2*	±2*	
Net Weight	Net Weight kg		60	150	325	410	350	
MAX. Work Load on the Table	Vertical	kg	50	150	250	250	250	
	Horizontal	kg	100	300	500	500		
MAX.	F	N	23520	39200	58800	58800	58800	
Thrust Load applicable on the Table	*1	F×L N·m	911	2156	5880	5880	5880	
	FF 1	F×L N·m	569	1421	3920	3920	3920	
Guide Line of MAX. Unbalancing Load	*2	N·m	30	30	100	100	-	
MAX. Work Inertia	Vertical $\left(\frac{\text{GD}^2}{4}\right)$	kg·m²	0.14	1.0	6.4	6.4	11.5	
Driving Torque		N·m			432	576	576	

- \*1 This is the strength of the clamping by the hirth coupling.

  \*2 The guide line of MAX unbalancing load means the unbalancing load, when the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer to #P.57 for more detail.

  \* NSVZ series are indexing table which is indexable at each 1°.

  \* NSVX series are rotary and indexing table which clamped by hirth coupling (of high precision & high rigidity) at each 1°, also perform min. command incremental at 0.001° and profile milling.

  \* (IFA/5000 motor can be mounted on NSVZ180 and NSVZ300 is used on the MC without budgetalls express.)

- ★ The air-hydraulic booster is available, when NSVZ180 or NSVZ300 is used on the M/C without hydraulic source.
  ★ Please be careful that the centralizing of work piece or jig fixture should be done after indexing, not rotating.
- + The solenoid valve is installed inside the table for the indexing table with NIKKEN controller. The solenoid valve must be installed at the hydraulic tank for the indexing table of the additional axis control.



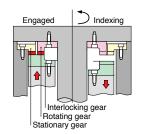
### NSVZ180, 300, NSVX400, 400T, 500



#### No lift (Three pieces of Hirth Coupling)

Three pieces of 360 division precision hirth coupling ensures smooth and fast indexing without table lifting.

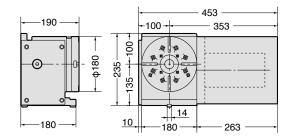
●3-piece Hirth coupling developed in-house by NIKKEN

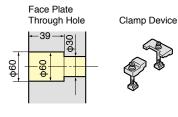


External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### NSVZ180











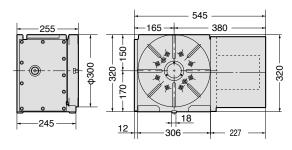


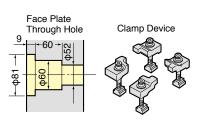


#### NSVZ300

Photo with center socket. (optional)









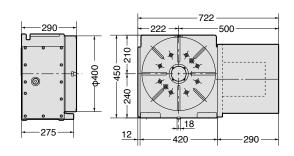


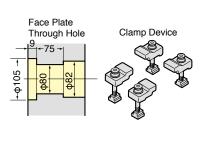




#### NSVX400









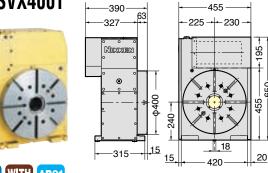






#### NSVX400T





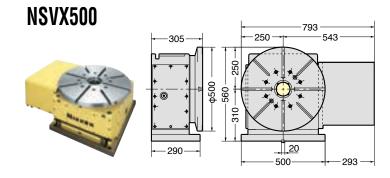
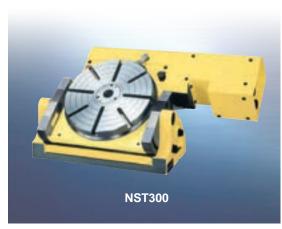


Photo: for horizontal use. Please contact us for external dimension.

# NST MANUAL TILTING ROTARY TABLE



- Table can be tilted at 0°~90° manually
- Indexing is CNC controlled so that it can be adapted to all kinds of machining
- Suitable for wide variety of applications thanks to numerical tilting axis control













### Specifications

Iten	n / Code No.	NST250	NST300	NST500
Diameter of T	able	250	300	500
Diameter of S	pindle Hole	Ф60нт Ф52	Ф60нт Ф60	Ф75нт Ф61.5
Center Height	: mm	155	208	288
Width of T Slo	ot mm	12 +0.018	12 +0.018	14 <sup>+0.018</sup>
Clamping Sys	tem	Pneumatic*2	Pneumatic*2	Pneumatic*2
Clamping Tor	que N·m	147	196	196
Table Inertia at I	Motor Shaft $(\frac{GD^2}{4})$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	0.39	0.59	0.69
Servo Motor	r/min	α iF2•2000	α iF4•2000	α iF8•2000
MIN. Increme	nt	0.001°	0.001°	0.001°
Rotation Spee	ed r/min	16.6	11.1	5.5
Total Reduction	on Ratio	1/120	1/180	1/360
Indexing Accu	iracy sec	20	20	20
Net Weight	kg	75	135	320
MAX. Work Load	90° kg	50	100	200
on the Table	Horizontal kg	100	300	500
MAX.	N	17500	31860	75000
Thrust Load applicable	*1 FXL N·m	603	903	2884
on the Table	FXL N·m	770	2010	8330
MAX. Work Inertia	90°	1.35	3.37	14.70
Driving Torque	N·m	144	288	1152

<sup>\*1</sup> This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

<sup>\*2</sup> Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. 🖙 P.95

<sup>★</sup> XiF4 motor can be mounted on NST250.

<sup>★</sup> **XiF8/3000** motor can be mounted on **NST300**.



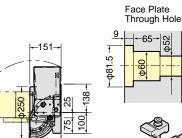
## NST250, 300, 500



External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### **NST250**





Center height at 90°: 155mm

Clamp Device









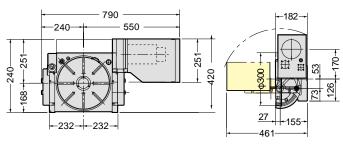
Center socket shown in photo is optional.

Guide key width: 18mm Table height in horizontal position: 151mm

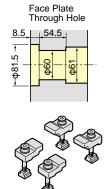
### **NST300**



Center socket shown in photo is optional.



Center height at 90°: 208mm



Clamp Device









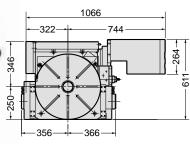


Guide key width: 18mm Table height in horizontal position: 182mm

#### **NST500**



Center socket shown in photo is optional.



110 175

← 650 ← Center height at 90°: 288mm

Face Plate Through Hole

Clamp Device







Guide key width: 18mm Table height in horizontal position: 285mm

# 5AX

### **TILTING ROTARY TABLE**

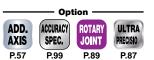
New

THE SMALLEST TILTING CNC ROTARY TABLE FOR COMPACT MACHINES



Ultra Compact Tilting Rotary Table

**5AX-100** PAT.





### Minimum & Lightest Weight

#### The Smallest and Lightest 5AX

### Demonstrates the true worth of a compact machining center with limited machining space.

With a body width of 466mm and product weight of 84 kg, the 5AX series is the smallest and lightest tilting rotary table in NIKKEN's history. It is an ideal counterpart to products such as the BT30 compact machining center. It allows you to secure more machining space than was possible with earlier models.

## Tilting Axis600Nm

Powerful braking system with double clamping sleeve type PAT. Tilt-axis with Air-hydranlic unit as Standard Equipment.

### Astoundingly powerful clamping capability in spite of compact body.

For machines with no hydraulic power source, the tilt-axis is equipped with an air-hydro unit that provides powerful hydraulic clamping using only an air supply. In spite of its compact body, it delivers an astounding 600 Nm of clamping power, enabling high positioning accuracy for highly precise machining.

### **Extensive Lineup of Attachments**

This extensive attachment lineup from NIKKEN allows machining of a wide variety of work pieces.



Jig Plate



Scroll Chuck

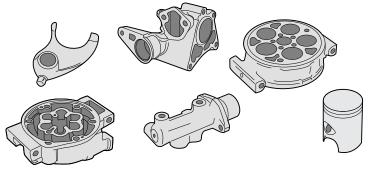


Center Socket

High-precision 5-axis machining of precision electronic devices such as smartphones, automobile parts, etc. can be accomplished using a compact machining center.



Impeller

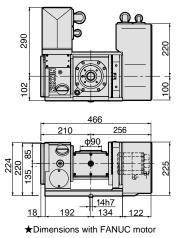


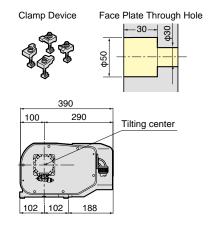
Components of Automotive Parts













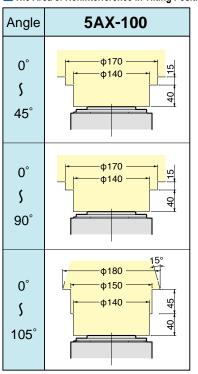






Specifi	cations		
Iten	n / Code No.	5AX-100	
Diameter of T	able	90	
Diameter of S	pindle Hole	Ф50н	7 Ф30
Center Height	t (90°) mm	1:	35
Table Height in H	Horizonatal Position (0°) mm	1:	90
Width of T Slo	ot mm	Ф8н7 F	Pin hole
Axis		Rotary	Tilting (0°∼105°)
Clamping Sys	tem	Pneumatic*1	Air Hydraulic Booster Built-in type
Clamping Tor	que N·m	205	600
Table Inertia at I	Motor Shaft $\left(\frac{\text{GD}^2}{4}\right) \text{ kg·m}^2 \times 10^{-3}$	0.09	0.12
Servo Motor	r/min	α iF1•2000	α iF1•2000
MIN. Increme	nt	0.001°	0.001°
Rotation Spee	ed r/min	44.4	22.2
Total Reduction	on Ratio	1/45	1/90
Indexing Accu	uracy sec	±30	60
Net Weight	kg	84	
MAX. Work Load	0° to 30° kg	4	0
on the Table	30° to 90°	2	20
	Tilting Angle   F   F   F   N	53	300
MAX. Thrust Load	Tilting Angle	L= 45mm	F=3820N
applicable on the Table	Tilting Angle F1 F2 = 90° + F1 F2	L <sub>1</sub> =0mm L <sub>2</sub> =100mm	$F_1 = 2945N$ $F_2 = 1045N$
	Tilting Angle F FXL N·m	S	98
MAX. Work Inertia	+ (GD <sup>2</sup> /4) kg·m <sup>2</sup>	0.	03
Driving Torque	N·m	1	8

■ The Area of Noninterference in Tilting Position.



### **COMPACT TILTING ROTARY TABLE**





- Rotary and tilting axes are controlled by CNC
- Various kinds of attachments







ADD. ACCU

P.57















#### Specifications

Item / Code No.		5AX-130		5AX-201		
Diameter of T	able	1	05	200		
Diameter of S	pindle Hole	Ф 60н	7 Ф30	Ф60нт Ф50		
Center Height	t (90°) mm	1	50	180		
Table Height in H	Horizonatal Position (0°) mm	2	20	2	60	
Width of T Slo	ot mm	ф10Н7	Pin hole	12	+0.018 0	
Axis		Rotary	Tilting (0°∼105°)	Rotary	Tilting (0°∼105°)	
Clamping Sys	tem	Pneumatic*2	Pneumatic*2	Pneumatic*1*2/ Hydraulic	Pneumatic*1*2/ Hydraulic	
Clamping Tor	que N·m	205	303	303*1*2/ 588	303*1*2/ 612	
Table Inertia at I	Motor Shaft $\left(\frac{GD^2}{4}\right)$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	0.09	0.12	0.11	0.16	
Servo Motor	r/min	αiF2•3000	α iF2•2000	α iF2•3000	α iS4•2000	
MIN. Increme	nt	0.001°	0.001°	0.001°	0.001°	
Rotation Spec	ed r/min	33.3	11.1	33.3	16.6	
Total Reduction	on Ratio	1/90	1/180	1/90	1/120	
Indexing Accuracy sec		±30	60	±15	60	
Net Weight kg		1	115		160	
MAX. Work Load	0° to 30°	5	50	6	60	
on the Table	30° to 90°	2	25	4	40	
	Tilting Angle   F   C45   N	58	5880		300	
MAX. Thrust Load	Tilting Angle	L=65mm	F=2940N	L=100mm	F=4900N	
applicable on the Table	Tilting Angle F1 F2 = 90° +	L <sub>1</sub> =0mm L <sub>2</sub> =100mm			F <sub>1</sub> =5880N F <sub>2</sub> =2940N	
	Tilting Angle F FXL N·m	98		3	82	
MAX. Work Inertia	+ ( <u>GD<sup>2</sup></u> ) kg·m <sup>2</sup>	0.12		0	.5	
Driving Torque	N·m	72		7	72	

<sup>\*1</sup> Air brake system is also available for 5AX-201.

<sup>\*2</sup> Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase.

 $<sup>\</sup>bigstar$ Location of tilting axis motor can be changed as an option. e.g. 5AX-130B.



### 5AX-130, 5AX-201

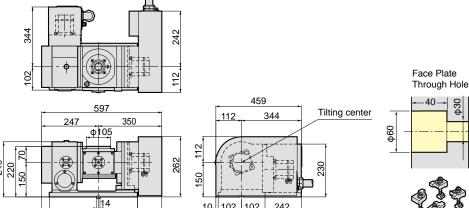


External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

### 5AX-130



Photo with φ130mm plate. (Standard accessories)









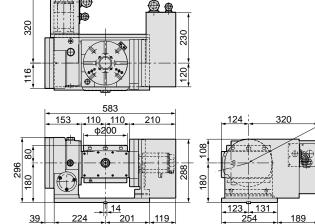


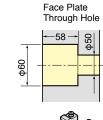
Center height of high column table is 65mm higher than that of standard table.



### 5AX-201

















Built-in type 4 ports rotary joint can be attached on standard type as an option. (High column type is not necessary.)

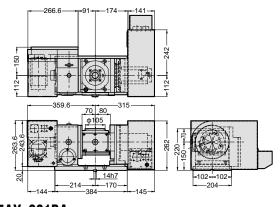
Clamp Device

#### ■ The Area of Noninterference in Tilting Position.

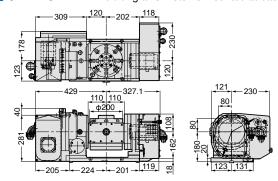
Angle	5AX-130	5AX-201
0° \$ 45°	φ135—	φ210 <del>4</del>
0° \$ 90°	ф300 ф135 с	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\
0° \$ 105°	ф235 ф135 02	φ250 - 15° φ210 - 08

#### **5AX-130BA** The tilting axis motor is mounted at back side.

Tilting center



**5AX-201BA** The tilting axis motor is mounted at back side.



### **STANDARD TILTING ROTARY TABLE**





- CNC tilting rotary table with powerful clamping system USA, EU: PAT
- A best-selling product suitable for use with mediumsize machining center
- Ideal for lines consisting of horizontal machines only



#### Specifications

Item / Code No.		5AX-230		5AX-250	
Diameter of T	able	23	80	250	
Diameter of S	pindle Hole	Ф 60н7	Ф40	Ф60нт Ф50	
Center Height	: (90°) mm	24	0	250	
Table Height in H	Horizonatal Position (0°) mm	28	5	25	50
Width of T Slo	ot mm	12 +	-0.018 0	12+	-0.018 0
Axis		Rotary	Tilting (0°∼105°)	Rotary	Tilting (0°∼105°)
Clamping Sys	tem	Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamping Tore	que N·m	490	3430	588	490
Table Inertia at I	Motor Shaft $\left(\frac{\text{GD}^2}{4}\right) \text{ kg·m}^2 \times 10^{-3}$	0.3	0.5	0.11	0.16
Servo Motor	r/min	α iF4•2000	α iF8•2000	α iF4•2000	α iF4•2000
MIN. Increme	nt	0.001°	0.001°	0.001°	0.001°
Rotation Spee	ed r/min	11.1	5.5	22.2	11.1
Total Reduction	on Ratio	1/180	1/360	1/90	1/180
Indexing Accu	iracy sec	20	60	20	60
Net Weight	kg	22	20	290	
MAX. Work Load	0° to 30° kg	100		80	
on the Table	30° to 90°	10	00	5	0
	Tilting Angle   F   F   F   P   P   P   P   P   P   P	117	760	98	00
MAX. Thrust Load	Tilting Angle	L=115mm	F=5880N	L=100mm	F=4900N
applicable on the Table	Tilting Angle	L <sub>1</sub> =0mm L <sub>2</sub> =100mm	F <sub>1</sub> =5880N F <sub>2</sub> =2940N	L <sub>1</sub> =0mm L <sub>2</sub> =100mm	F <sub>1</sub> =12040N F <sub>2</sub> =6020N
	Tilting Angle = 90° F FXL N·m	451		38	32
MAX. Work Inertia	+ $\left(\frac{\text{GD}^2}{4}\right) \text{ kg·m}^2$	0.66		0.	5
Driving Torque	N·m	28	38	14	14



### 5AX-230, 5AX-250



External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).



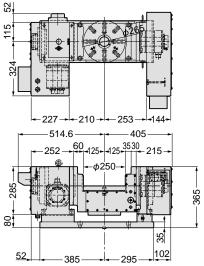


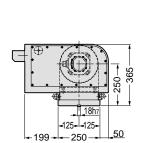
Center socket shown in photo is optional.

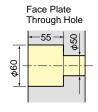


### 5AX-250











WITH FACE PLATE



Built-in type 3 ports rotary joint can be attached on standard type as an option.

#### ■ The Area of Noninterference in Tilting Position.

Angle	5AX-230	5AX-250
0° \$ 45°	φ350	φ315 φ260 φ260 Φ260
0° \$ 90°	φ480 φ320 β6	φ425 φ315 φ260 φ260 8
0° \$ 105°	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	φ315 φ260 08

Example when tilting base is supplied from M/C builder.



Tilting Base

### **STANDARD TILTING ROTARY TABLE**





- CNC tilting rotary table with powerful clamping system
- A best-selling product suitable for use with medium-size and large machining center
- Ideal for lines consisting of horizontal machines only













### Specifications

Iter	n / Code No.	5AX	-350	5A)	(-550
Diameter of T	able	3	50	550	
Diameter of S	pindle Hole	Ф8	0н7	Ф130н7	
Center Height	(90°) mm	3	00	3	80
Table Height in F	Horizonatal Position (0°) mm	3	00	5	18
Width of T Slo	ot mm	12	+0.018 0	14	+0.018 0
Axis		Rotary	Tilting (0°∼105°)	Rotary	Tilting (0°∼105°)
Clamping Sys	tem	Hydraulic	Hydraulic	Hydraulic	Hydraulic
Clamping Tore	que N·m	1568	1568	3430	6272
Table Inertia at I	Motor Shaft $\left(\frac{GD^2}{4}\right)$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	0.8	1.35	5.5	5.2
Servo Motor	r/min	α iF8 •2000	αiF12 •2000	αiF12 ⋅2000	α iF12 ⋅2000
MIN. Increme	nt	0.001°	0.001°	0.001°	0.001°
Rotation Spee	ed r/min	22.2	22.2	11.1	5.5
Total Reduction	on Ratio	1/90	1/90	1/180	1/360
Indexing Accu	iracy sec	20	60	20	60
Net Weight kg		420 (without Base:355)		1150	
MAX. Work Load	0° to 30°	2	00	5	00
on the Table	30° to 90°	2	00	3	00
	Tilting Angle   F   F   N	19	600	31	360
MAX. Thrust Load	Tilting Angle	L=175mm	F=4900N	L=275mm	F=9800N
applicable on the Table	Tilting Angle F <sub>1</sub> F <sub>2</sub> = 90° +	L₁=0mm L₂=100mm	F <sub>1</sub> =17160N F <sub>2</sub> =8580N	L <sub>1</sub> =0mm L <sub>2</sub> =200mm	F <sub>1</sub> =19600N F <sub>2</sub> =14120N
	Tilting Angle F FXL N·m	8:	58	29	548
MAX. Work Inertia	+ $\left(\frac{\text{GD}^2}{4}\right) \text{ kg·m}^2$	3.2			23
Driving Torque	N·m	2	88	8	64



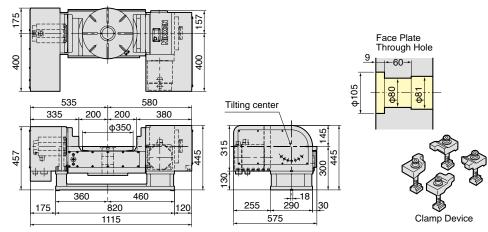
### 5AX-350, 5AX-550



External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### 5AX-350









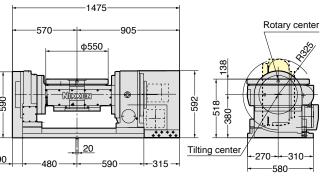
Built-in type 6 ports rotary joint is available on standard type. (optional) (High column type is not necessary)

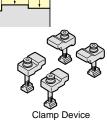
#### 5AX-550

### Powerful double clamping system on both ends of tilting axis



Center socket shown in photo is optional.









Built-in type 4 ports rotary joint is available on standard type. (optional) (High column type is not necessary)

#### ■ The Area of Noninterference in Tilting Position.

Angle	5AX-350	5AX-550
0° \$ 45°	0455 0400 02	04 0550 05 05
0° \$ 90°	\$\frac{\phi 540}{\phi 455}\$\$\$\frac{\phi 400}{\phi 400}\$\$\$?	φ750 φ640 φ550 Q4
0° \$ 105°	0 A 455 84 P	φ550 

Built-in type **5AX**- rotary tables are more and more getting popular as a component of M/C, even for the special applications.



Utilization for 4th and 5th axis rotary table of the M/C for die molding



Utilization for 4th and 5th axis rotary table of special grinding center



Ball Bar System



R-Test System

### **LARGE TILTING ROTARY TABLE**





- CNC tilting rotary table with powerful clamping system at both side
- Counter balance weight can be installed on 5AX-1200A to compensate the unbalancing load as standard
- Ideal for gantry type systems, machining centers, and 5-plane machines



#### Specifications The specification will be varied according to your application. Please contact us.

Iter	m / Code No.	5AX	-800	5AX	-1200	
Diameter of T	able	800×	500	1200		
Diameter of S		Ф1	30	Ф300н7		
Center Heigh	t (90°) mm	55	50	750		
Table Height in	Horizonatal Position (0°) mm	50	00	9	50	
Width of T Slo	ot mm	(14 +	0.018)*1	22	+0.018 * l	
Axis		Rotary	Tilting	Rotary	Tilting (-20°~105°)	
Clamping Sys	stem 3.5MPa	Hydraulic	Hydraulic	Hydraulic	Hydraulic	
Clamping Tor	que N·m	4655	6125	14700	19600	
Table Inertia at	Motor Shaft $(\frac{GD^2}{4})$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	6.8	6.0	10.8	3.5	
Servo Motor	r/min	αiF22•2000	αiF40•2000	α iF22•2000	α iF22•2000	
MIN. Increme	ent	0.001°	0.001°	0.001°	0.001°	
Rotation Spe	ed r/min	25	12.5	5.5	2.7	
Total Reducti	on Ratio	1/60	1/120	1/360	1/720	
Indexing Acc	uracy sec	20	60	20	60	
Indexing Accu	racy of Ultra Precision *2 sec	±5	±10	±5	±10	
Net Weight kg		2300		7300		
MAX. Work Load	0° to 30°	50	00	25	500	
on the Table	30° to 90°	50	00	15	500	
	Tilting Angle   F   = 0°	313	360	137	7200	
MAX. Thrust Load	Tilting Angle	2695		54	488	
applicable on the Table	Tilting Angle F <sub>1</sub> F <sub>2</sub> = 90° +	2824		9600		
Table	Tilting Angle F FXL N·m	2548				700
MAX. Work Inertia	+ ( <u>GD</u> <sup>2</sup> ) kg·m <sup>2</sup>	23		2	76	
Driving Torque	N·m	42	22	3	168	



### 5AX-800, 5AX-1200

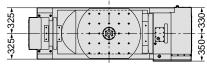


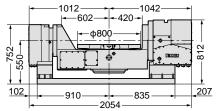
External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

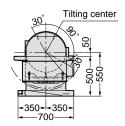
#### 5AX-800

#### Powerful double clamping system on both ends of tilting axis.





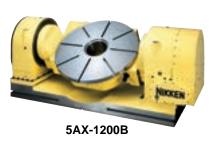


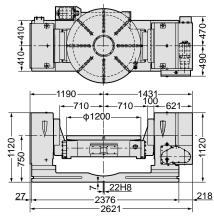


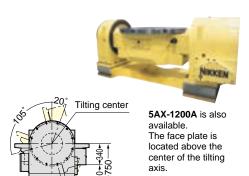


#### 5AX-1200

#### Powerful double clamping system on both ends of tilting axis.











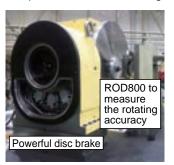
#### ■ The Area of Noninterference in Tilting Position.

Angle	5AX-800	5AX-1200
0° \$ 45°	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	Ф2900 Ф1300 Q2900 Ф1300 Q2900
0° \$ 90°	φ1080 φ800	ф1480 ф1280 024
0° \$ 120°	9800	15° φ1280

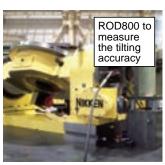
Counter balance weight can be installed on **5AX-1200A** to compensate the unbalancing load as standard.

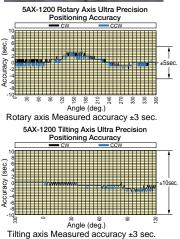
410<del>-|-</del>410-

820









### **MULTI-SPINDLE TILTING ROTARY TABLE**





■ Tilting rotary table with Multi-Spindle

Various attachment for fixing work piece

Ideal for small items and massproduced parts



Option ADD. ACCURACY ROTARY **AXIS** SPEC. JOINT P.57 P.99 P.89 P.87









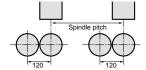


5AX-4MT-105-120

#### Specifications Multi-Spindle Tilting Rotary Tables are all semi-standard models. Please contact us.

Item / Code No.		5AX-2MT-105-120		5AX-4MT-105-120	
Diameter of T	able	1	05	105	
Diameter of S	pindle Hole	Ф60н	7 Ф30	Ф60нт Ф30	
Number of sp	indles (Pitch) mm	2 spind	les (120)	4 spindles (120)	
Center Height	t (90°) mm	1	75	:	235
Table Height in H	Horizonatal Position (0°) mm	2	50	;	300
Width of T Slo	ot mm	16	+0.018 0	16	S +0.018 0
Axis		Rotary	Tilting (0°∼105°)	Rotary	Tilting (−110°∼+110°)
Clamping Sys	stem	Pneumatic*1	Pneumatic*1	Hydraulic	Hydraulic
Clamping Tor	•	147	147	147	343
Table Inertia at I	Motor Shaft $\left(\frac{GD^2}{4}\right) \text{ kg} \cdot \text{m}^2 \times 10^{-3}$	0.13	0.13	0.2	0.48
Servo Motor	r/min	α iF2•3000	α iF2•2000	α iF8•3000	α iF4•2000
MIN. Increme	nt	0.001°	0.001°	0.001°	0.001°
Rotation Spee	ed r/min	33.3	11.1	16.6	16.6
Total Reduction Ratio		1/90	1/180	1/180	1/120
Indexing Accu	uracy sec	±30	60	±45	±30
Net Weight	kg	150		350	
MAX. Work Load	0° to 30°	15		25	
on the Table	30° to 90°	1	10		15
	Tilting Angle  F	3920		3	920
MAX. Thrust Load	Tilting Angle	L=60mm F <sub>1</sub> =784N		L=60mm	F=2858N
applicable on the Table	Tilting Angle F1 F2 = 90° +	L <sub>1</sub> =0mm F <sub>1</sub> =653N L <sub>2</sub> =100mm F <sub>2</sub> =490N		L <sub>1</sub> =0mm L <sub>2</sub> =100mn	F <sub>1</sub> =1380N n F <sub>2</sub> =1040N
	Tilting Angle L————————————————————————————————————	49			49
MAX. Work Inertia	+ $\left(\frac{GD^2}{4}\right) \text{ kg·m}^2$	0.014		0	.021
Driving Torque	N·m	3	36		144

<sup>\*1</sup> Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. 🖙 P.95



<sup>★</sup> Min. pitch between spindles:120mm. If you need different pitch, please contact us.

<sup>★ 4</sup> spindle rotary table to suit 2 Spindle M/C is also available, please contact with us.

<sup>★</sup> Max numbers of spindles:4 spindles.



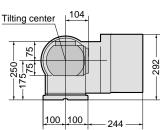
### 5AX-2MT,5AX-4MT

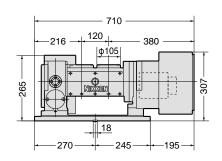


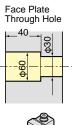
External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).

#### 5AX-2MT-105-120











Clamp Device







Center height of high column table is 35mm higher than that of standard table.

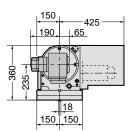
MAX. number of ports in rotary joint Standard: 4 ports, High Column: 6 ports

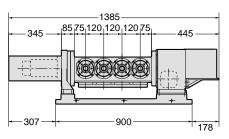
If you need a knock hole for positioning or a key way on the table surface, please contact us.

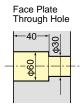
#### 5AX-4MT-105-120



4" Power chuck in photo is optional.













MAX. 6 port rotary joint can be installed on standard type as an option.

If you need a knock hole for positioning or a key way on the table surface, please contact us.

#### Multi-Spindle Tilting Rotary Table

For Multi-Spindle Tilting Rotary Table, please contact us to know the required faceplate diameters, fixture attachment (e.g. Power Chuck etc), the required spindle pitch, the M/C model and the type of NC.



5AX-2MT-170-200



5AX-2MT-201-250FA



5AX-2MT-200-360



5AX-2MT-200-250



5AX-2MT-201-320



5AX-2MT-180-250FA



5AX-2MT-130-170



5AX-2MT-182-250-205B

# DD

### **CNC ROTARY TABLE WITH DD MOTOR**

New

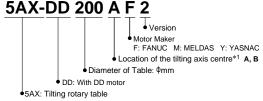
THE SMALLEST TILTING CNC ROTARY TABLE WITH DD MOTOR FOR COMPACT MACHINES



Ultra Compact Tilting Rotary Table with DD Motor

# 5AX-DD100

•Explanation of the Code No.(Example)





## Only 554mm Wide

The Smallest 5AX with DD Motor

### Demonstrates the true worth of a compact machining center with limited machining space.

With a body width of 554 mm, 5AX-DD100 is he smallest tilting rotary table with DD motor in NIKKEN's history. It is an ideal counterpart to products such as the BT30 compact machining center. It allows you to secure more machining space than was possible with earlier models.

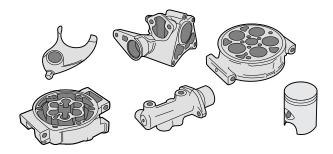
# Opens up New Possibilities for Machining with Compact M/C

### Suitable for many applications, from IT parts to automotive parts.

High-precision 5-axis machining of precision electronic devices such as smartphones, automobile parts, etc. can be accomplished using a compact machining center.



Impeller



Components of Automotive Parts

# High-acceleration/deceleration.

Compact unit with high-speed rotation

#### Standout performers in 5-axis high-speed machining

This compact unit employs a DD motor for high-speed rotation and high-acceleration/deceleration. Opens up new possibilities for cutting and machining, ranging from IT parts requiring high-speed, high-grade machining to auto parts requiring high-speed machining.

#### **NIKKEN's Exclusive "TT Solutions"**

#### As an expert in both tables and tooling, NIKKEN offers more.

Allows for even higher precision and efficiency when combined with our Mini-Mini Chuck Advanced Alpha collet chucks, which are standout performers in 5-axis machining.

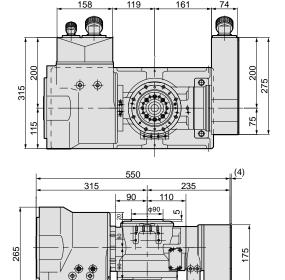


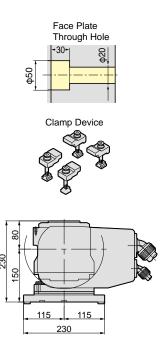
Image: 5AX Machining

### **5AX-DD100**









### ■ The Area of Noninterference in Tilting Position.

Angle	5AX-DD100
0°	φ200
0° <b>\$</b> 90°	φ200 
0° \$ 110°	\$20° \$200 \$200

#### **Specifications** The external dimension and the specification will be varied according to the DD motor. Please contact us.

4

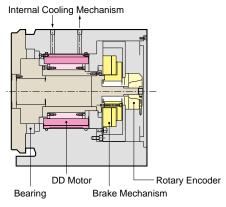
Item / Co	ode No.	5AX-DI	D100AF	
Diameter of Table	Фmm	90		
Diameter of Spindle	Hole ¢mm	50н7	ф20	
Center Height (90°)	mm	15	50	
Table Height in Horizonat	al Position (0°) mm	23	30	
Width of T Slot	mm	ф8н7 F	Pin hole	
Axis		Rotary	Tilting (0°∼110°)	
Clamping System		Pneumatic*1 (0.5MPa)	Pneumatic*1 (0.5MPa)	
Clamping Torqyue	Nm	75	205	
Motor (FANUC)		DiS15/1000	DiS60/400	
Encoder		MPRZ-536A MPRZ-536A		
Min. Incremental	deg.	0.001		
Rotation Speed	r/min	200	200	
indexing Accuracy	sec.	±10	±1	
MAX. Torque	Nm	35	130	
Constant Torque	Nm	8.7/16 <sup>*2</sup>	24/65*2	
Net Weight kg		120		
MAY Month of	0∼30deg. kg	2	0	
MAX. Work Load	0∼90deg. kg	10		

<sup>\*1</sup> Air-air Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase.

<sup>\*2</sup> Show the figures with cooling system.

### **CNC ROTARY TABLE with DD MOTOR**





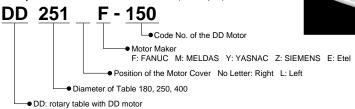
#### Configuration

There is no mechanical reduction mechanism such as worm system in a rotary table with DD motor. DD (Direct Drive) motor is built in the the rotary table to drive directly. High rotation speed and high acceleration/deceleration can be done. However, the driving torque of the rotary table is not strong due to no mechanical reduction mechanism. Therefore, the suitable application of the rotary table with DD motor must be selected.

High Response : 150r/min (DD251)

High Response of Micro Spike Clamping System

Explanation of the Code No.(Example)



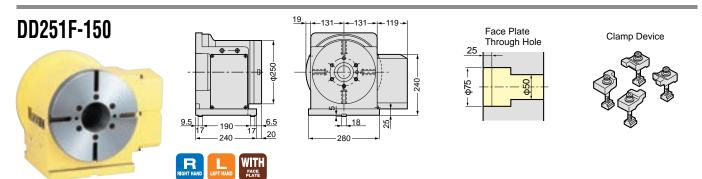
### **High-Acceleration / High-Speed / Compact Unit**

Suitable for the machining of the impeller.



Suitable for the machining of the impeller.

Micro Spike



#### **Specifications** The external dimension and the specification will be varied according to the DD motor. Please contact us.

Item / Code No.		DD180F-60	DD251F-150	DD400F-250	
Diameter of Table	фтт	180	250	400	
Diameter of Spindle Hole	фтт	ф30н7	ф <b>7</b> 5н7	ф100н7	
Center Height	mm	135	170	230	
Width of T Slot	mm	12н7	12н7	14н7	
Clamping System			Pneumatic*1 (0.5MPa)		
Clamping Torqyue	Nm	150	500	1000	
Motor (FANUC)		DiS60/400	DiS180/800-B	DiS250/250	
Encoder		lpha iCz Ser	lpha iCz Sensor 512A		
Min. Incremental	deg.		0.001		
Rotation Speed	r/min	200	150	125	
indexing Accuracy	sec.		±10		
Net Weight	kg	70	105	245	
MAX. Work Load	kg	50	100	250	
MAX. Torque	Nm	130	380	600	
Constant Torque	Nm	24/65 <sup>*2</sup>	73/170 <sup>*2</sup>	120/225 <sup>*2</sup>	
Necessary Cooling Capacit	ty w	1500	1600	1200	

<sup>\*1</sup> Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. 🐷 P.95

<sup>\*2</sup> Show the figures with cooling system. Please be careful that cooling by the special liquid may not be good for the chiller system. When cooling system is used, please check the cooling system, and stop the DD motor when the unusual condition is found.

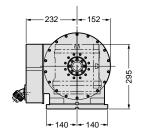
### **ROTARY TILTING TABLE with DD MOTOR**

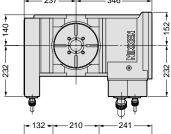


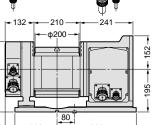
#### 5AX-DD200AF2 PAT.

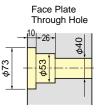


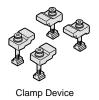
★The tilting axis center is located in the same position as the center of the rotary axis body.









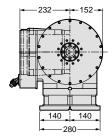


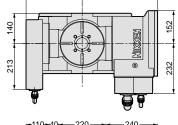


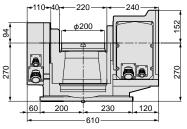
### 5AX-DD201BF3 PAT.

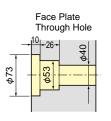


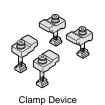
★The tilting axis center is located in the same position as the top surface of the rotary axis body.











#### **Specifications** The external dimension and the specification will be varied according to the DD motor. Please contact us.

Item / Co	ode No.	5AX-DD	200AF2	5AX-DD201BF3	
Diameter of Table	фmm	20	00	200	
Diameter of Spindle	Hole ¢mm	53	H7	53	Вн7
Center Height (90°)	mm	19	95	2	70
Table Height in Horizonata	al Position (0°) mm	29	95	2	70
Width of T Slot	mm	12	H7	12	2н7
Axis		Rotary	Tilting (±110°)	Rotary	Tilting (±110°)
Clamping System		Pneumatic*1 (0.5MPa)	Pneumatic*1 (0.5MPa)	Pneumatic*1 (0.5MPa)	Pneumatic*1 (0.5MPa)
Clamping Torqyue	Nm	150	500	150	500
Motor (FANUC)		DiS60/400	DiS150/300	DiS60/600-B	DiS180/800-B
Encoder		αiCz	512A	α iCz 512A	
Min. Incremental	deg.	0.0	001	0.001	
Rotation Speed	r/min	200	150	200	150
indexing Accuracy	sec.	±10	±15	±10	±15
MAX. Torque	Nm	130	380	140	400
Constant Torque	Nm	24	73/170 <sup>*2</sup>	34	75/180 <sup>*2</sup>
Net Weight	kg	190		205	
MAX. Work Load	0~30deg. kg	3	0	30	
IVIAA. VVOIK LOAD	0∼90deg. kg	1	5	30	

<sup>\*1</sup> Air Intensifying Booster system is available if the supplied air pressure is under 0.5MPa or the brake torque is required to increase. 🐷 P.95

<sup>\*2</sup> Show the figures with cooling system. Please be careful that cooling by the special liquid may not be good for the chiller system. When cooling system is used, please check the cooling system, and stop the DD motor when the unusual condition is found.

### **ROTARY TILTING TABLE with DD MOTOR**

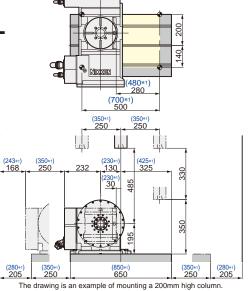


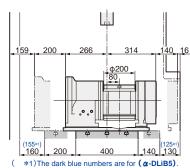
### 5AX-DD Table for **FANUC ROBO DRILL 5AX-DD200AF2**





Layout for the ROBO DRILL with 200mm high column



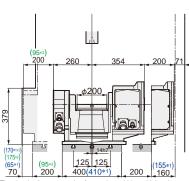


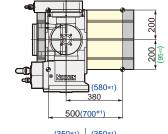
#### 5AX-DD201BF3

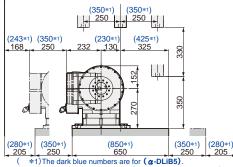




Layout for the ROBO DRILL with 200mm high column









5AX-DD200AF2

#### The Area of Noninterference in Tilting Position. 5AX-DD200AF2 **5AX-DD201BF3** Angle -45° φ285 9 5 65 45° Ф285 -90° 9 S 65 90° φ290 -110° φ240 09 72 S 65 110



### **Notice on the Use of DD TABLES**

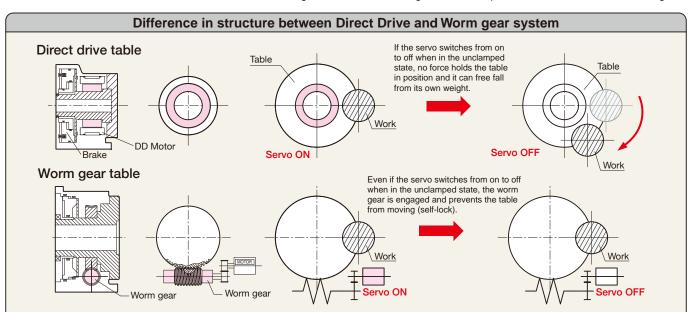


#### DD table characteristics

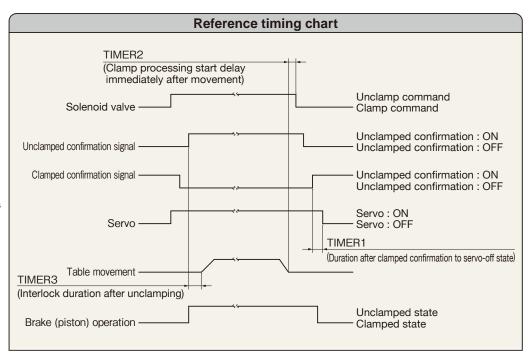
- The spindle is linked directly to the motor for excellent responsiveness. As a tradeoff for this responsiveness, the system is very sensitive to external force and loads, so it is necessary to set suitable parameters for each application.
- Adjustment is necessary to perform 5-axis simultaneous machining (synchronized machining). The NIKKEN standard parameters can be used for indexing and positioning. After confirming with the machine manufacturer that optional functions\* for synchronized machining are available, it is necessary to make appropriate settings to satisfy the customer's machining time and machining precision requirements. For simultaneous operation, suitable settings must be made to align the 4th (5th) axis with the three basic axes (XYZ).

#### Clamping operation

Due to the characteristics of the DD table it can be turned easily by hand if power is not being supplied (free run state). The table will again be in the free run state when the servo turns off after the brake is applied, unless appropriate settings are made, and this can cause positioning inaccuracy. Consult with the machine manufacturer to ensure that the timing is as shown in the timing chart below to prevent a free run state from occurring.



- Preventing emergencies (in case of power interruption) Configure a pneumatic (hydraulic) circuit (off-clamp) that will provide an effective brake should an emergency stop occur. Unlike normal clamping operation, in an emergency stop the brake is applied at the same time that the servo turns off momentarily, and this can result in positioning inaccuracy on an axis carrying a large load, such as the weight axis. To prevent this, enable the brake control function (FANUC), vertical axis drop prevention function (Mitsubishi), etc.
- Brake control function To prevent the fall of the weight axis when an alarm is generated or an emergency stop occurs, instead of stopping excitation of the motor immediately, excitation of the motor continues for the duration specified by a parameter to allow the mechanical brake to engage.
- Shaft core cooling system PAT. In the case of a DD table for turning ,there is also a system that forcibly cools from the center of the table in order to suppress the thermal displacement of the DD table itself.



#### Cooling of Direct Drive Servomotor

Except for some types of direct drive servomotor, you can choose no-cooling or liquid cooling. Keep cooling makes it possible to use under continuous rating torque. However, the special care is required because the continuous rating torque may fluctuate depending on the cooling condition.

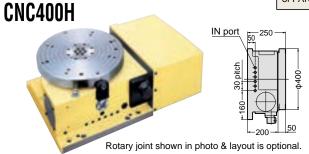
External cooling devices should be prepared for cooling, such as chiller unit which is normally used for high speed spindles. Oil cooling must be used; water cooling is not allowed to prevent the rust. Recommended cooling oil is [ISO VG2] equivalents. (Ex. IDEMITSU "SUPER MULTI 2")

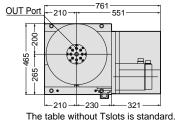
- •In the case cooling is needed: ① Long time continuous running under high (close to maximum) speed rotation ② Very long time running under overload (above rated torque-below maximum torque) ③ Using special super-high speed servomotors
- •Examples of cooling needed: ① Always-servo on under high-load condition (continuous turning operation) ② No-brake or the configuration that the servo is not off when clamping (Note: NIKKEN default configuration is servo OFF when clamping)

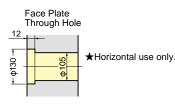
•Examples of cooling NOT needed: ① Indexing only ② Special use considering overload duty characteristics during non-cooling Please feel free to contact us if you need any concerns of questions regarding cooling or if you use direct drive rotary table under special conditions.

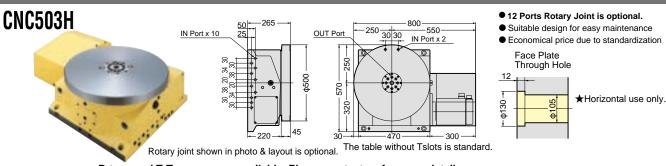
# **BUILT-IN BUILT-IN type CNC ROTARY TABLE**

External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).





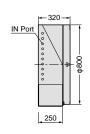


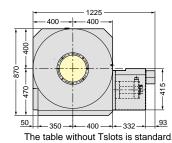


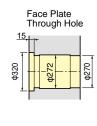
B-type and T-Type are now available. Please contact us for more detail.

### CNC802 Ultra Big Bore (\$\phi 270mm\$) Specification ★ Built-in type rotary joint can be mounted on CNC802 refer to \$\infty P.89\$









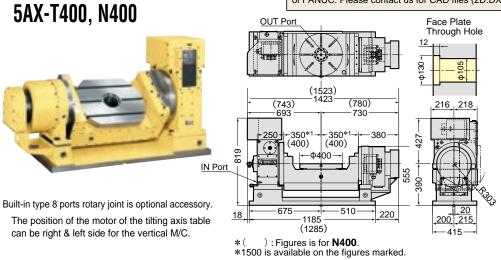
#### Specifications Built-type CNC Rotary Tables are all semi-standard models. Please contact us. ( ):High Speed type Please contact us.

		. ,		
Item /	Code No.	CNC400H CNCZ400H	CNC503H CNCZ503H	CNC802
Diameter of Ta	ıble ¢mm	Ф400	Ф500	Ф800
Diameter of Spi	ndle Hole	Ф105н7	Ф105н7	Ф270н7
Clamping Syst	em 3.5MPa	Hydraulic	Hydraulic	Hydraulic
Clamping Torq	ue N·m	1760	1890	7000
Table Inertia at Motor	Shaft $\binom{GD^2}{4}$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	2.8	8	5.3
Servo Motor	r/min	α iF12 ⋅2000	αiF12·2000	α iF22•2000
MIN. Incremen	t	0.001°	0.001°	0.001°
Rotation Spee	d r/min	22.2(44.4)	16.6(33.3)	5.5
Total Reductio	n Ratio	1/90 (1/45)	1/120 (1/60)	1/360
Indexing Accur	racy sec	20	20	15
Net Weight	kg	295	400	1100
MAX. Work Load on the Table	Horizontal kg	500	1000	3000
MAX.	N N	53100	63720	247920
Thrust Load applicable on the Table	*1 FXL N·m	2648	3531	8563
on the rable	F×L N·m	3840	5990	36260
MAX. Work Inertia	$\left(\frac{\text{GD}^2}{4}\right) \text{kg·m}^2$	16.6(8.3)	32.5(16.3)	234
Driving Torque	N·m	432 (345)	576 (460)	3168

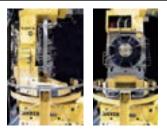
## **BUILT-IN type TILTING ROTARY TABLE**



External dimensions depend on the type of the servo motor. Indicated dimensions are in case of FANUC. Please contact us for CAD files (2D:DXF, 3D:PARASOLID).







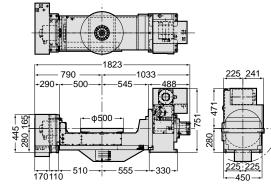
#### Combination of CNC503H & CNC302T



5AX-B450

Built-in type 17 ports rotary joint is optional accessory. The position of the motor of the tilting axis table can be right or left side for the vertical M/C.

#### Tilting base will be supplied from M/C builder.





T400

Item / Code No.	5AX-	T400 N400	5AX-B450		
Diameter of Table	400		500		
Diameter of Spindle Hole \$\phi\$mm	ф10	)5н7	Ф155н	7 ф109	
Center Height (90°) mm	3	90	280	<sub>0</sub> *1	
Table Height in Horizontal Position (0°) mm	3:	90	280	)*1	
Width of T Slot mm	14 0	0.018	-	-	
Axis	Rotary	Tilting	Rotary	Tilting	
Clamping System 3.5MPa	Hydraulic	Hydraulic	Hydraulic	Hydraulic	
Clamping Torque N·m	1760	1760	1760	3870	
Table Inertia at Motor Shaft (GD <sup>2</sup> /4) kg·m <sup>2</sup> ×10 <sup>-3</sup>	2.8	2.44	2.8	2.9	
Servo Motor r/min	αiF12 •2000	aiF22 •2000	αiF12 •2000	aiF22 •2000	
MIN. Increment	0.001°	0.001°	0.001°	0.001°	
Rotation Speed r/min	22.2	16.6	22.2	16.6	
Total Reduction Ratio	1/90	1/120	1/90	1/120	
Indexing Accuracy sec	15	60	20	60	
Net Weight kg	750( <b>w/c</b> 995( <b>wit</b> l	,	1050( <b>w/o base</b> )		

Item /	Code No.	5AX-T400 N400	5AX-B450
MAX. Work Load	0° to 30° kg	300	300
on the Table	30° to 90°	250	250
	Tilting Angle = 0°	31360	31360
MAX. Thrust Load	Tilting Angle = 0°	L=200mm F=6860N	L=250mm F=5488N
applicable on the Table	Tilting Angle = 90°  F1 F2  + C	L=100mm F=11660N	L=100mm F=11660N
	Tilting Angle = 90°  L  F  F  K  N·m	1166	1166
MAX. Work Inertia	$+ \frac{1}{\left(\frac{GD^2}{4}\right)} \text{ kg·m}^2$	5.1	5.1
Driving Torque	N·m	432	432



### **Servo Motor List**



#### **Maker and Motor Model**

Stall	Torque	)	1 Nm	2 Nm	3 Nm	6 Nm	12 Nm	22 Nm
Rotatio	on Spec	ed	2000r/min	2000r/min	2000r/min	2000r/min	2000r/min	2000r/min
Maker		Model 1	Model 1 Model 2 Model 3 Model 6		Model 6	Model 12	Model 22	
			<b>≪</b> iF1/5000	<b>X</b> iF2/5000	<b>≪</b> iF4/5000	<b>≪</b> iF8/3000	<b>≪</b> iF12/4000	<b>X</b> iF22/3000
FA	NUC		<b>X</b> iS2/5000	<b>∝</b> iS4/5000	<b>⋉</b> iS8/4000	<b>∝</b> iS12/4000	<b>∝</b> iS22/4000	<b>α</b> iS30/4000
			βiS2/4000	βiS4/4000	βiS8/3000	βiS12/3000	βiS22/2000	
			HF75T	HF105T	HF54T	HF104T	HF204S	HF354S
ME	LDAS				HP54T	HP104T	HP204S	HP354S
			HG56T	HG75T	HG104T	HG154T	HG204S	HG354S
			SGMPH-04AAA6S	SGMPH-08AAA6S	SGMGH-05ACA5S	SGMGH-09ACA5S	SGMGH-20ACA2S	SGMGH-30ACA2S
YAS	SNAC		SGMAV-04A3A6S	SGMGV-03A3A6S	SGMGV-05A3A6S	SGMGV-09A3A6S	SGMGV-20A3A2S	SGMGV-30A3A2S
			SGM7A-04A7A6S	SGM7G-03A7A6S	SGM7G-05A7A6S	SGM7G-09A7A2S	SGM7G-20A7A2S	SGM7A-30A7A2S
	OSP2			BL-MC24J-30S	BL-MC25J-30T	BL-MC50J-30T	BL-MC100J-20S	BL-MC200J-20S
OSP	OSP3			BL-ME24J-50SN	BL-ME40J-40TN	BL-ME80J-40TN	BL-ME100J-30SN	BL-ME200J-20SN
OSI	OSP4			BL-ME24M-50SN	BL-ME40M-40TN	BL-ME80M-40TN	BL-ME100M-30SN	BL-ME200M-20SN
	OSP4	NEW			BL-MT40M-40TN	BL-MT80M-40TN	BL-MT100M-30SN	BL-MT200M-20SN
					MFA055MBJNC1	MFA100MBJNC1	MFA180MBJNB	MFA350MBJNB
TO	CMILC		MDM032R4L	MDM062R4L	MDM052R4L	MDM152R4L	MDM212R4C	MDM402R4C
10.	TOSNUC				MHMA052K2LA	MHME102F2CA	MTMA402F2CA	MTMA552F2CA
			MHMD482S1C	MHMD082S1C	MHME102SCC	MHME152SCC	MHME302SCC	MHME402SCC
Brother	SANY	O*1	R2AD08040FXPGA		R2AAB8100HXPGA			
Diotilei	SANY	O*2	R2AA08040FXR5E		R2AAB8100HXRGA			
SIE	MENS		1FT-6031-4AK71	1FT-6034-4AK71	1FT-6044-1AK71	1FT-6064-1AK71	1FT-6082-1AF71	1FT-6086-1AF71
SIL	WILING			1FK-7042	1FK-7060	1FK-7063	1FK-7083	
INDF	RAMAT		MAC63A	MAC63C	MAC71B	MAC71C	MAC93B	MAC93C
HEIDI	HEIDENHAIN			QSY96A	QSY116C	QSY116E	QSY155B	QSY155D
	FLEX				444,2,20	444,3,20	445,2,20	
	EM			HJ96C6-44	HJ116C6-64	HJ116E6-130	HJ155A8-130	HJT155D8-180
	SCH		SE-B2.010	SE-B2.020	SE-B3.055	SE-B3.075	SE-B4.130	SE-B4.210
GLE	NTEK		GM3340	GM4020	GM4040,GM4050	GM5065		
KOLLI	MORGE	N	6SM37L	6SM47L	6SM57L	6SM57M	6SM77K	

- \*1 The end of the rotary table Code No. is "SA-BR2"
- \*2 The end of the rotary table Code No. is "SA-BR3"
- ★The characteristics(stall torque, MAX. torque and rotor inertia etc.) of the servo motors differ, therefore the specification of CNC rotary table will be
- ★Other servo motor can be mounted, please inform us the external dimension, specification of your servo motor.



### Relation between Unbalancing Load and Servo Motor **NIKKEN**

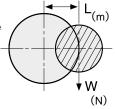


This table shows the guide line. Please make the unbalancing load as small as possible to use the counter balance weight for the precision machining.

Excessive unbalancing load causes the indexing accuracy and the durability to be worse. The relation between the guide line of the unbalancing load and the servo motor shows below. Please do not apply the load exceeding the guide line.

CNCZ series table can not be recommended for the application with large unbalancing load. CNCZ series table is recommended for the application only with light load.

Please inform us the detail of the component, jig fixture, indexing time etc. prior to your order. Then, the calculation of the load is studied and the best suitable rotary table (including the suitable motor) for your application is proposed. The servo parameter is also tuned.



### Guide Line of MAX. Unbalancing Load for Additional Axis Control Please contact us for the other maker.

FANUC motor is described.

MAX. Unbalancing Load (N·m)	CNC180FA	CNC202FA	NCT200FA	CNC302FA	CNC321FA 401FA	CNCB450FA	CNC <sup>501FA</sup>
30	≪iF2						
50	≪iF4	≪iF4					
60			≪iF4	≪iF4			
100				≪iF8	≪iF12		
150						≪iF12	
200					≪iF22		≪iF12
300						≪iF22	
400							≪iF22

#### Guide Line of MAX. Unbalancing Load with NIKKEN Controller

MAX. Unbalancing Load (N·m)	CNC180	CNC202	NCT200	CNC260	CNC302
10	CNC180AR21-04				
20	CNC180AR21-08	CNC202AR21-08	NCT200AR21-08		
30				CNC260AR21-08	CNC302AR21-08
50	CNC180AR21-06	CNC202AR21-06			
60			NCT200AR21-06	CNC260AR21-06	CNC302AR21-06

### Flow Chart of the Additional Axis Control



Servo enable is basically kept OFF during the mechanical brake clamps. Servo enable is recommended to be kept ON, even when the mechanical brake clamps for the CNC rotary tables listed in the box below. But, the case when a big electric current always flows in the motor due to the heavy unbalancing load, please keep servo enable OFF when the mechanical brake clamps.

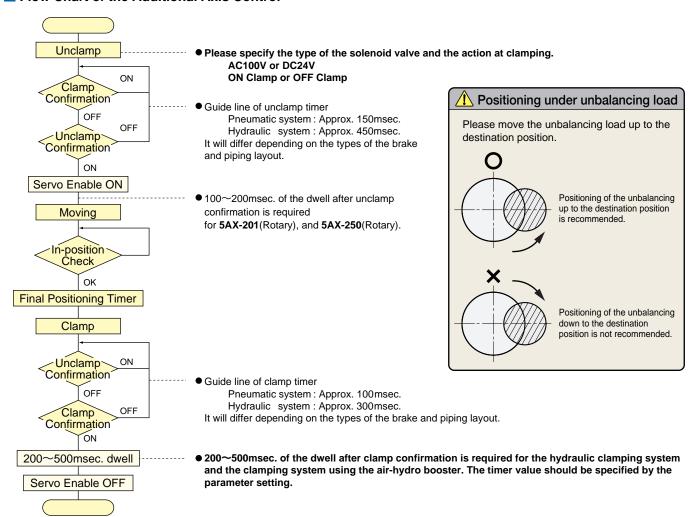
- ·CNC321, 401, 501, 601, 802, 803
- ·CNC400H, 503H
- ·5AX-250 (Tilting)
- ·5AX-T(N)400 (Rotary. Tilting)



Please specify the brake control when ordering

- ·Type of solenoid valve (AC100V or DC24V)
- ·Motion of solenoid valve for clamp (ON: Clamp, OFF: Clamp)

#### Flow Chart of the Additional Axis Control

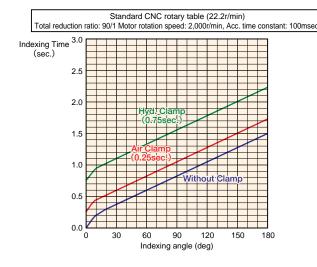


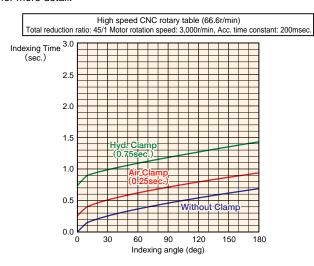


### **Indexing Time**



Guide line of the indexing time is shown. The indexing time will be different according to the total reduction ratio, motor rotation speed, servo parameter setting and the piping of the brake circuit. Please contact us for more detail.





# M-signal CNC ROTARY TABLE with AR21 CONTROLLER

- Minimum Command Increment: 0.001° or 1sec.

  AR21 controller can drive all models of NIKKEN CNC rotary table.
- Single M signal provides Various Automatic Operation.

  Any unequal dividing, equal dividing, arc cutting, lead cutting etc.

  can be done very easily.
- USB interface as standard equipment

  By connecting to a PC, program data and parameters can be input and output.

  (However, communication software is required on the PC side.)
- Upgrade of Water Proof Characteristic EMC Assessment → P.103

The direct out type connection is applied for all models of CNC rotary table, and the EMC assessment is satisfied as the total system.

Digital Servo System & Absolute Encoder

Very excellent acceleration/deceleration characteristics, the powered up torque

and the best suited servo parameter realize the high quality and long life.

All after Power ON or after releasing the emergency stop condition is not necessary.\*

Plenty of Optional Functions

True Closed Loop, Manual Pulse Generator, M Function (Input: 5/ Output: 5), External N Number Search, External Position Display, External Power ON/OFF, Pitch Error Compensation

- More than 30,000 sets working in the field. This fact ensures the highest reliability.
- Product compatible with ROHS2-10 commands

  The AR21 controller is now ROHS2-10 compliant and has the product code AR21, which can be shipped to EU member countries.
- \*: The operation to establish the coordinate system is required at once, when turning the POWER ON at first time just after connecting the cable. Please refer to P.62



AR21 controller

- Standard (400W, 750W)= 300×280×285 10kg
- · Single Phase AC200/220V



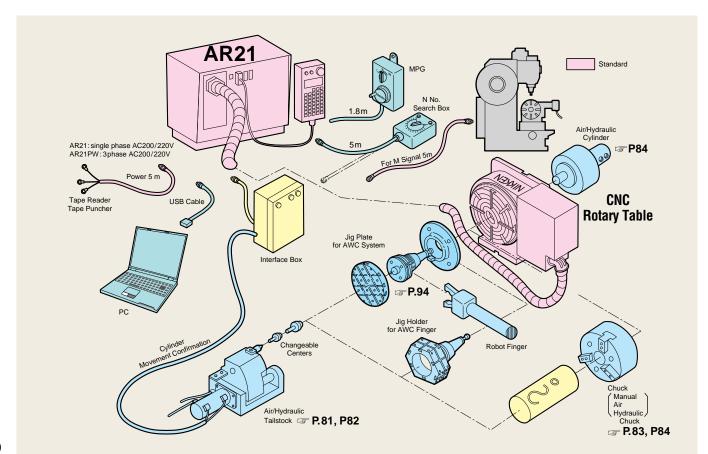
AR21 PW controller • Power up (1.3KW, 1.8KW) 540×360×400 28kg

· 3 phase AC200/220V



AR21 controller for larger capacity (2.7KW, 4.4KW and 11kW) is available.

· 3 phase AC200/220V



### **AR21 CONTROLLER Specification**



#### Main Specification of Controller (NIKKEN-AR21 controller)

Item	Specification	Remarks
MIN. Increment	0.001° or 1"	Free Selection
MAX. Programmable Angle	±9999 rotation, ±999.999° & ±999°59'59"	Free Selection
MAX. Equal Dividing	2~9999 equal dividing	
Program Capacity	rogram Capacity 1000 Blocks	
Input System	MDI Key Board, Pendant type	5 years memory
Programming System	Combined use of Incremental/Absolute	Free Selection of G91 / G90
Zero Return	Machine Zero Position/Work Zero Position	can be commanded from outside.
Manual Feed	Rapid Feed/Fine Feed/Step Feed/Continuous Feed	
Uni-directional Positioning	Uni-directional Positioning can be done to eliminate the mechanical backlash.	G14
Emergency Stop	Whole system stops	can be commanded from outside.
Feed Hold	Table rotation temporarily stops.	can be commanded from outside.
Jump Function	Jump to sub program etc.	
Repeating Function	By specifying start No. and final No., multiple sequence are repeated.	
Buffer Function	Reading next block, and execute job without stop.	Useful for lead cutting etc.
Dry Run	Table always rotates in rapid feed for checking.	
Key Lock Function	Even if operation button is pressed by mistake, such command is neglected for safety.	
Preparatory Function	Dwell, Clamping/Unclamping, Lead Cutting	G04~G92
G1 Code, G2 Code	2 kind of G codes can be entered in one block.	
Block Data display	At programming, previous block data or next block data are displayed.	
USB Interface	Program data and parameters can be input and output.	
Software Limit Function	± stroke limit values can be set by parameter.	
Over Travel Detection Function	Over travel detection zone can be set at outside of software limit by using control circuit, and the CNC rotary table can be protected not to exceed safety zone.	Standard for 5AX- type tilting axis
Alarm No. Automatic Indication Function	When alarm is detected, controller automatically goes to diagnosis mode and Alarm No. is displayed.	When duplicated, it flickers every 2 sec.
Alarm Out	Alarm condition of AR21 can be sent to M/C	
Emergency Stop Out	Emergency stop condition of AR21 can be sent to M/C.	
Self Diagnosis Function	Inside situations of controller can be seen.	
Modal G Code Flicker Function	All G codes used in program are indicated in flickering.	Every 2 sec.
Pitch Error Compensation Function	Rotary axis: 15° unit, Tilting axis: 5° unit	Option
Feed Rate Override	5~200%,999% (Rapid feed)	±5%
nput Signals 1 kind of Auxiliary Function.(Automatic operation can be done by only one M signal.)		With or without contact signal *1
Output Signal 1 Block Finish signal, Work Zero Position Signal, Alarm Out Signal *2		Ask Time Chart
Servo Motor	AC servo motor with serial encoder	
Input Power	AR21: Single phase AC200~220V, 50Hz / 60Hz	400W:480VA*3,750W:760VA*3
pac : Onoi	AR21PW: 3 phase AC200~220V, 50Hz / 60Hz	1.3kW:960VA* <sup>3</sup> ,1.8kW:1.2KVA* <sup>3</sup>

<sup>\*1:</sup> M signal of M/C is valid only the block without DEN (Distribution End).

#### OPTIONAL SPECIFICATION

#### 1 True Closed Loop

This is to be used for ultra precision rotary table.

#### Manual pulse generator (X1, X10, X100)

This pulse generator enables the table to be rotate or tilted by manual operation on every 0.001∼0.1° unit.

#### 3 Five M functions

Control and confirmation of other actuator (hydraulic tailstock, coolant controller, robot etc.) can be done from AR21side.
AR21 for AWC, this is included as standard.

#### 4 External N Number Search Function

When plural programs are entered in 1000 blocks. Desired N number can be searched from outside (applicable also to FMS line)

#### 5 External Power ON/OFF

Interface to perform Power ON/OFF by external circuit is available.

#### 6 Pitch Error Compensation

Rotary Axis:

by 15° unit × 24 points Tilting Axis:

by 5° unit x 24 points The optimum correction value is adjusted and shipped with increased indexing accuracy.

#### 7 Output Signal \*2

Work Zero position signal is the signal set to ON while the CNC rotary table is in the work zero position. Alarm Out signal is the signal set to ON when AR21 is in alarm condition. These signals can be used for interlocking function.

#### 8 Direct Angle Command Interface

By connecting the machine side RS232C interface to the AR21 controller, it is possible to manage all the programs of the AR21 controller.
For details, please refer to page 76.

#### 9 Harting Connector Type...Only for AR21

Harting Connector can be corresponded to the CNC Rotary Table side.
The AR21PW controller is not compatible.

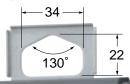


<sup>\*2:</sup> Work Zero Position Signal and Alarm Out Signal are optional signals.

<sup>\*3</sup> Input load capacity at 40% of average load factor.

### **Explanation of PENDANT 1**







- 1 Power Switch
  - (2) Emergency Stop Button
- **- | | | + |** 34 Manual Jog Button
- (5) High Speed Button
  - (6) Auto/Manual Select Switch
  - 7 Edit/Current Position Select Switch
  - (START (8) Start Button
  - 9 Stop Button
  - CF 10 Continuous Feed Button
  - ORG (11) Original Point Set Button
  - 12 Machine Zero Return Button
  - (3) Work Zero Return Button
  - DGN (14) Diagnosis Button
- 1 | 1 15 Increment/ Decrement of Block No.
- (16) Feed Rate Override Button OVR OVR
  - 17 Reset Key
- **READY** ······Turned ON when input power is supplied. ● COM.····Turned ON while AR21 main unit and the
  - pendant are communicating.
- **ALARM**······Turned ON when AR21 is in alarm condition.
- COM . ALARM ···· Turned ON when communication time out error occurs between AR21 main unit and the pendant.





#### 1 Power Switch







**34 Manual Jog Button** ▶ + Clockwise, - ◀ Counter clockwise. While this button is being depressed, the table continually rotates slowly. When this button is depressed once, the table steps by 0.001°(1").

#### 5 High Speed Button

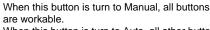


When this button is depressed together with ③ or 4,the table rotates in rapid feed. When jog 11 while depressing 5, table moves

	,
Gear Ratio	Table Movement
1:720	0.5°
1:360	1.0°
1:180	2.0°
1 · 120	3.0°

Gear Ratio	Table Movement
1:90	4.0°
1:60	6.0°
1:45	8.0°

#### 6 Auto/Manual Select Switch



When this button is turn to Auto, all other buttons except 1,2,6,8,9,4,6,17 are ineffective.



#### 7 Edit/Current Position Select Switch

On  $\theta$  of  $\circledR,$  programming or present position is displayed alternatively.



#### (8) Start Button

The table rotates as programmed.



#### Stop Button

The table slows down and stops. (Feed Hold Function). When ® is depressed again, the table rotates the remaining angle of the



#### 10 Continuous Feed Button

When this button is depressed, the table rotates continually. And, when (9) is depressed, the table stops. The desired feed and direction are to be input in N997 Block. (Refer P.53 ®)



#### 11 Original Point Set Button

When this button is depressed at any angle, the position display shows 000.000°, and it is used as the work zero position. When the cumulative angle becomes 360°, work zero position signal is sent, which can be used as interlock.



M ZRN

12 Machine Zero Return Button When this button is depressed, the table returns to the machine zero position (0° of the graduation of the table) clockwise in rapid feed, then low speed for final positioning.



#### 13 Work Zero Return Button

When this button is depressed, the table returns to the position set by (1) clockwise in rapid feed.



#### **14** Diagnosis Button

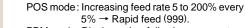
(5) Increment/Decrement of Block No. Previous block data and next block data are displayed.



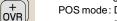
OVR



#### 16 Feed Rate Override Button



PRM mode: Displays the following parameters sequentially.



POS mode: Decreasing feed rate 200 to 5% every 5%. PRM mode: Displays the proceeding parameters



**17** Reset Key

This is for calling N000 and also for resetting alarm display etc.

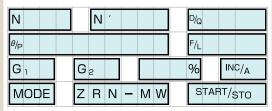
sequentially.



### **Explanation of PENDANT 2**



® Display



N: Sequence No. N000~N999

NRS: Direct angle command interface is selected.

N': Jump & Return J000~J999, RET

θ: Rotation angle of table (Decimal, Sexagecimal) 0~±999.999° (Decimal)

0~±999.59'59" (Sexagecimal)

D: Equal division (divided by 2 to 9999)

F: Feed rate

Cutting feed: 0.01~9.99r/min

Rapid feed: 000

G: Preparatory function G01~G92 Two kind of G codes (G1, G2) can be input in one block.

%: Feed rate override

(5% to 200%, or 999 for rapid feed rate)

P: Starting block No. of repeating function (G27)

Q: Final block No. of repeating function (G27)

L: Repeating frequency (G27)

INC/ABS: INC (Incremental)

ABS (Absolute)

MODE: EDT (Edit mode)

MAN (Manual mode)

AUT (Auto. mode)

MPG (MPG mode) **DGN** (Diagnostic mode)

#### ZRN-MW

M Flickering (Returning to M ZERO)

M (Stop at M ZERO)

W Flickering (Returning to W ZERO)

W (Stop at W ZERO)

START/STOP: START (Starting)

STOP (Stop)

**Key Encoder** 

For calling a certain sequence, input the number after this key so that the program of the block is display, also you can start from the program.

This key is to be used when you want to call sub program N' or jump to N' after N block is completed.

When sub program is finished, enter R at ® N' display. And, it returns to the block next to the one where J' was commanded in the main program.

θ : You can input 0° to ±999.999° in 0.001° increment, or 0° to ±999°59'59" in 1" increment.

The selection of decimal or sexagesimal system is set up by parameter.

In case of Dwell Instruction (G04), the waiting time is inputted. (0.001 to ±999.999 sec.).

P: Starting number of repeating function (G27) 000 to 999.

**DIV**: Automatic equal dividing times 0 to 9999. Lead cutting instruction (G07) 0 to 999.

Q: Final number of repeating function (G27) 000 to 999.



F: Cutting feed F001(0.01 r/min) to F999(9.99 Rapid feed F000 or F0.

L: Repeating frequency 0 to 999.



Without G: Positioning G21 : Simultaneous start G04: Dwell G22: Continuous start G23: Machine zero point return G06 : Constant acceleration G07: Rotation number G24: Work zero point return \* G08: Buffer commencing G27: Repeating function \* G09 : Buffer ending G28: Programmable machine

\* G10: Brake unclamped Pzero position return \* G11 : Brake clamped \* G90 : Absolute command

G14: Uni-directional positioning \* G91 : Incremental command \* G15: Droop check G92: Coordinate system setting

\* G16: Droop cancel

#### M Function (Option)

G60~G74: Activate an actuator

#### How to enter G code:

0 cannot be suppressed for both G1 and G2 codes. For example, when G1=07 and G2=08, enter them

G0708\*

and indication will become as;





When you want to enter 9°, just depress keys as  $\Theta \rightarrow \Theta \rightarrow \bullet$ , and 9.000° or 9°00′00″ is displayed.



This is for command of Counter clockwise rotation.



This is depressed as programming of each block being completed.

(Hereafter shown as \*).



For deletion or alternation of  $\theta$ , DIV, or F individually, just depress  $\theta$ , DIV, or F, then depress. Also when you depress \* with pressing C, complete one block is deleted.

#### Deleting successive blocks

For example, in order to delete blocks from N000 to N999, push keys N0 -999 at Edit mode, and jog while depressing **c** key.

means optional function.

Operation of the pendant of AR21 controller for tilting axis specification and for NSV index specification differs, please refer instruction manual.

#### Caution for AR21 Controller

- The alarm regarding the absolute encoder will be appeared, when turning the POWER ON at first time just after connecting the cable. This is because the coodinate system is not established yet. Please try as follows;
  - DGN Return to pervious mode.
  - PRM#110=1 Writting parameter value enable.
  - $G_{NO}$  7 2  $A_{DATA}$  1 PRM#72=1
  - · Turn the POWER OFF and ON
  - For rotary axis (M) Execute machine zero return. For tilting axis

First set the temporary machine zero position and [M]. Please refer instruction manual for more detail.

• When the alarms regarding the absolute encoder such as ALARM#1101 or #1102 are appeared, please set PRM#71=1 and turn the POWER OFF and ON to establish the coodinate system again.



Ν

(3digits)

J

(3digits)

RET

| **=** 

 $\theta$  (±6~7digits)

P (3 digits)



# **Operation & Confirmation of PROGRAMS**



#### Operation of Keys.

Before programing, be sure that mode is <a href="EDT">EDT</a>.

Before start the programs, push <a href="EDT">II</a> ...... in <a href="EDT">EDT</a> mode, and confirm input date. Then start the program in <a href="MAN">MAN</a> mode to confirm the moving.

Then start the program in MAN mode to confirm the moving.				
① Angle Dividing	45°	Rapid feed.  Input Angle  No need of pressing 0 under decimal point.  No 0 0 0 →   Sequence No.		
② Arc Milling	45.123°	N 0 0 0 θ 4 5 1 2 3 F 1 2 3 R  123 x 1/100 r/min rotation speed.  means 45.123°  Cutting Feed : = 2 πR x 1.23 r/min  = 7.7 R mm/min.		
③ Equal Dividing	45° 45° 45° 45° 45° 45° 45° 45° 45° 45°	N 0 0 0		
④ Unequal Dividing	57.396° 45° 35.12° 61.567° 93.567°	N 0 0 0 0 4 5		
⑤ Incremental/ Absolute Dividing	90.987° 45.123° 181.567°	N 0 0 0 0 0 4 5 1 2 3		
© Repeating Function	13 <sub>14</sub> 13 14 18 13 14 11 13 14 18	N 0 0 0 0 1 3		
© Counter Clockwise Rotation	45°	N 0 0 0 0		
® Continuous Feed 0.5		N 9 9 7 0 0 F 5 0 Continuous feed 0.5r/min (CCW)  Command of continuous FeedStart  Stop		
9 Equal Dividing of Arc	158° 90° 13 112° 23 dividing	N 0 0 0		
Equal Dividing of Circle (360°)	1231 1231 equal 91 77 111 dividing	N 0 0 0 0 3 6 0 0 m       9 1 F 0 ★       91 Equal dividing of circle and go to N001         0 0 1 0 3 6 0 0 m       7 7 ★       77 Equal dividing of circle and go to N002         0 0 2 0 3 6 0 0 m       1 1 1 ★       111 Equal dividing of circle and go to N003         0 0 3 0 3 6 0 0 m       2 3 1 ★       231 Equal dividing of circle and go to N004         0 0 4 0 0 0 3 6 0 0 m       1 2 3 1 ★       1231 Equal dividing of circle and return to N000		
(300 )		Ontinual Supplies tion		
M function		Optional Specification  N 0 0 0 G 6 0  Tailstock forward  0 0 1 G 3 6 0		

### **Example of PROGRAMS**





#### Program of NC Machine

0 0 0 0 0; ··· Main program
 M 9 8 P 0 1 0 0 L 2 3; ··· Drilling cycle 23 times
 M 9 8 P 0 1 0 1 L 2 3; ··· Tapping cycle 23 times
 M 0 2;

**0 0 1 0 0** ;...Sub program 1

G 0 1 Z — ;···Drilling fixed cycle
M 2 1 ; ----M 9 9 ;

**0 0 1 0 1**; ... Sub Program 2

G 0 1 Z — ;···Tapping fixed cycle
M 2 1 ; ----M 9 9 :

111 3 3

#### **2** Example for Arc Milling

Program of NC Machine

0 0 0 0 1; M 2 1;

**G 0 0 Z** — ; · · · Z axis up

M 2 1;

#### **3 Example for Lead Cutting**

Program of NC Machine

0 0003; M21:

**G 0 1 Z** — ;····Z axis down

M 2 1; M 2 1;

G 0 1 X 4 0 . F 1 0 0 ; \*1 ←---G 0 0 Z — ; ··· Z axis up

M<sub>2</sub>1;

#### - Calculations for Feed Rate in Lead Cutting

- 1. Make a development elevation like Fig.2 to calculate the vector.
- 2. Give feed in lead cutting (cutting feed from 1 to 2).....e.g. 200 mm/min (depend on work piece materials).
- 3. Cutting speed of X axis: Fx= 200 mm/min x 40 mm  $\div$  80mm =100 mm/min F100 \*1
- 4. Cutting speed of  $\theta$  axis:  $f = 200 \text{ mm/min x } 69.2 \text{ mm} \div 80 \text{mm} = 173 \text{ mm/min}$

173 mm/min x 1r/min ÷ 314 mm/min =0.55r/min F55 \*2

#### **4 Example of continuous rotation** as turning operation

Program of NC Machine

0 0004;

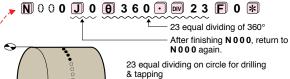
M21 ; Start continuous rotation

X & Z Contouring

M 2 1; Stop continuous rotation

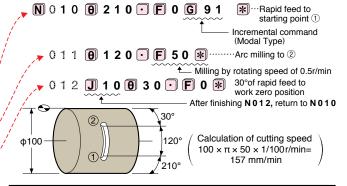
M 21; Machine zero position return with dog

### ● Program of AR21▶ N ○ ○ 0 J 0 ⊕ 3



When NC Machine executes the sub program 23 times, drilling & tapping of 23 holes is completed with 23 equal divisions calculated to 1/23rd of 360° to third decimal places automatically, e.g. 15.652°.

#### Program of AR21

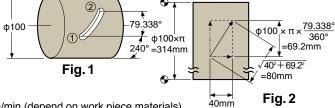


#### Program of AR21

▶ 0 2 1 **G** 1 0 **★** ······· Brake unclamped

0 2 2 1 7 9 3 3 8 F 5 5 G 2 1 \*\*... Cutting feed to 2

▼ 0 2 3 **J** 2 0 **⊕** 0 **. G** 9 0 1 1 **\*\*** ··· Rapid feed to work zero position **G 90** (Absolute) & G11 (Brake clamped)



#### Program of AR21

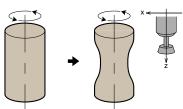
N 030 G 22 \*

·····Continuous rotation

N 031 J 30 G 28

\* ······Programmable machine zero position return with dog

N 997 0 ■ 10 • F 300 \*



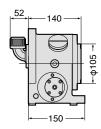
The direction and feed rate of continuous rotation are specified on N997. When higher rotation speed than standard is required, please contact with us.

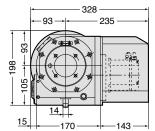
### **CNC ROTARY TABLE with AR21 CONTROLLER**



### CNC105AR21-04

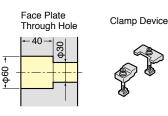






CNC180AR21-04 (400W) is standard. CNC180AR21-08 (750W) and CNC180AR21-06 (High Torque) are available.

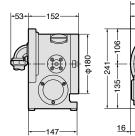
#### Powerful Clamping Torque: 205Nm



Air purge function is provided.

CNC180AR21-04





326 -220 106 \_\_\_14 181

Powerful Clamping Torque: 303Nm

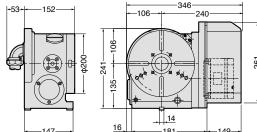




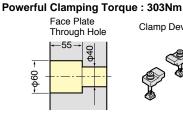
Air purge function is provided.

CNC202AR21-08





CNC202AR21-08 (750W) is standard. CNC202AR21-06 (High Torque) is available.







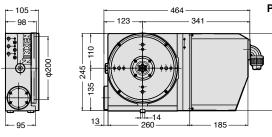
Air purge function is provided.

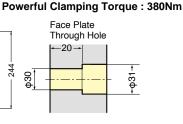
#### CNC205AR21-05



Rotary joint shown in photo is optional.

NC202AR21-05 (450W) is standard. ★Built-in type rotary joint 6+1 can be mounted.



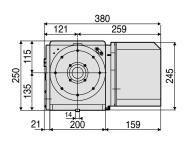


Air purge function is provided.

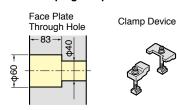
### NCT200AR21-08





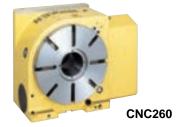


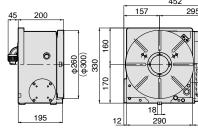
Powerful Clamping Torque: 900Nm

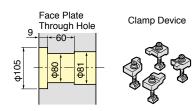


Air purge function is provided.

#### CNC260AR21-08, 302AR21-08 CNC260, 302AR21-08 (750W) is standard. CNC260, 302AR21-06 (High Torque) is available.







### **CNC ROTARY TABLE with AR21 CONTROLLER**

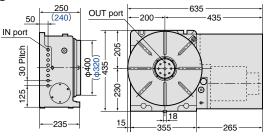


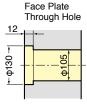
### CNC321, 401AR21-18

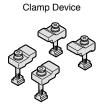


Rotary joint shown in photo is optional.

★Built-in type rotary joint can be mounted, refer to P.89



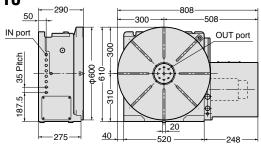


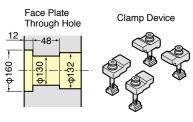


Please contact us for the dimension of CNC321AR21-18.

#### ★Built-in type rotary joint can be mounted, refer to P.89 CNC501, 601, 802AR21-18





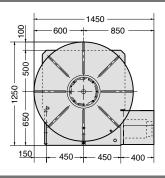


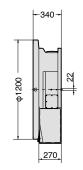
★ Please contact us for the dimension of CNC501, 802AR21-18.

### CNC1000, 1200AR21



Center socket shown in photo is optional.

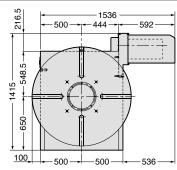


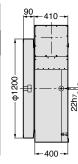


- ★ Ultra precision of ±3sec. is available as an option. There is no through hole on the rotary table due to the rotary encoder for ultra precision option.
- ★ Please contact us for the dimension of CNC1000AR21.
- ★ Code No. will be varied according to the servo motor capacity. e.g CNC1000AR21-44 (4.4KW Motor)

#### CNC1201AR21

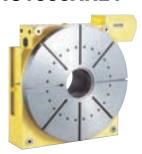


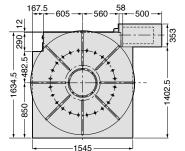


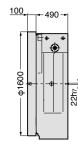


- ★ Ultra precision of ±3sec, is available as an option There is no through hole on the rotary table due to the rotary encoder for ultra precision option.
- Please contact us for the dimension of CNC1000AR21.
- ★ Code No. will be varied according to the servo motor capacity. e.g CNC1201AR21-110 (11KW Motor)

#### CNC1600AR21







- ★ Ultra precision of ±3sec. is available as an option. There is no through hole on the rotary table due to the rotary encoder for ultra precision option.
- ★ Please contact us for the dimension of CNC2000AR21.
- ★ Code No. will be varied according to the servo motor capacity. e.g CNC1600AR21-44 (5KW Motor)

#### The specification of the large rotary table will be varied according to your application.

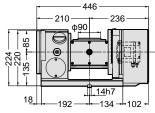
- 1. With/without T slot, Width of T slot
- 2. Spindle hole dimension···Center socket for centering is normally installed.
- 3. Layout of the rotary table...Vertical use, horizontal use, vertical and horizontal use
- 4. Total reduction ratio...Suitable capacity of the servo motor can be selected.

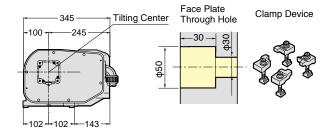
### **Tilting Rotary Table with AR21 Controller**



#### 5AX-100WAR21



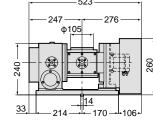




Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-100WAR21-0404

#### 5AX-130WAR21





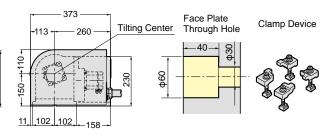
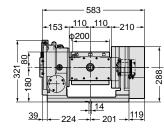


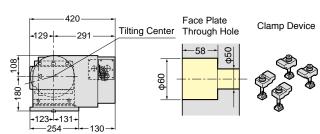
Photo with φ130mm plate. Rotary axis cable stays.

Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-130WAR21-0404

#### 5AX-201WAR21



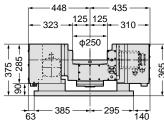


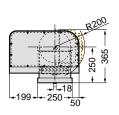


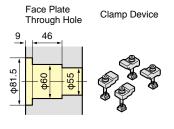
Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-201WAR21-0408

### 5AX-250WAR21





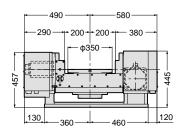


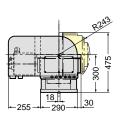


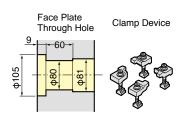
Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-250WAR21-1313

### 5AX-350WAR21







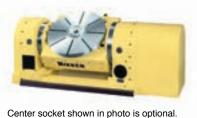


Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-350WAR21-1318

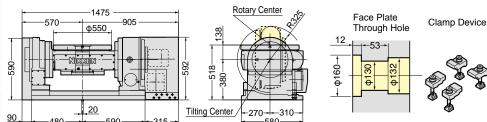
### **Tilting Rotary Table with AR21 Controller**



#### 5AX-550WAR21



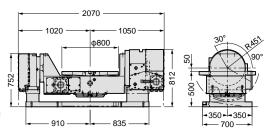
The specification of the large rotary table will be varied according to your application.



Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-550WAR21-1818

#### 5AX-800WAR21

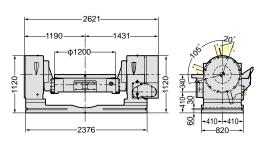




Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-800WAR21-1875

#### 5AX-1200BWAR21





Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-1200BWAR21-4444

- 1. Moving angle of the tilting axis
- 2. Relation between the tilting axis center and the rotary axis



**5AX-1200A**:The tilting axis center is located in the same position as the center of the rotary axis body.

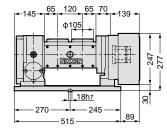


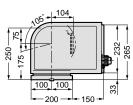
**5AX-1200B**:The tilting axis center is located in the same position as the top surface of the rotary axis.

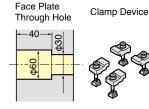
- 3. Tilting axis base···It can be supplied to us.
- 4. With/ witout T slot, Width of T slot
- 5. Spindle hole dimension
  - ···Center socket for centering is normally attached.

### 5AX-2MT-105WAR21









Motor capacity of rotary axis and tilting axis are added at the end of Code No. e.g 5AX-2MT-105WAR21-0404 If you need a knock hole for positioning or a key way on the table surface, please contact us.

AR21 controller can drive the all models of NIKKEN rotary tables. Please contact us for the external dimension.



Back side motor mounted CNC rotary table





Top side motor mounted CNC rotary table

Indexing of MIN. incremental of 1° is done by AR21 controller.



Multi-spindle CNC rotary table





ST manual tilting rotary table

AR21 controller can perform indexing of MIN. 1° with hirth coupling and can also perform indexing of MIN. incremental by 0.001° and profile milling.

NSVZ index NSVX rotary index table

## M-signal CNC ROTARY TABLE with EZ CONTROLLER

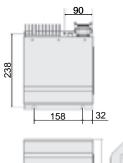
- Compact and lightweight state-of-the-art numerical control unit
- Minimum setting unit of 0.001 or 1 second
- Digital servo and absolute encoder
- Large-capacity, high-torque servo motor (1.0 kw, 3.92 N·m continuous stall torque)
- Ability to back up programs and parameters to USB flash drive

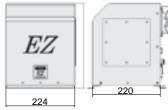




Method of connection to machining center

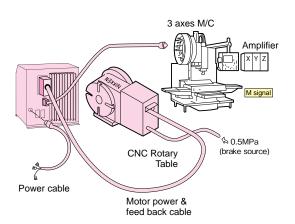
For a CNC rotary table, the interface is the same as that used previously with AR21 controllers. P.75
For 5AX rotary tables using EZ controllers for the rotation and tilt-axes, a power supply and M signal cable is required for each EZ controller.



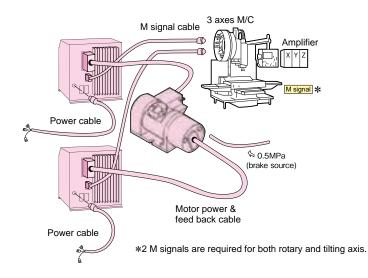




EZ controller connection for CNC rotary table (1-axis)



EZ controller (2 units) connection for 5AX tilting rotary table (2-axis)





### **EZ CONTROLLER SPECIFICATION**



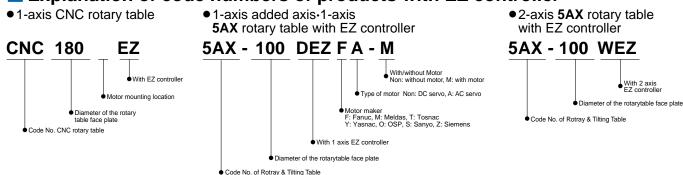
#### Main Specification of Controller

EZ controller is interchangeable for operation and program with existing ≪21 controller in case of 1 axis control.

Item	Specification	Remarks
MIN. Increment	0.001° or 1"	Free Selection
MAX. Programmable Angle	±999.999° & ±999°59'59"	Free Selection
Program Capacity	1000 Blocks	N000~N999
Input System	MDI Key Board, Pendant type	Maintained by a ten-year battery
Programming System	Combined use of Incremental/Absolute	Free Selection of G91 / G90
Zero Return	Machine Zero Position/Work Zero Position	
Manual Feed	Rapid Feed/Fine Feed/Step Feed/Continuous Feed	
Uni-directional Positioning	Uni-directional Positioning can be done to eliminate the mechanical backlash.	G14
Emergency Stop	Whole system stops	can be commanded from outside.
Jump Function	Jump to sub program etc.	
Dry Run	Table always rotates in rapid feed for checking.	
Preparatory Function	Dual, brake enable / disable, unidirectional positioning, machining origin return	G04~G92
G1 Code, G2 Code	2 kind of G codes can be entered in one block.	
Block Data display	At programming, previous block data or next block data are displayed. Nine lines are displayed per screen.	
Software Limit Function	± stroke limit values can be set by parameter.	
Over Travel Detection Function	Over travel detection zone can be set at outside of software limit by using control	Standard for 5AX- type tilting
Over Travel Detection Function	circuit, and the CNC rotary table can be protected not to exceed safety zone.	axis
Alarm No. Automatic Indication Function	When alarm is detected, controller automatically goes to diagnosis mode and Alarm No. is displayed.	
Self Diagnosis Function	Inside situations of controller can be seen.	
Modal G Code Flicker Function	All G codes used in the program are displayed.	
Feed Rate Override	1 to 255% (increment determined by parameter setting), 999% (fast feed)	
Input Signals	1 kind of Auxiliary Function.(Automatic operation can be done by only one M signal.)	±5%
Output Signal	1 Block Finish signal, Work Zero Position Signal, Alarm Out Signal	With or without contact signal *1
Servo Motor	AC servo motor with serial encoder R2AAB8100HXPGA (1.0kW)	Ask Time Chart
Input Power	Single phase AC200~230V、50Hz / 60Hz	840VA (Average load factor)

<sup>\*1:</sup> M signal of M/C is valid only the block without DEN (Distribution End).

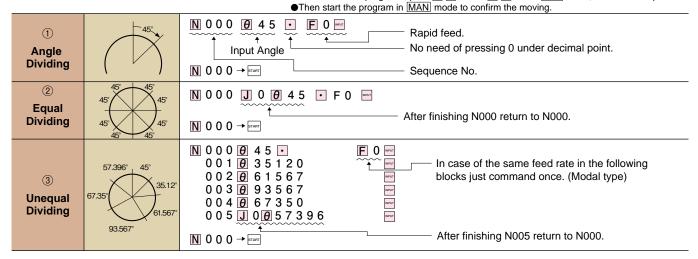
#### Explanation of code numbers of products with EZ controller



#### Operation & Confirmation of Programs

●Before programing, be sure that mode is EDT.

Before start the programs, push ↓ ↓ ...... or ↑ ↑ ...... in EDT mode, and confirm input date.



# **Explanation of PENDANT 1**





Turned ON when input power is supplied. Turned ON when EZ is in alarm condition.

(6) Feed Rate Override Button

(15) Increment/ Decrement of Block No.

(14) Diagnosis Button

17 Reset Key

DGN

ţ

+ OVR



#### 1 Power ON/OFF switch

## ② Emergency Stop Button



ΗΙ

#### **34 Manual Jog Button**

▶ + Clockwise, - ◀ Counter clockwise.
While this button is being depressed, the table continually rotates slowly. When this button is depressed once, the table steps by 0.001°(1").

#### 5 High Speed Button

When this button is depressed together with 3 or 4, the table rotates in rapid feed. When jog 1 while depressing 5, table moves as following;

Gear Ratio	Table Movement
1:720	0.5°
1:360	1.0°
1:180	2.0°
1:120	3.0°

Gear Ratio	Table Movement
1:90	4.0°
1:60	6.0°
1:45	8.0°

#### AUT MAN

#### 6 Auto/Manual Select Switch

When this button is turn to Manual, all buttons are workable.

When this button is turn to Auto, all other buttons except 1, 2, 6, 8, 9, 4, 6, 7 are ineffective.



#### 7 Edit/Current Position Select Switch

On  $\theta$  of (B), programming or present position is displayed alternatively.



#### **® Start Button**

The table rotates as programmed.



#### 9 Stop Button

The table slows down and stops. (Feed Hold Function). When ® is depressed again, the table rotates the remaining angle of the program.



## Continuous Feed Button

When this button is depressed, the table rotates continually. And, when (9) is depressed, the table stops. The desired feed and direction are to be input in N997 Block. (Refer P.53 (8))



#### 11 Original Point Set Button

When this button is depressed at any angle, the position display shows 000.000°, and it is used as the work zero position. When the cumulative angle becomes 360°, work zero position signal is sent, which can be used as interlock.



#### 12 Machine Zero Return Button

When this button is depressed, the table returns to the machine zero position (0°of the graduation of the table) clockwise in rapid feed, then low speed for final positioning.



#### **13 Work Zero Return Button**

When this button is depressed, the table returns to the position set by 1 clockwise in rapid feed.



#### **14** Diagnosis Button



## (5) Increment/Decrement of Block No.

Previous block data and next block data are displayed.



OVR

#### (6) Feed Rate Override Button

POS mode: Increasing feed rate 5 to 200% every  $5\% \rightarrow \text{Rapid feed (999)}.$ 

PRM mode: Displays the following parameters sequentially.

OVR POS mode: Decreasing feed rate 200 to 5% every 5%.



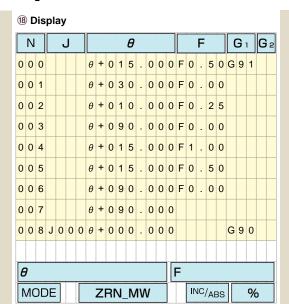
PRM mode: Displays the proceeding parameters sequentially.

## Reset Key

This is for calling N000 and also for resetting alarm display etc.

# **Explanation of PENDANT 2**





The program is displayed nine lines at a time.

- N: Sequence No. N000~N999
- J: Jump target sequence number and return display J000~J999, RET
- θ: Rotation angle of table (Decimal, Sexagecimal) 0~±999.999° (Decimal)

0~±999.59'59" (Sexagecimal)

F: Feed rate

Cutting feed: 0.01~9.99r/min

Rapid feed: 000

G₁, G2: Preparatory function G01~G92 Two kind of G codes (G1, G2) can be input in one block.

- θ: Rotation angle of table (Decimal, Sexagecimal)
  - 0~±999.999° (Decimal)
  - 0~±999.59'59" (Sexagecimal)
- F: Feed rate

Cutting feed: 0.01~9.99r/min

Rapid feed: 000 MODE: EDT (Edit mode)

MAN (Manual mode) AUT (Auto, mode) **DGN** (Diagnostic mode)

#### ZRN-MW

M (Stop at M ZERO) W (Stop at W ZERO)

INC/ABS: INC (Incremental)

ABS (Absolute)

%: Feed rate override

(5% to 200%, or 999 for rapid feed rate)

#### **Key Encoder**

For calling a certain sequence, input the number after this key so that the program of the block is display, also you can start from the program.

This key is to be used when you want to call sub program N' or jump to N' after N block is completed.

When sub program is finished, enter R at ® N' display. And, it returns to the block next to the one where J' was commanded in the main program.

 $\theta$  : You can input 0° to ±999.999° in 0.001° increment, or 0° to  $\pm 999°59'59"$  in 1"

The selection of decimal or sexagesimal system is set up by parameter.

In case of Dwell Instruction (G04), the waiting time is inputted.  $(0.001 \text{ to } \pm 999.999 \text{ sec.})$ .

Not used



F: Cutting feed F001(0.01 r/min) to F999(9.99

Rapid feed F000 or F0.

Without G: Positioning G NO G04: Dwell

\* G10: Brake unclamped \* G11 : Brake clamped

G14: Uni-directional positioning

G21 : Simultaneous start

G23: Machine zero point return G24: Work zero point return

G28: Programmable machine

zero position return

\* G90 : Absolute command

\* G91: Incremental command

G92: Coordinate system setting

#### How to enter G code:

0 cannot be suppressed for both G1 and G2 codes. For example, when G1=14 and G2=91, enter them as follows;

1491\*

and indication will become as:

G <sub>1</sub>	G <sub>2</sub>
14	91

DATA

When you want to enter 9°, just depress keys as  $\theta \rightarrow 9 \rightarrow \square$ , and 9.000° or 9°00′00″ is displayed.



This is for command of Counter clockwise rotation.

This is depressed as programming of each block INPUT being completed.

(Hereafter shown as 脉).

C

For deletion or alternation of  $\theta$ , DIV, or F individually, just depress  $\theta$ , DIV, or F, then depress. Also when you depress \* with pressing C , complete one block is deleted.

#### **Deleting successive blocks**

For example, in order to delete blocks from N000 to N999, push keys N 0 - 999 at Edit mode, and jog ★ while depressing c key.

Pendant operation is somewhat different on the tilt-axis specification EZ. Refer to the EZ instruction manual for details.

## Caution for EZ Controller

- This is an absolute encoder, with alarm #2162 displayed when the cable is initially connected to the rotary table and the power is turned on because the coordinate system is not established. Proceed with the following steps:
- DGN Return to pervious mode.

PRM#110=1

Writting parameter value enable.

1

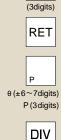
PRM#72=1

- · Turn the POWER OFF and ON
- For tilting axis

For rotary axis MRI Execute machine zero return.

First set the temporary machine zero position and ZHN Please refer instruction manual for more detail.

• When the alarms regarding the absolute encoder such as ALARM#1101 or #1102 are appeared, please set PRM#71=1 and turn the POWER OFF and ON to establish the coodinate system again.



Ν

(3digits)

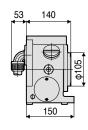
J

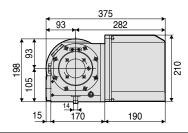
## **CNC ROTARY TABLE with EZ CONTROLLER**

## **NIKKEN**

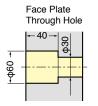
## CNC105EZ







#### Powerful Clamping Torque: 205Nm



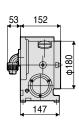


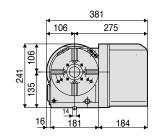
Clamp Device

Air purge function is provided.

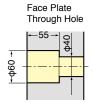
CNC180EZ







Powerful Clamping Torque: 303Nm



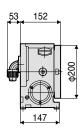


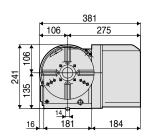
Clamp Device

Air purge function is provided.

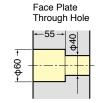
CNC202EZ







Powerful Clamping Torque : 303Nm



Clamp Device



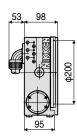
Air purge function is provided.

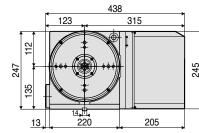
CNC205EZ



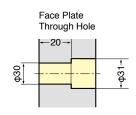
Rotary joint shown in photo is optional.

★Built-in type rotary joint 6+1 can be mounted.





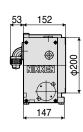
Powerful Clamping Torque: 380Nm

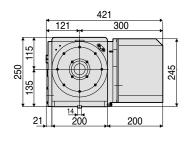


Air purge function is provided.

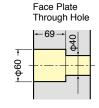
## NCT200EZ







Powerful Clamping Torque: 900Nm

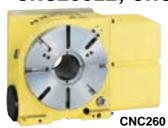


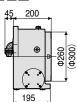


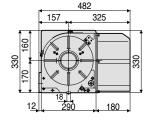


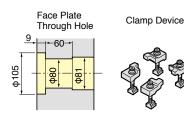
Air purge function is provided.

## CNC260EZ, CNC302EZ









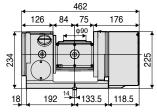
High seed rotation Z series is available for all models of CNC rotary table. e.g. CNCZ260EZ

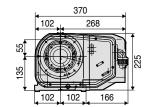
# **TILTING ROTARY TABLE with EZ CONTROLLER**

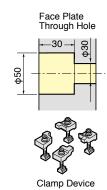


## **5AX-100WEZ**



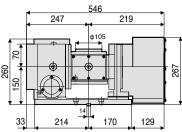


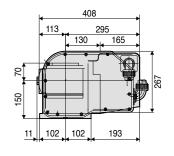


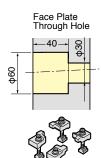


## **5AX-130WEZ**







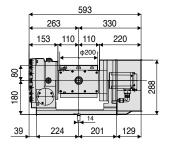


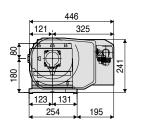
Clamp Device

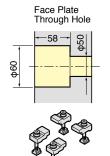
Photo with φ130mm plate.

## 5AX-201WEZ





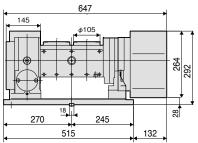


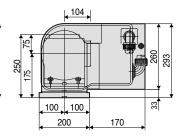


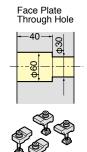
Clamp Device

## **5AX-2MT-105WEZ**









Clamp Device

If you need a knock hole for positioning or a key way on the table surface, please contact us.

## **Technical Information of NIKKEN CONTROLLER 1**

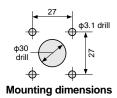


#### AR21 and EZ controller connection

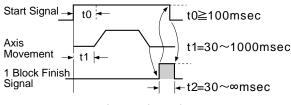
Normally the controller will be operated only by connecting M Signal (Start Signal) and 1 Block Fin. Signal. Emergency Stop Input must be set to B contact only for 5AX-Tables. For other Tables, you can choose A/B contact for Emergency Stop Input.

When to be connected to machine, receptacle MS3102A18-1P is provided. Arrange the electric circuits of your machine side.

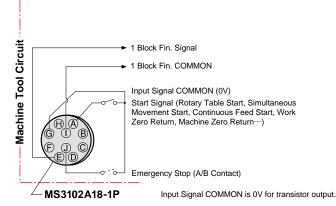




## Input/Output Time Chart



t1 and t2 can be set by parameter.

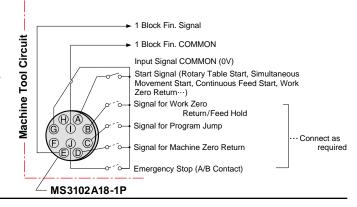


#### Connection for Automatic Operation(AR21only)

Once program is loaded to AR21, all operations such as Power ON, Machine Zero Return, Program Section, Start etc. can be done by machine side. 3 sets of M signals are required for CNC rotary table and 6 sets of M signal are required for 5AX- tilting rotary table. e.g.

M21: Start Signal

M22 : Program Jump (Selection) Signal M23 : Machine Zero Return and Reset



## RS232C Automatic Loading Interface. · · · Pendant is to be used for manual operation and maintenance only. (AR21only)(OPTION)

Program is loaded from Custom Macro of M/C, and start the program by the ordinary M signal. Total management of programs can be done on only M/C side. The necessary functions of M/C side are;

Custom Macro

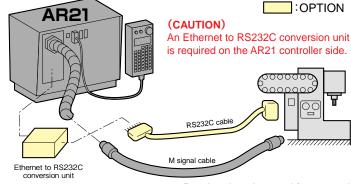
Custom Macro External Output Function

2 sets of M signals

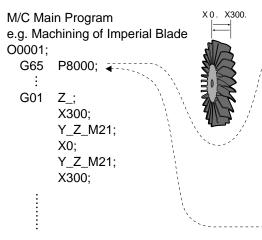
e.g.

M21: Start signal

M24 : Start signal of RS232C Automatic Loading Function (Start signal without 1 Block Fin. signal confirmation and keep this signal ON at least 100msec.)



Pendant is to be used for manual Macro Program operation and maintenance only. (Down Loading to AR21) M24; Activate AR21 automatic loading function. POPEN; #100=165; Send %, CR, LF. BPRNT[#100[0]]; DPRNT[N10 G90 A22.149]; Send block data. N No.must #100=165; Send %, be specified BPRNT[#100[0]]; CR.LF. on each block data G04 P3000; Dwell 3sec. PCLOS; M66;



## **Technical Information of NIKKEN CONTROLLER 2 NIKKEN**



DB-25P-N

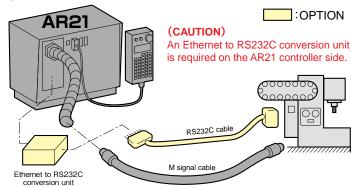
#### RS232C Direct Angle Command Interface (AR21 only)(OPTION) JAPAN PAT.

This interface can start the block after sending one block data from custom macro of M/C. Equal dividing function (e.g. divided by 7) also can be sent. Therefore, program will be simple and more accurate and the total management of the programs can be done

Required functions at the M/C

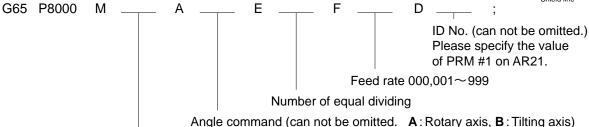
- Custom macro
- Custom macro external output function
- 1 M signal (Start signal) M21

5AX-table with 2 off AR21 controllers can be connected to use RS232C direct angle command interface. In this case, special RS232c cable is required and 2 off M signals are required.



Pendant is to be used for manual operation and maintenance only.

#### Special cable AR21 (Male) = X21#1 RS232C interface 1 1 1 X21#2 The cable is available as an option. RD (2) 2 Baud rate: 9600 bps SD ③ 3 RD Code: ISO 4 4 RS Data bit length: 7 bits Parity bit: Even parity (5) (5) CS-connect to RS Stop bit length: 2 bits 6 DR-connect to ER Parameter setting of M/C must be "LF CR" or "CR LF" SG (5) (7) SG is sent at EOB sending. 8 CD-connect to ER 420 ER Call off macro program for direct angle command



90/91 = Absolute/Incremental

M21(start) will be executed as required times after execution of macro program for direct angle command.

## Macro program for direct angle command (Example for only rotary axis control)

DPRNT [ID#7[10] A#1[43]E#8[40]]; O 8000: N<sub>6</sub> POPEN: GOTO 10: #100=165; N7 IF [#9 EQ #0] GOTO 8: BPRNT [#100[0]]; DPRNT [ID#7[10] A#1[43]F#9[30]]; IF [#13 EQ #0] GOTO 5; **GOTO 10:** IF [# 8 EQ #0] GOTO 3: N8 DPRNT [ID#7[10] A#1[43]]; BPRNT [#100[0]]; IF [# 9 EQ #0] GOTO 2; N10 N1 DPRNT [ID#7[10] G#13[20]A#1[43]E#8[40]F#9[30]]; G04 P200: P CLOS: **GOTO 10:** N2 DPRNT [ID#7[10] G#13[20]A#1[43]E#8[40]]; M 99: **GOTO 10:** N3 IF [#9 EQ #0] GOTO 4; DPRNT [ID#7[10] G#13[20]A#1[43]F#9[30]]; Work zero position signal and alarm **GOTO 10**;



out signal can be output as an option. Be careful that these signals are non-contact type output and output common line is 0V. These signals must be recieved on the relay. Please contact with us for more details.

## Termination of the maintenance work for NIKKEN controllers

The maintenance work of the NIKKEN controllers is continued as long as the electric parts could be supplied. However, about the following controllers, the maintenance has to be terminated, because the supply of the electric parts became impossible. Please examine reshuffling to the CNC rotary table with &21

Terminated at April 2005 for CNC rotary table ND5000, 8000DC, 8800DC, 9000DC Terminated at April 2005 for NSV index table NSV controller (M signal I / F, B signal I/F) Terminated at April 2013 CNC rotary table 8800DX, 8800AX

DPRNT [ID#7[10] A#1[43]E#8[40]F#9[30]];

DPRNT [ID#7[10] G#13[20]A#1[43]];

IF [#8 EQ #0] GOTO 7;

IF [#9 EQ #0] GOTO 6;

N4

N5

**GOTO 10**;

GOTO 10;



# **Comparison between AR21 and EZ controller NIKKEN**



## G Codes

	Groups	Function	AR21	EZ
W/O G codes	*	Positioning	0	0
G04	*	Dwell command	0	0
G06	*	Constant acceleration command	0	×
G07	*	Lead-cut command	0	×
G08	А	Buffer command	0	×
G09	(A)	Buffer command cancel	0	×
G10	В	Brake disused command	0	0
G11	(B)	Brake used command	0	0
G12	С	Running	0	0
G13	(C)	Running cancel	0	0
G14	*	One way positioning command	0	0
G15	D	For Droop check	0	×
G16	(D)	Droop check cancel	0	×
G21	*	Interlock start	0	0
G22	*	Interlock start command	0	×
G23	*	Machine Zero return	0	0
G24	*	Program Zero return	0	0
G27	*	Repeat command	0	×
G28	*	Programmable dog machine zero return	0	0
G60~G74	-	M function	Optional	×
G90	E	Absolute command	0	0
G91	(E)	Incremental command	0	0
G92	*	Configuration of coordinate system	0	0

## Program

	Remarks	Function	AR21	EZ
Frequency change	PRM#15	Base 10 / Base 60	0	0
J	-	Jump command	0	0
RET	-	Return command	0	0
D	-	Dividing command	0	×
Rotating axis specification	PRM#30=0	1	0	0
Tilting axis specification	PRM#30=1	Soft over-travel, Hard over-travel	0	0
NSVZ	PRM#30=2	Indexing specification	0	×
NSVX	PRM#30=3	Rotary Index specification	0	×



# Comparison between AR21 and EZ controller **NIKKEN**



## Options

	Remarks	Function	AR21	EZ
Magnescale(RU77)	-	- Fully closed Loop		×
PGSL1∼6	-	Program-select function	Optional	×
PRM#213, 216	-	Pitch-error compensation	Optional	×
Manual pulse	-	Manual pulse handle	Optional	×

## Other functions

	Remarks	Function	AR21	EZ
PRM#14	-	Grid-mask amount	0	×
PRM#41	-	Moving angle direct command	0	×

## Input signal

	Remarks	Function	AR21	EZ
START	-	Start	0	0
EM	-	Emergency stop	0	0
WZRN/FHOLD	PRM#54=0	Interlock start	0	×
	PRM#54=1	Component Zero return	0	×
	PRM#54=2	Field hold	0	×
JUMP	PRM#51=0	Interlock start	0	×
	PRM#51=1	Voluntary block skip	0	×
MZRN	PRM#50=1	Machine origin return	0	×
	PRM#50=2	External reset signal	0	×
SV OFF	_	Servo off	0	×

## Output signal

	Remarks	Function	AR21	EZ
WPOS	PRM#55=1	Component zero position signal (regular OPEN)	0	×
	PRM#55=2	Component zero position signal (regular CLOSE)	0	×
BOUT1	PRM#90~93	NSV solenoid valve output [both solenoid]	0	×
ALM	-	Alarm out signal	0	×
EMG OUT1 $\sim$ 2	_	Emergency stop signal	0	×

## SUPPORT TABLE

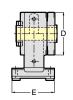
			With C	lamping	0 0 17.11
Table Model	Center Height	W/O Clamping	Air (0.5MPa)	<b>Hyd.</b> (3.5MPa)	Slim Spport Table With Clamping
CNC105	105	CST100-105	TAT-105N		
CNC180, 202,205	135	CST100-135	TAT-170N		TAS-100N
NCT200	135	CST100-135	TAT-170N		TAS-100N
CNC180B, 202B	180		TAT-170N*1		TAS-100N*1
CNC260, 302			<b>TAT-250N</b> (Sh	ared use Air/Hyd)	
CNC260P, 302P	170		<b>TAT-200N</b> (Sh		
CNC321	230			TAT-321N	
CNC401	230			TAT-401N	
CNC321T	240			TAT-321N*4	TAT-403N
CNC401T	240			TAT-401N*4,403N	TAT-403N
CNC501, 601	310			TAT-501N	
NSVZ180	135		TAT-170N		
NCV/7200	470		TAT-250N(Sh	ared use Air/Hyd)	
NSVZ300	170		<b>TAT-200N</b> (Sh	ared use Air/Hyd)*2	
NSVX400	240			TAT-401N*4	TAT-403N
DD250	170		TAT-170N*3		

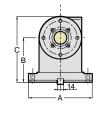
- \*1 : A separate sub-base is required to align the center height.
- \*2 : The center height is possible to increase 20mm to use sub-base.
- \*3 : The support tables that can be used are subject to limitations based on the number of rotations.
- \*4 : When a sub-base is used to adjust the center height, a +10 mm variation in the specification can be accommodated.

## Compact Support Table

**CST100-105**, **135** (W/O Clamping System)







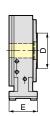


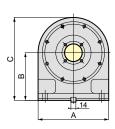
Code No.	Α	В	С	D	E	Weight(kg)
CST100-105	150	105	155	100	100	7
CST100-135	150	135	185	100	100	8

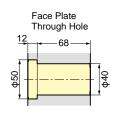
## Compact & Slim Support Table

**TAS-100N** 







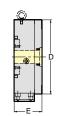


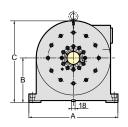
Code No.	Α	В	С	D	Е	Clamping System	Clamping Torque(N·m)	Weight(kg)
TAS-100N	200	135	235	100	80	Pneumatic	217	17

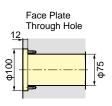
## Slim Support Table

**TAT-403N** 









The table without T slots "N" is standard.

T slots are available (optional)

Code No.	Α	В	С	D	Е	Clamping System	Clamping Torque(N·m)	Weight(kg)
TAT-403N	480	240	440	400	150	Hydraulic	1500	155

- ★ Pneumatic ports: 2 x Rc1/8 Solenoid, Clamp-Unclamp switches are not included.
- ★ Hydraulic connections are RC3/8 X 2 and pneumatic connections are RC1/8 X 2. Confirmation switches for clamp/unclamp and solenoid valve are not included.
- ★ Hydraulic pressure is 3.5MPa. Air pressure is 0.5MPa.
- ★ Rotary joint is available for all models. **P.89**
- ★ Please add "— center height" at the end of Code No. for the support table with different center height (B) . e.g. TAT321-240 (For CNC321T)

# SUPPORT TABLE

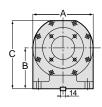


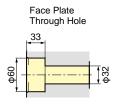
## Support Table

**TAT-105N** 







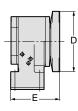


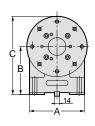
Without T-slots "N" (standard) / With T-slots (optional) in case of TAT-105

Code No.	Α	В	С	D	E	Clamping System	Clamping Torque(N·m)	Weight(kg)
TAT-105N	155	105	175	105	113	Pneumatic	205	16

## **TAT-170N**









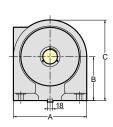
Without T-slots "N" (standard) / With T-slots (optional) in case of TAT-170

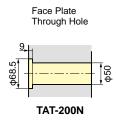
Code No.	Α	В	С	D	E	Clamping System	Clamping Torque(N·m)	Weight(kg)
TAT-170N	155	135	220	170	138	Pneumatic	205	25

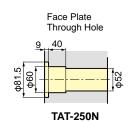
## **TAT-200N, 250N**











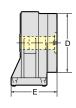
The table without T slots "N" is standard. T slots are available (optional)

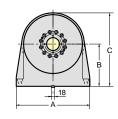
Code No.	Α	В	С	D	Е	Clamping System	Clamping Torque (N·m)	Weight(kg)
TAT-200N	250	150	275	200	145	Pneumatic / Hydraulic	112/784	43
TAT-250N	250	170	295	250	145	Pneumatic / Hydraulic	112/784	50

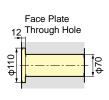
★TAT-200N is used in combination with CNC321T or CNC401T to install lifting-block.

## TAT-321N, 401N, 501N









The table without T slots "N" is standard. T slots are available (optional)

Code No.	Α	В	С	D	E	Clamping System	Clamping Torque(N·m)	Weight(kg)
TAT-321N	400	230	400	320	250	Hydraulic	1470	120
TAT-401N	400	230	430	400	250	Hydraulic	1470	140
TAT-501N	480	310	560	500	250	Hydraulic	1470	220

# TAILSTOCK (MANUAL, PNEMATIC, HYDRAULIC) NIKKEN

## Tailstock

	ilstock	Manual	PNEUMATIC / HYDRAULIC	HYDRAULIC
	ilstock illust ter Height	Stroke: 15mm	Stroke: 60mm	Stroke: 100mm
CNC105	105	P-105S	PBA-105	
CNC180, 202	135	P-125S	PBA-135	
NCT200	135	P-125S	PBA-135	
CNC180B, 202B	180	P-170S	PBA-180	H-170S
NST250	155	P-150S		H-150S
CNC260, 302, 260P, 302P	170	P-170S	PBA-170	H-170S
CNC321, 401	230	P-230S		H-230S
CNC501, 601	310	P-310S		
NST300	208	P-210S		H-210S
NST500	288	P-280S		
5AX-100	135	P-125S	PBA-135	
5AX-130	150	P-150S	PBA-150	H-150S
5AX-201	180	P-170S	PBA-180	H-170S
5AX-230	240	P-230S		H-230S
5AX-250*	250			
5AX-350	300	P-310S		
CNC100-2, 3, 4W	105		PB-105-2,3,4W	
NSVZ180	135	P-125S	PBA-135	
NSVZ300	170	P-170S	PBA-170	H-170S
NSVX400	240	P-230S		H-230S

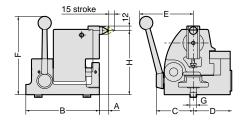
<sup>\*</sup>Please contact us about the Tailstock for **5AX-250**.

## Manual Tailstock





Changeable Center



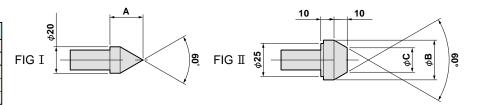
The center height can be adjusted. Please refer to Center Height H on the table.

Code No.	Center Height H	Α	В	С	D	Е	F	G	Weight (Kg)
P-105S	102~110	27	150	76	74	120	195	14	10
P-125S	130~140	27	150	76	74	120	210	14	11.5
P-150S	145~160	25	195	98	102	145	210	18	22
P-170S	160~180	25	195	98	102	145	210	18	22.5
P-210S	200~220	25	195	98	102	145	250	18	26.5
P-230S	220~240	25	195	98	102	145	250	18	27
P-280S	280~300	15	235	103	124	145	330	20	41
P-310S	300~320	15	235	103	124	145	330	20	41.5

★Left hand type is available for all models. ★For P-150S or larger size tailstocks, 5 pcs of changeable centers are included. ★Live center can be applied.

## Changeable Center

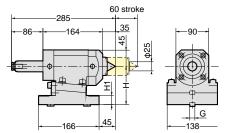
Code No.	FIG	Α	В	С
PC-2	I	25		
PC-3	I	50		
PC-4	II		30	18.45
PC-5	II		40	28.45
PC-6	II		50	38.45



# TAILSTOCK (MANUAL, PNEMATIC, HYDRAULIC) NIKKEN

## Pneumatic / Hydraulic both usable Small Size Tailstock





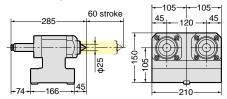
The center height can be adjusted within 0.35mm.

Code No.	Center Height H	ш	G	Thrus	st (N)	Weight (Kg)
Code No.	Center neight n	<b>H</b> <sub>1</sub>	G	Pneumatic. 0.5MPa	Hydraulic. 2MPa	weight (Kg)
PBA-105	105	25	14	1176	4733	15
PBA-135	135	55	14	1176	4733	20
PBA-150	150	70	18	1176	4733	22
PBA-170	170	90	18	1176	4733	24.5
PBA-175	175	95	18	1176	4733	25
PBA-180	180	100	18	1176	4733	25.5

<sup>★</sup>Rotary center is built-in. ★MT (Morse Taper) type quill is also available. Please contact with us.

## Pneumatic / Hydraulic both usable for Multi-Spindle Tailstock



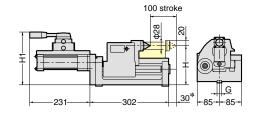


Code No.	Center Height H	H <sub>1</sub>	G Thrust (N)		st (N)	Weight (Kg)
00de 140.	Ochter Height H	111	G	Pneumatic. 0.5MPa	Hydraulic. 2MPa	Weight (itg)
PB-105-2W						28
PB-105-3W	105	25	18	1176	4733	42
PB-105-4W						55

- $\bigstar \text{For fitting metal and stepped guide piece, refer to } \ensuremath{\text{\textbf{P.85}}}$
- ★MT (Morse Taper) type quill is also available. Please contact us.
- ★The stroke 60mm can be changed. Please contact us.

## Hydraulic Tailstock





The center height can be adjusted. Please refer to Center Height H on the table.

Code No.	Center Height H	H₁	G	Thrust (N)	Weight (Kg)	
3545 1151	Conton Horgin H			Hydraulic. 3.5MPa	1101911 (119)	
H-150S	145~160	191	18	5370	28	
H-170S	160~180	211	18	5370	35	
H-210S	200~220	251	18	5370	41	
H-230S	220~240	271	18	5370	45	

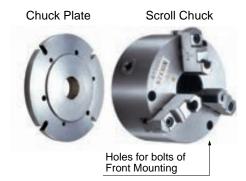
<sup>★</sup>Rotary center is built-in.

MAX. work piece diameter must be smaller than φ130mm, when the stroke of changing the work piece is more than 30mm marked \*.

<sup>★</sup>The different length of the stroke is available. Please contact us.

# **SCROLL CHUCK**





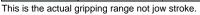
Scroll Chucks with chuck plate marked\* are NIKKEN Scroll Chuck of Front Mounting (Fig.1)

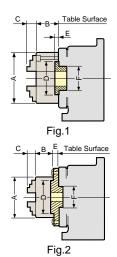
NIKKEN Scroll Chuck is used for X-4B, X-6E & X-9F.

The chuck plates for the scroll chucks without \* can be used for the scroll chuck based on JIS B6151 SC/TC standard.

## **Scroll Chuck & Chuck Plate**

Chuck	Rai	nge
Size	External	Internal
4"	2~ 89	36~ 78
5″	3~104	42~ 92
6″	3~135	52~119
7″	3~153	56~134
9″	4~190	64~169
10″	10~229	72~208
12″	10~258	82~238





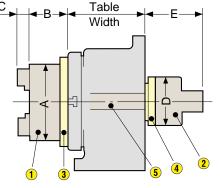
## Front End Dimensions with Scroll Chuck & Chuck Plate

Table Model	Chuck Size	Chuck Plate	Α	В	С	D	E	F	Fig. No
CNC105	R-4	X-4B	112	58	31.25	80	13	60	2
CNIC400	R-5	X-5C*	132	60	37.25	100	3.5	60	1
CNC180	R-6	X-6B*	167	66	44.25	130	4	60	1
	R-5	X-5C*	132	60	37.25	100	3.5	60	1
CNC202	R-6	X-6B*	167	66	44.25	130	4	60	1
	R-7	X-7A*	192	75	46.25	155	4	60	1
	R-6	X-6G*	167	66	44.25	130	4	80	1
CNC260, 260P	R-7	X-7L*	192	75	46.25	155	4	80	1
	R-9	X-9H	233	82	55.25	190	25	80	2
	R-6	X-6G*	167	66	44.25	130	4	80	1
CNC302, 302P	R-7	X-7L*	192	75	46.25	155	4	80	1
,	R-9	X-9J	233	82	55.25	190	18	80	2
	R-7	X-7N	192	75	46.25	155	16	105	2
0110004	R-9	X-9K	233	82	55.25	190	18	105	2
CNC321	R-10	X-10G	274	86	53.25	230	20	105	2
	R-12	X-12F-1	310	92	59.25	260	25	105	2
	R-7	X-7K	192	75	46.25	155	16	105	2
	R-9	X-9G	233	82	55.25	190	20	130	2
CNC401	R-10	X-10D	274	86	53.25	230	20	105	2
	R-12	X-12G	310	92	59.25	260	20	105	2
	R-9	X-9D	233	82	55.25	190	20	130	2
CNC501, 601	R-10	X-10	274	86	53.25	230	20	130	2
CI4C301, 001	R-12	X-12B	310	92	59.25	260	20	130	2
	R-12	X-5B	132	60	37.25	100	16	60	2
NST250, 300	R-6	X-6A	167	66	44.25	130	16	60	2
1401230, 300	R-7	X-7B	192	75	46.25	155	16	60	2
		X-9A	233	82	55.25	190	18	60	2
NST300	R-9 R-10	X-9A X-10B-1	233	86	53.25	230	25	60	2
	R-12	X-12A-1	310	92	59.25	260	25	60	2
	R-7	X-7G	192	75	46.25	155	18	75	2
NST500	R-9	X-9B	233	82	55.25	190	18	75	2
	R-10	X-10C	274	86	53.25	230	20	75	2
EAV 400	R-12	X-12	310	92	59.25	260	20	75	2
5AX-100	R-4	X-4D*1	112	58	31.25	80	3	40	1
5AX-130	R-4	X-4B	112	58	31.25	80	13	60	2
	R-4	X-4B	112	58	31.25	80	13	60	2
5AX-201	R-5	X-5C*	132	60	37.25	100	3.5	60	1
07.0X <b>20</b> 1	R-6	X-6B*	167	66	44.25	130	4	60	1
	R-7	X-7A*	192	75	46.25	155	4	60	1
5AX-230	R-6	X-6B*	167	66	44.25	130	4	60	1
5AX-250	R-7	X-7A*	192	75	46.25	155	4	60	1
CAN LOS	R-9	X-9F	233	82	55.25	190	20	60	2
	R-7	X-7M	192	75	46.25	155	16	80	2
5AX-350	R-9	X-9J	233	82	55.25	190	18	80	2
3AV-330	R-10	X-10E-1	274	86	53.25	230	25	80	2
	R-12	X-12D-1	310	92	59.25	260	25	80	2
NSVZ180	R-6	X-6E	167	66	44.25	130	15	60	2
	R-6	X-6A	167	66	44.25	130	16	60	2
NCV/7200	R-7	X-7B	192	75	46.25	155	16	60	2
NSVZ300	R-9	X-9A	233	82	55.25	190	18	60	2
	R-10	X-10B-1	274	86	53.25	230	25	60	2
	R-7	X-7D	192	75	46.25	155	16	80	2
110101110	R-9	X-9C	233	82	55.25	190	18	80	2
NSVX400	R-10	X-10A	274	86	53.25	230	20	80	2
	R-12	X-12C	310	92	59.25	260	20		2

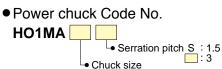
# **POWER CHUCK**



- 1 Power Chuck
- 2 Rotary Cylinder
- 3 Chuck Adapter
- 4 Cylinder Adapter
- **5** Connecting Rod



When power chuck or rotary cylinder is installed on 5AX-table, the 5AX-table must be High Column type.



Power Chuck & Rotary Cylinder

Table Model	Power Chuck Code No.	Pneu. Rotary Cylinder /Hyd. Rotary Cylinder	Α	В	C	D	E	Table Model	Power Chuck Code No.	Pneu. Rotary Cylinder / Hyd. Rotary Cylinder	Α	В	С	D	E					
CNC105	HO1MA-4	H05CH-100 HH4C-80	110	70	27	115 130	215 220	5AX-100H 5AX-130H	HO1MA-4		110	70	27	_	-					
	HO1MA-4	H05CH-100 HH4C-80	110	70	27	115 130	215 220		HO1MA-4	-	110	70	27	-	-					
CNC180	HO1MA-5	H05CH-150 HH4C-80	135	70	27	115 186	215 235	5AX-201H 5AX-230H	HO1MA-5	-	135	70	27	-	-					
	HO1MA-6(S)	H05CH-175 HH4C-100	165	94	43	135 210	240 240		HO1MA-6(S)	_						165	94	43	-	-
	HO1MA-4	H05CH-100 HH4C-80	110	70	27	115 130	215 220	EAV OFOLI	HO1MA-6(S)	-	165	94	43	-	-					
CNC202	HO1MA-5	H05CH-150 HH4C-80	135	70	27	115 186	215 235	5AX-250H H01MA-8(S)	Please ask for the detail.	210	110	43	-	-						
	HO1MA-6(S)	H05CH-175 HH4C-100	165	94	43	135 210	240 240		HO1MA-6(S)	HO1MA-6(S)	165	94	43	-	-					
	HO1MA-4	H05CH-100 HH4C-80	110	70	27	115 130	215 220	5AX-350H	HO1MA-8(S)	-	210	110	43	-	-					
NCT200	HO1MA-5	H05CH-150 HH4C-80	135	70	27	115 186	215 235		HO1MA-10(S)	254	120	43	-	-						
	HO1MA-6(S)	H05CH-175 HH4C-100	165	94	43	135 210	240 240	5AX-2MT-105H	HO1MA-4		110	70	27	118 98	120 115					
CNC260	HO1MA-6(S)	H05CH-175 HH4C-100	165	94	43	135 210	240 240	5AX-4MT-105	HO1MA-4		110	70	27	118 98	120 115					
CNC260P	HO1MA-8(S)	H05CH-250 HH4C-125	210	110	43	160 290	250 295		HO1MA-4	H05CH-100 HH4C-80	110	70	27	115 130	215 220					
	HO1MA-6(S)	H05CH-175 HH4C-100	165	94	43	135 210	240 240	NSVZ180	HO1MA-5	H05CH-150 HH4C-80	135	70	27	115 186	215 235					
CNC302 CNC302P	HO1MA-8(S)	H05CH-250 HH4C-125	210	110	43	160 290	250 295		HO1MA-6(S)	H05CH-175 HH4C-100	165	94	43	135 210	240 240					
	HO1MA-10(S)	H05CH-300 HH4C-125	254	120	43	160 340	250 310		HO1MA-6(S)	H05CH-175 HH4C-100	165	94	43	135 210	240 240					
	HO1MA-8(S)	H05CH-250 HH4C-125	210	110	43	160 290	250 295	NSVZ300	HO1MA-8(S)	H05CH-250 HH4C-125	210	110	43	160 290	250 295					
CNC321, 401	HO1MA-10(S)	H05CH-300 HH4C-125	254	120	43	160 340	250 310		HO1MA-10(S)	H05CH-300 HH4C-125	254	120	43	160 340	250 310					
	HO1MA-12(S)	H05CH-300 HH4C-140	304	140	53	180 340	260 310		HO1MA-8(S)	H05CH-250 HH4C-125	210	110	43	160 290	250 295					
	HO1MA-8(S)	H05CH-250 HH4C-125	210	110	43	160 290	250 295	NSVX400, H01MA-10(S) H01MA-12(S)	HO1MA-10(S)	H05CH-300 HH4C-125	254	120	43	160 340	250 310					
CNC501, 601	HO1MA-10(S)	H05CH-300 HH4C-125	254	120	43	160 340	250 310		H05CH-300 HH4C-140	304	140	53	180 340	260 310						
	HO1MA-12(S)	H05CH-300 HH4C-140	304	140	53	180 340	260 310	-	-	-	-	-	-	-	-					
CNC-100-2 (3, 4)W	HO1MA-4	H05CH-100 HH4C-80	110	70	27	115	215	-		-	-	-	-	-	-					

- ★HOWA power chucks and rotary cylinders (Higher: Pneu, Lower:Hydraulic) are listed. Other maker's one can be mounted, please specify the Code No.
- ★Above power chucks are not applicable to **NST** Table. Please contact with us for mounting.
- ★NIKKEN air/hydraulic rotary cylinder is also available.
- ★For the specifications of power chuck and rotary cylinder, please refer to material of HOWA MACHINERY, LTD.

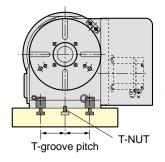
# **CLAMPING DEVICE and T-NUT**



## ■Clamping device list by CNC rotary table model

Code No.	Guide-piece width of CNC rotary table (mm)	Clamping device shape1 Code No.	Quantity	Clamping device shape2 Code No.	Set	Thickness of the sim plate(mm)
CNC105	14	CLA114	1	CLE13	1	5
CNC180	4.4	01.4044				
CNC202	14	CLA214	2	_	_	_
NCT200	14	CLA214	2	-	-	_
CNC180B	18	CLB18	2	CLC18	2	
CNC202B	10	CLDIO	2	CLC16	2	_
CNC202T	14	CLB14	2	CLC14	2	5
CNC260, 260P	18	CLB18	2	CLC18	2	5
CNC302, 302P	10	CLD16	2	CLOTO	2	3
CNC260B	18	CLB18	2	CLD18	2	5
CNC302B	10	OLDIO	CLD10 2			J 3
CNC321(B)	18	CLB18	2	CLC18	2	10
CNC401(B)	10	CLD10	CLD10 2			10
CNC501	20	CLA118	4	_	_	20
CNC601	20	OLATIO				20
CNC350	18	CLB18	2	2 <b>CLC18</b>		10
CNC450	18	CLA118	4	4 –		10
CNC100 (Mult spindle)	18	CLA118	4	-	-	5
CNC180 (Mult spindle)	18	CLA218	4	_	_	_
CNC202 (Mult spindle)	10	OLAZIO	7			_
NST250	16 W-16B Stepped	CLA218	3	-	-	3
NST300	18	CLA118	3	CLB118	3	
NST500	20	CLA118	4	-	-	_
5AX-100	14	CLA214	4	-	ı	_
5AX-130	14	CLB14	2	CLC14	2	_
5AX-150	14	CLB14	2	CLC14	2	_
5AX-201	14	CLA114	4	-	-	-
5AX-230	18	CLB18	2	CLC18	2	-
5AX-250	18	CLA218	4	-	-	15
5AX-550	20	CLA118	4	-	-	20
5AX-2MT-105	18	CLA118	4	-	-	-
NSVZ180	14	CLA114	2	-	-	-
NSVZ300	18	CLB18	2	CLC18	2	5
NSVZ400	18	CLA118	4	-	ı	10

 $<sup>\</sup>bigstar \bigstar \text{CLD18}$  is what makes additional processing on CLC18, width: from 55 to 50mm



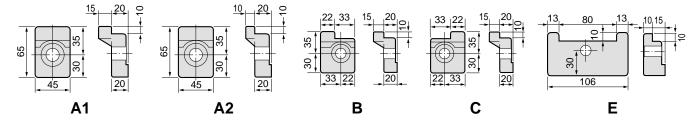
CLAMPING DEVICE is designed for T-slot pitches of 100mm or 125mm on the machine bed table. Please contact with us for the other pitches.

## **CLAMPING DEVICE and T-NUT**



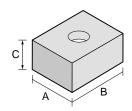
## ■ Code No. of Clamping Device

Size of clamping	Clamping Device Type							
device bolt	A1	A2	В	С	E			
M12	CLA114	CLA214	CLB14	CLC14	CLE13			
M16	CLA118	CLA218	CLB18	CLC18	CLE18			
M20	CLA120	CLA220	CLB20	CLC20	CLE20			



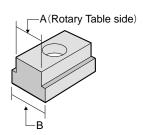
★ Clamping Devices (Fitting Metals) for the following CNC Table Models are Not Included. If necessary, consult NIKKEN sales parson. CNC400H, CNC503H, CNC802, CNC803, CNC1000, CNC1002, CNC1200, CNC1201, CNC1600, 5AX-800, 5AX-1200, 5AX-T400, 5AX-N400 and 5AX-B450T.

## Standard Guide Piece



Key width dimension	A×B×C	Code No.
14	14 × 18 × 9	W141809
16	16 × 20 × 10	W162010
18	18 × 25 × 10	W182510
20	20 × 30 × 14	W203014
22	22 × 40 × 14	W224014

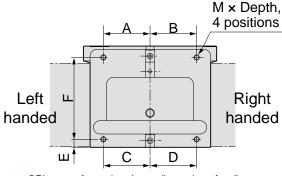
## Stepped Guide Piece



AB	10	12	14	16	18	20	22	24	7/16″	11/16″
14	W-14I	W-14H		W-14A	W-14B	W-14C			W-14F	W-14G
18		W-18E	W-18A	W-18B		W-18C	W-18D			
20				W-20A	W-20B		W-20C	W-20D		

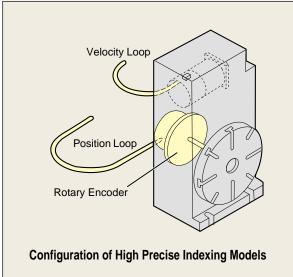
- ★ The item is a set of two each.
- Please note that clamping device is altered when using stepped guide-piece.

# TAP HOLES POSITION at the BOTTOM OF ROTARY TABLE



•Please refer to the above dimensions for direct mounting with the bolts from base plane side.

Table Model	Α	В	С	D	Е	F	M × Depth, 4positions
CNC105, 105L	55	55	55	55	10	125	M10×12L, 4positions
CNC180, 202 CNC180L, 202L	70	70	70	70	12	123	M 8×10L, 4positions
CNC205	85	85	85	85	15	60	M10×15L, 4positions
NCT200	70	70	70	70	12	123	M 8×15L, 4positions
CNC260, 302 CNC260P, 302P	105	120	105	120	12.5	167.5	M12×16L, 4positions
CNC260L, 302L CNC260PL, 302PL	120	105	120	105	12.5	167.5	M12×16L, 4positions
CNC321, 401	145	135	165	135	15	200	M12×20L, 4positions
CNC321L, 401L	135	145	135	165	15	200	M12×20L, 4positions
CNC501, 501L	240	240	240	240	20	235	M16×30L, 4positions



Full closed loop control becomes possible by mounting a rotary encoder at the back of rotary table. And high precise indexing becomes possible by detecting the rotary angle of the table directly.

- 3 grades can be selected for indexing accuracy; ±3", ±5" and ±10".
- Every high Precise Indexing models take a test based on ISO 230-2 to measure the positioning accuracy.
- In case indexing unit of 1" or very high rigidity is required, please select Hirth Coupling Index NSVZ, NSVX series table. F.33
- ★Cables are not included in ultra precision option. Please order separately.
- ★Air purge of the encoder inside is available as an option for water proof. Please contact us.
- ★Encoders from other encoder manufacturers can also be installed. Please contact us separately.

## **CNC** High Precise Indexing for CNC Rotary Table

Indexing Accuracy	±3″	±:	5″
Table Model Maker	Heidenhain	Heidenhain	Magnescale
CNC105, 180, 202, NCT200	_	RCN2391	RU77-4096A
CNC260, 302, 260P, 302P	RCN8591	RCN2391	RU77-4096A
CNC321~1600	RCN8591	RCN8391	RU77-4096A

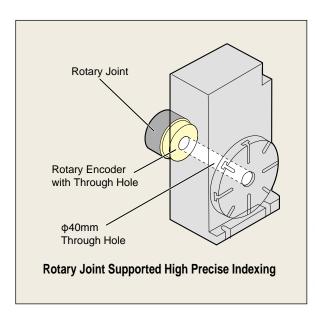
## 5AX High Precise Indexing for Tilting Rotary Table

	Indexing Accuracy		5″	±1	±10″	
Table Model, axis	Maker	Maker Heidenhain Magnescale		Heidenhain	Magnescale	
EAV 120 201 220 250	Rotary	RCN2391	RU77-4096A	_	_	
5AX-130, -201, -230, 250	Tilting	_	_	RCN2391	RU77-4096A	
5 A V 0 5 O	Rotary	RCN2391	RU77-4096A	_	_	
5AX-350	Tilting	_	_	RCN2391	RU77-4096A	
5AX-550, 800	Rotary	RCN8391	_	_	_	
	Tilting	_	_	RCN8391	_	

- ★Higher indexing accuracy (Rotary: ±3 sec., Tilting: ±5sec.) is available. Please contact us.
- ★Some models of Magnescale rotary encoders differ depending on the NC manufacturer used. Please contact us separately.
- ★There is also a circular table to which a Magnescale (RECAPPS) encoder that realizes high-precision positioning can be attached. Please contact us separately.

# **Rotary Encoder with Through-hole**





## Rotary Joint Supported High Precise Indexing

- Even the number of IN ports is limited, rotary joint can be installed for the rotary table with the rotary encoder forhigh precision indexing. Please contact us.
- The rotary table with RCN8391 or RCN8591 has φ40mm through hole, and the rotary joint can be mounted.

## **CNC** High Precise Indexing with Through-hole for CNC Rotary Table

Indexing Accuracy	±3″	±5″
Table Model	Rotary Encoder	Rotary Encoder
CNC260, 302, 260P, 302P	RCN8591	_
CNC321~1600	RCN8591	RCN8391

## 5AX High Precise Indexing with Through-hole for Tilting Rotary Table

Indexin	ng ccuracy	±5″	±10″
Table Model	Couracy	Rotary Encoder	Rotary Encoder
EAV EED OOD	Rotary	RCN8391	_
5AX-550, 800	Tilting	_	RCN8391

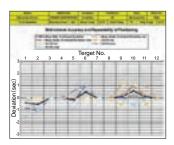
## ■ ISO230-2 : Accuracy Measurement Based on International Standard

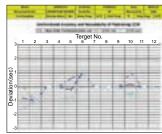
Accuracy Measuring Method Rotating Axis: 30.2°X 12 points Tilting Axis: 15.2°X 8 points

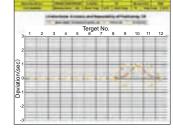
Continually repeating 5 times rotation of CW/CCW, measuring are to be done at above-mentioned points.

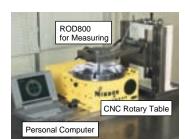
And, bidirectional accuracy of positioning, bidirectional repeatability of positioning, unidirectional accuracy of positioning, unidirectional repeatability of positioning etc. are calculated.

Test data sheet is available in English.









Bidirectional Accuracy and Repeatability of Positioning

## **ROTARY JOINT**





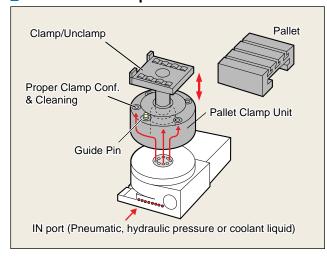
Rotary Joint is a rotating connector to supply air, hydraulic pressure or coolant liquid from outside to a fixture on a CNC rotary table. If liquid is supplied with ordinary hoses, twisting will happen on them by rotation of the table. However, rotary joints can solve this problem as it rotates in accordance with the table.

- Provides Pneumatic, hydraulic pressure or coolant from the rear of the table to a fixture.
- Automation of clamping/unclamping workpieces becomes possible.
- With a choice of 3 types: Cylinder type, Flange Plate type and Built-in type
- ★The coolant port is recommended to be separated because that the fine cutting swarf may come through the filter into the coolant port.
- ★The cylinder type rotary joint is equipped with a port in the center bore exclusively for the coolant liquid.
- ★Even the number of IN ports is limited, rotary joint can be installed for the rotary table with the rotary encoder. Please contact us.

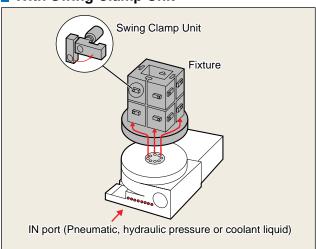
## The Examples of How Rotary Joint is Used

Rotary joint is used for clamping/unclamping workpieces, confirmation of proper clamp, cleaning, coolant etc.

# Automation Application Examples With Pallet Clamp Unit

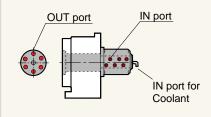


# Automation Application Examples With Swing Clamp Unit



## Type of Rotary Joint

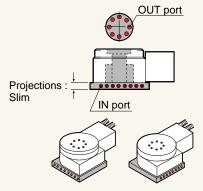
- 1 Cylinder type Rotary Joint
- Cylinder type rotary joint allows many ports.
- Cylinder type rotary joint can be mounted later.



★The cylinder type rotary joint is useful in machining with the coolant liquid, because it's equipped with a port exclusively for the coolant liquid.

## 2 Flange Plate type Rotary Joint

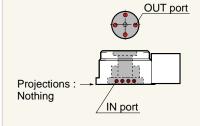
- Flange plate type rotary joint reduces supply block projections
- •IN ports position can be changed at any side: front, back, left or right side.



- ★The every position which causes no interference against M/C can be selected.
- ★Flange plate type rotary joint is useful in NSV series.

## 3 Built-in type Rotary Joint

- The highest space efficiency of all models of rotary joints
- Built-in type rotary joint can be mounted without changing dimension.







## **CNC** Rotary Joints for CNC Rotary Tables

Code No	Cylinder type	Flange Plate	e type	Built-in type
Code No.	MAX. Number of Ports	MAX. Number of Ports	T*(mm)	MAX. Number of Ports
NCT 200	6+1	6	39	_
CNC 105	4+1	4	25	_
180, 202	6+1	6	25	_
205	_	_		6+1
260, 302, 260P, 302P	10+1	11	60	_
(260B, 302B)	_	8+1	_	
321, 401, 401H	12+1	_		8+1
B350	16+1	_	_	
B450	20+1	_		_
503H	12+1	_		12+1
501, 601	14+1	15*6	_	8+1
802	16+1	_	_	10+1
NSVZ 180	6+1	5	25	_
300	8+1	6	30	_
400, 500	12+1	13	50	_

## **Rotary Joints for Support Tables**

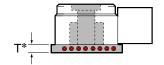
Code No.	Cylinder type	Flange Plate	e type	Built-in type
Code No.	MAX. Number of Ports	MAX. Number of Ports	T*(mm)	MAX. Number of Ports
TAT- 105, 170	6+1	2	25	_
200, 250	9+1*1	7	30	_
321, 401, 501	14+1	8+1	35	_

<sup>\*1</sup> MAX Number of Ports is 8+1P for TAT-200.

## 5AX Rotary Joints for Tilting CNC Rotary Tables

Codo No	MAX. Number of	Cylinder type	Flange Plate	e type	Built-in type	
Code No.	Ports on Main Unit	MAX. Number of Ports	MAX. Number of Ports	T*(mm)	MAX. Number of Ports	
5AX- 100	_	(4)	3	25	_	
130	_	2 (4)	_	_	_	
201	4	4 (6)	_	_	4*2	
250	3	_	_	_	3*3	
350	6	_	_	_	6+1*4	
550	4	10*5	_	_	_	
800	6	<del>_</del>	_	<del>-</del>	6	
DD250	_	_	6	30	_	
DD400	_	_	8	30	_	
5AX-DD200A,B	_	_	4	<u> </u>	_	

- ★ ( ): MAX No. of high column table.
- ★"+1" is the port located in the center hole for coolant.
- \* "T" is dimension of supply block projections after mounting rotary joints.
- \*2 : 4 reserve ports are provided on 5AX-201.
- \*3:3 reserve ports are provided on **5AX-250** and 2 external ports are available.
- \*4 : 6reserve ports are provided on **5AX-350**. No additional port is available.
- \*5: 4 reserve ports are provided on 5AX-550 as standard, and the additional 6 ports are available.
- \*6: It becomes correspondence of a special use.



## Caution of IN port

- •When the air is supplied for all IN ports, please contact us.
- •Please do not supply the different pressure of the air in the IN ports next each other.
- •Please make sure that the line filter should be provided for pneumatic supply use in order to avoid swarf and water ingress for rust problem.
- •This is not avoidable that the oil of the hydraulic port may be leaked to the next air port for the long time use, due to the characteristic of the seal. Please do not assign the air port next to the hydraulic port as much as possible.
- •The rotary joint must be specially treated to prevent from the rust, when using the glycol solution for the operating fluid. Please inform us when ordering.
- •When the rotary joint is designed at your side, please select the low friction type seal. Then, please check the rotary table movement after installation of your rotary joint, not to over load.

# **How to Read Product Code of ROTARY JOINT**



# RT-CN105 SD-3+1-L

Hose Direction of the Sleeve seen from behind, or sub-code.

R: Right (Cylinder type) Fig.1

L : Left (Cylinder type) Fig.2 F : Flange (Flange Plate type) Fig.3

B: Main Unit (Built-in type)

A:5AX

Number of Ports 3+1 With a Center Port 3+N W/O a Center Port

SD: Standard

Diameter of Table

RT: Cylinder type Rotary Joint

RN: Flange Plate type Rotary Joint, Built-in type Rotary Joint.







R : Right (Cylinder type)

L: Left (Cylinder type) Flange (Flange Plate type)

## **Code No. of Rotary Joint**

Table Model	No. of port	Туре	Code No.	Remarks
	3+1		RT-CN105SD-3+1-L	3+1RJ Cylinder type
	3+1		RT-CN105SD-3+1-R	3+113 Cyllinder type
CNC105	4+1	Cylinder type	RT-CN105SD-4+1-L	4+1RJ Cylinder type
CNC105	4+1	Cylinder type	RT-CN105SD-4+1-R	4+1K3 Cyllilidel type
	6+1		RT-CN105SD-6+1-L	6+1RJ Cylinder type
	6+1		RT-CN105SD-6+1-R	6+1K3 Cyllinder type
	3+1	Cylinder type	RT-CN180SD-3+1-L	2.11P I Cylinder type
	3+1	Cylinder type	RT-CN180SD-3+1-R	3+1RJ Cylinder type
	4		RN-CN180SD-4+N-F	4RJ Flange Plate type
	4+1	O dia dan tan	RT-CN180SD-4+1-L	4 · 4 D I Codin don tono
0110400 000	4+1	Cylinder type	RT-CN180SD-4+1-R	4+1RJ Cylinder type
CNC180, 202	4+1	Flange Plate type	RN-CN180SD-4+1-F	4+1RJ Flange Plate type
	5+1	Flange Plate type	RN-CN180SD-5+1-F	5+1RJ Flange Plate type
	6	Flange Plate type	RN-CN180SD-6+N-F	6RJ Flange Plate type
	6+1	0 11 1	RT-CN180SD-6+1-L	C. A.D. I. Coding days from a
	6+1	Cylinder type	RT-CN180SD-6+1-R	6+1RJ Cylinder type
CNC205	6+1	Flange Plate type	RN-CN205SD-6+1-B	6+1RJ Flange Plate type
	6	Flange Plate type	RN-NC200SD-6+N-F	6RJ Flange Plate type
NCT200	6+1	Ordinalay truna	RT-NC200SD-6+1-L	C. A.D. I. Culindor tuno
	6+1	Cylinder type	RT-NC200SD-6+1-R	- 6+1RJ Cylinder type
	6	Flange Plate type	RN-NC20ESD-6+N-F	6RJ Flange Plate type
NCT200E	6+1	O dia dan tana	RT-NC20ESD-6+1-L	C. A.D. I. C. dia dan tropa
	6+1	Cylinder type	RT-NC20ESD-6+1-R	6+1RJ Cylinder type
	4+1	Ordinalay truna	RT-CN260SD-4+1-L	4.4D L Cylinder type
	4+1	Cylinder type	RT-CN260SD-4+1-R	4+1RJ Cylinder type
	4+1	Flange Plate type	RN-CN260SD-4+1-F	4+1RJ Flange Plate type
	6+1	Ordinalay truna	RT-CN260SD-6+1-L	C. A.D. I. Culindor tuno
CNC260, 302 CNC260P, 302P	6+1	Cylinder type	RT-CN260SD-6+1-R	6+1RJ Cylinder type
0110200F, 302F	6+1	Flange Plate type	RN-CN260SD-6+1-F	6+1RJ Flange Plate type
	8+1	Culin day tung	RT-CN260SD-8+1-L	9 L1D I Cylindor typo
	8+1	Cylinder type	RT-CN260SD-8+1-R	8+1RJ Cylinder type
	8+1	Flange Plate type	RN-CN260SD-8+1-F	8+1RJ Flange Plate type

# **How to Read Product Code of ROTARY JOINT**



Table Model	No. of port	Туре	Code No.	Remarks
CNC321	8+1	Built-in type	RN-CN321SD-8+1-B	8+1RJ Built-in type
CNC401	8+1	Built-in type	RN-CN401SD-8+1-B	8+1RJ Built-in type
CNCEONL	8+1	Duilt in tune	RN-CN503HSD-8+1-B	8+1RJ Built-in type
CNC503H	12+1	Built-in type	RN-CN503HSD-12+1-B	12+1RJ Built-in type
CNC501	8+1	Built-in type	RN-CN501SD-8+1-B	8+1RJ Built-in type
CNC601	8+1	Built-in type	RN-CN601SD-8+1-B	8+1RJ Built-in type
CCT400 425	4+1	Culindar tuna	RT-CST100SD-4+1-L	4 . 1 D. I. Cylindor typo
CST100-135	4+1	Cylinder type	RT-CST100SD-4+1-R	4+1RJ Cylinder type
	3+1		RT-TA105SD-3+1-L	2.4D L Cylinder type
	3+1		RT-TA105SD-3+1-R	3+1RJ Cylinder type
TAT 405N	4+1	O dia dan tana	RT-TA105SD-4+1-L	4 · 4 D I Coding day to a
TAT-105N	4+1	Cylinder type	RT-TA105SD-4+1-R	4+1RJ Cylinder type
	6+1		RT-TA105SD-6+1-L	C. AD I Codin don ton
	6+1		RT-TA105SD-6+1-R	6+1RJ Cylinder type
	3+1		RT-TA170SD-3+1-L	2.4D LOulindar turns
	3+1		RT-TA170SD-3+1-R	3+1RJ Cylinder type
<b>747</b> 4 <b>76</b> 11	4+1		RT-TA170SD-4+1-L	4.4510.15.1.4
TAT-170N	4+1	Cylinder type	RT-TA170SD-4+1-R	4+1RJ Cylinder type
	6+1		RT-TA170SD-6+1-L	0.40104554555
	6+1		RT-TA170SD-6+1-R	6+1RJ Cylinder type
	4+1		RT-TA200SD-4+1-L	4.4010.5.4.4.4
	4+1		RT-TA200SD-4+1-R	4+1RJ Cylinder type
<b>-1-</b>	6+1		RT-TA200SD-6+1-L	0.4010151.4
TAT-200N	6+1	Cylinder type	RT-TA200SD-6+1-R	6+1RJ Cylinder type
	8+1		RT-TA200SD-8+1-L	0.40104554555
	8+1		RT-TA200SD-8+1-R	8+1RJ Cylinder type
	4+1		RT-TA250SD-4+1-L	4.4010.5.4.4.4
	4+1		RT-TA250SD-4+1-R	4+1RJ Cylinder type
TAT 050N	6+1	O dia dan tana	RT-TA250SD-6+1-L	C. 4D I Culinday tuna
TAT-250N	6+1	Cylinder type	RT-TA250SD-6+1-R	6+1RJ Cylinder type
	8+1		RT-TA250SD-8+1-L	O. 4D I Culinday tuna
	8+1		RT-TA250SD-8+1-R	8+1RJ Cylinder type
EAV 400	3	Flange Plate type	RN-AX101SD-3+N-A	3 Flange Plate type
5AX-100	4	Cylinder type	RT-AX101SD-4+N-A	4 Cylinder type
EAV 420	3	Culinder	RT-AX130SD-3+N-A	3 Cylinder type
5AX-130	4	Cylinder type	RT-AX130SD-4+N-A	4 Cylinder type
EAV 204	4	Flange Plate type	RN-AX201SD-4+N-A	4 Flange Plate type
5AX-201	6+1	Cylinder type	RT-AX201SD-6+1-A	6+1 Cylinder type
5AX-250	3	Flange Plate type	RN-AX250SD-3+N-A	3 Flange Plate type
5AX-350	6	Flange Plate type	RN-AX350SD-6+N-A	6 Flange Plate type
5AX-550	6	Flange Plate type	RN-AX550SD-6+N-A	6 Flange Plate type

## **AWC SYSTEM**



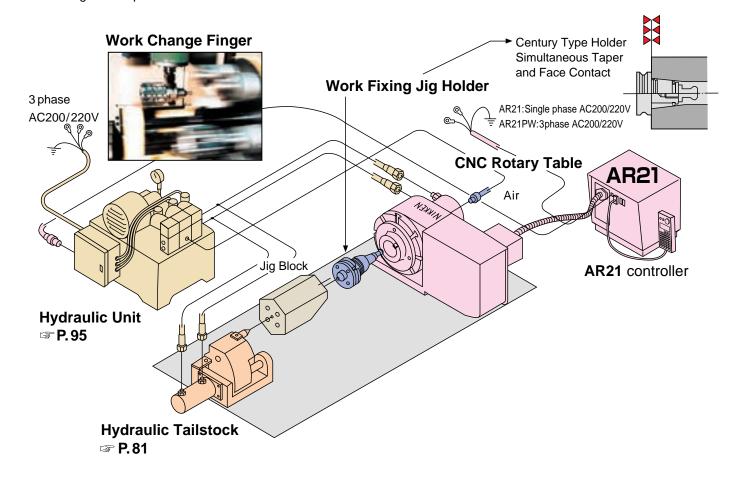


Extremely flexible, and can take many kinds of work pieces. Jig Holder is firmly held in the center hole of CNC Rotary Table as Century Type Holder System. (Simultaneous taper and flange contact) Jig Block can take various work fixtures designed according to each work piece.

Plural number of work pieces can be held. Jig Holder with ID is available (optional), and automatic selection of Jig Holder in magazine is possible.



AWC magazine, Disc type, Chain type, Horizontal type and Bar Work type are available.

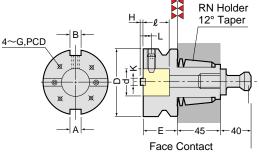


# AWC SYSTEM



## Work Fixing Jig Holder





Standard Pull Stud: PS-3 Holder with ID, Pull Stud with ID are available. (optional) Whether Work Fixing Jig Holder is suitable to the work or not results in big difference in productivity. We have wide and deep experiences and know-how. Please contact us.

Refer to NC5 tooling system literature for NC5 models

#### Side Lock type Holder

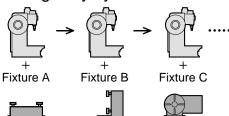
Code No.	D <sub>1</sub>	d	K	Е	Н	R	L	M	G	PCD	A 0 -0.010	В	Weight
RN40-63×25	63	25H <sub>6</sub>	10h7	40	5	30	15	M10	M8	48	16	18	1.5kg
RN45-85×32	85	32H <sub>6</sub>	12h7	45	5	35	20	M12	M10	65	18	20	2.5kg

Examples of Jig Block (optional)



## Advantage of 5AX-Table in Automation Production Line

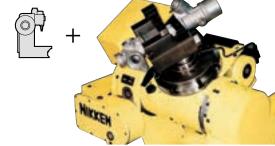
The originally system



It's necessary to prepare suitable jig fixtures for each process, then the machining cycle time will be adjusted with increasing the number of processes.

- It's difficult to obtain the exactly same reference location in each operation, therefore it's easy to affect the finish quality.
- If the one machine breaks down, all of the production line will be stopped.
- The cost and the delivery for making a new jig fixture for the new design causes problems.

System with 5AX-Table



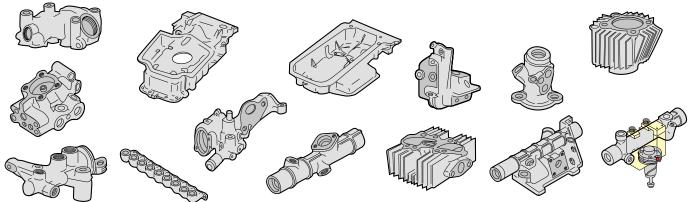
The full surface machining

on top half of the component can be achieved with only one setup.

The machining cycle time will be adjusted with increasing the number of machines.

- As the full surface machining can be done with only one setup, the finish quality will be improved.
- Even if one machine breaks down, the extended operation time on another machine can achieve same quantity of production.
- It's easy and quick to machine new design component only by changing machining program.
- The random production can be done by the jig holder with ID tip. (That's ideal for the automotive production line as there are many pair parts of right and left.)





## **NIKKEN**

## Waterproof Specifications

- •Mechanical parts of the table are perfectly sealed. For water resistance to electric parts such as cables, the hard-wired type connection on the motor cover is available as an option.
- •For the rotary table with pneumatic clamping, air purge is arranged inside the motor cover as standard.
- In case of the table which with **α**21 controller, the hard-wired type connection on the rotary table side and harting connector fitting on the controller side, however, the harting connector fitting on the rotary table side is also available as an option.

For all CNC rotary tables,  $\triangle$  mark obtained parts or equivalent and  $\bigcirc$  marked electric parts are used, ensuring high safety.

▲ : Safety approval mark by TUV RHEINLAND.

( ): Safety mark required for marketing in Europe from '95.







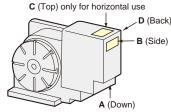
Cable with Blade (Option) Standard Length: 5m



Harting Connector type

## Position & Direction of Connecting Cable

The standard of the cable connecting direction is **B** or **D**. **A** or **C** is possible on demand.



## Hydraulic Unit

Specifications TCC-150

MAX.14 $\ell$ /min MAX.3.5MPa

- ●AC 200~220V, 3 phases, Capacity: 1KVA.
- •Solenoid valves and pressure switches depends on your applications.
- ●Dimension: 400×405×479mm

# TCC-150

#### **VBA10A-02G**

# OUT Pressure gauge RC1/4 IN Port OUT P

## Air Intensifying Booster (Max. Output: 0.7MPa)

The air pressure can be double by Air Intensifying Booster. This is suitable for tables with the Double Intensifying Clamping System.

## Air Hydraulic Booster

Please order an air hydraulic unit for the machine without hydraulic source.

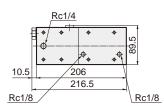
Applicable for CNC260, CNC302: AY0400 / CNC321~CNC803: NB-AB30-150 / 5AX-201,350: NB-AB30-75

Please ask for the layout of the booster.

## AY0400

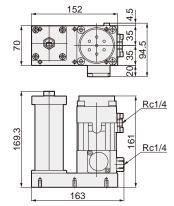
Oil Capacity: 30cc Input pneumatic Pressure: 0.4~0.5MPa Output hydraulic Pressure: 2.0~2.5MPa





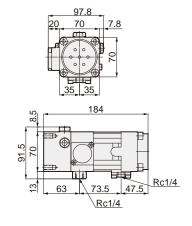
## NB-AB30-150

Oil Capacity: 150cc Input pneumatic Pressure: 0.41~0.47MPa Output hydraulic Pressure: 3.5~4.0MPa



## NB-AB30-75

Oil Capacity: 75cc Input pneumatic Pressure: 0.41~0.47MPa Output hydraulic Pressure: 3.5~4.0MPa



## **NIKKEN**

## Air Craft-related Parts Apprication.



Synchronous Rotation by CNC401 X 2units



5AX-150 for 4th and 5th axes tilting rotary table on special grinding center

## Automobile Parts Apprication.



CNC180 + TAT-105N





CNC601,3m Jig Block & TAT-501N





3 sets of power chucks are used for work clamping.

## Energy-related Parts Apprication.



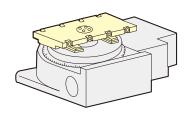
CNC1800 & Support Branch Indexing/ clamping of the turbine disk



CNC1201 Indexing of the turbine shaft. Turbine shaft is supported and clamped by the roller support.

## ■ Built-in Pallet Clamp System

Available to CNC rotary table and 5AX- tilting rotary table. Very suitable to NC special purpose machine and Horizontal M/C as built-in B axis



Lifting type Pallet Clamp Unit

## Special Color

Please order with the color sample or Munsell Color No.



Pallet Clamp Unit with Automatic Coupler



NIKKEN CNC rotary tables are used in various kinds of world wide applications. Please contact with us with the dimension of your work piece and construction of the jig fixture etc. We will recommend you the best application.

## Combination with Pallet Changer







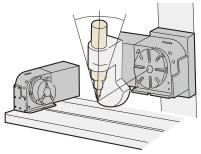


2 units of CNC rotary tables are used on the TAPPING CENTER with swing type pallet changer.

## Combination of CNC Rotary Tables







Machining of turbine wheel to use 2 units of CNC rotary tables, one for the swing axis of the HF motor and the other for the rotary axis of the work piece



5AX-400FA-RJ8-800/150



5AX-500MA-RJ10-900/100



5AX-321FA



CNC180+TAT-105N+CNCZ503



**CNC180+Special Support Table** 



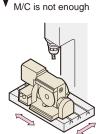
## ■ Example of 5AX Rotary Table location on M/C

There are various ways of arrangement.

Y axis stroke of the



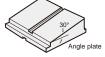
▼ Tail Stock is used together.







▼ Tilting range is 30-135

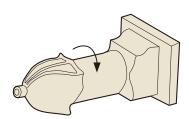




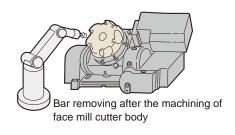
5AX-300 Example on the angle base (60°)

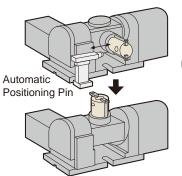
## Application of 5AX-Table

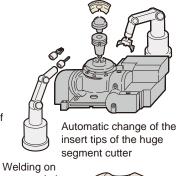


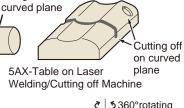


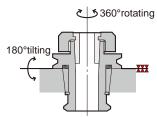
Simultaneous 3 axes control of X, Z & A axis instead of turning.











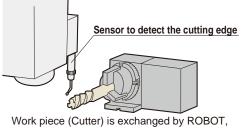
5AX-Multi Spindle Table + Jig Holder with Through Hole

Hobbing of

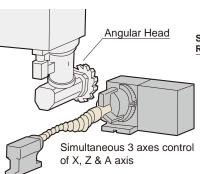
- 1. The work piece is exchanged by ROBOT, the positioning pin goes forward, then the work piece is clamped at the tilting axis = 90°.
- 2. The positioning pin goes backward, the tilting axis moves to 0°, then the machining starts.

The tilting movement is used only for automatic work piece exchange

#### Other Application

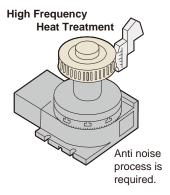


and the cutting edge will be detected automatically.





tooth module 6∼7 Separate Clamping Rotary table is used to drive by spline and positioning.





CNC1201 Indexing of the turbine shaft. Turbine shaft is supported and clamped by the roller support.

# TEC TECHNICAL DATA Accuracy Standard

## ■ CNC Rotary Table only for Vertical Use···Back side motor mounted type F.21,22. Top side motor mounted type F.17~P.20

No.	Measuring Item	Measuring Method	CNC180•202 NCT200	CNC205	CNC <sub>302</sub> , 260P	CNC321	CNCB <sub>450</sub>	CNC <sup>501</sup>
2	Runout of table surface		0.01mm	0.01mm	0.015mm	0.015mm	0.015mm	0.02mm
3	Concentricity of center bore		0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	0.01mm
4	Squareness of table surface (Minus deviation at upper part is not permitted.)	To To	0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.03mm
5	Parallelism between center line of test bar and key way		At 150mm 0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.02mm
6	Parallelism between frame bottom surface and table center line		At 150mm 0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.03mm
7	Indexing accuracy		±20″	±20"	20"	15″	15"	15″
8	Repeatability		4"	4"	4"	4"	4"	4"

<sup>★</sup> For ultra precision option: One rank higher accuracies than the above figures are inspected.

## ■ CNC Rotary Table only for Horizontal Use…Built-in type P.55

	cite iteating raises citing for t		21 - 21							
No	. Measuring Item	Measuring Method	CNC 180 NCT 200	CNC360, 260P	CNC 321 400H	CNC 503H 601	CNC <sub>1000</sub>	CNC <sub>1201</sub>	CNC1600	
1	Parallelism between table surface and frame bottom surface (Concave)		0.015mm	0.02mm	0.02mm	0.02mm	0.03mm	0.04mm	0.05mm	
2	Runout of table surface at horizontal position		0.01mm	0.015mm	0.015mm	0.015mm	0.03mm	0.03mm	0.04mm	
3	Concentricity of center bore		0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	0.01mm <sup>*1</sup>	0.01mm*1	
6	Squareness between frame bottom surface and table center line		At 150mm 0.02mm	0.02mm	0.02mm	0.03mm			_	
7	Indexing accuracy		±20"	20"	15"	15″	15"	15"	15"	
8	Repeatability		4"	4"	4"	4"	4"	4"	4"	

<sup>★</sup> For ultra precision option: One rank higher accuracies than the above figures are inspected.

#### ■ DD Motor ··· 🖙 P.49~P.54

No.	Measuring Item	Measuring Method	DD180F-60	DD251F-150	DD400F-250
2	Runout of table surface		0.01mm	0.01mm	0.015mm
3	Concentricity of center bore		0.01mm	0.01mm	0.01mm
4	Squareness of table surface (Minus deviation at upper part is not permitted.)		0.01mm	0.01mm	0.02mm
5	Parallelism between frame bottom surface and table center line		At 150mm 0.02mm	0.02mm	0.02mm
6	Parallelism between frame bottom surface and table center line		At 150mm 0.02mm	0.02mm	0.02mm
7	Indexing accuracy		±10"	±10"	±10"
8	Repeatability		4"	4"	4"

No.	Measuring Item	Measuring Method	5AX-DD100AF	5AX-DD200AF2	5AX-DD201BF3
1	Parallelism between table surface andframe bottom at tilting angle 0° (Concave)		0.01mm	0.01mm	0.01mm
2	Deviation of table surface at tilting angle 0°		0.01mm	0.01mm	0.01mm
3	Deviation of table center hole at tilting angle 0°		0.01mm	0.01mm	0.01mm
4	Displacement of center when moving from 0° to 90° at tilting angle 90°		0.015mm	0.015mm	0.015mm
5	Parallelism between table surface and center line of guide key at tilting angle 90°		0.01mm	0.01mm	0.01mm
6	Indexing accuracy of rotary axis		±5"	±10"	±10"
7	Repeatability of rotary axis		2″	4"	4"
8	Repeatability of tilting axis	Cumulative	±10"	±15"	±15"
9	Indexing accuracy of tilting axis		±3"	6"	6"

<sup>★</sup> Please contact us for the accuracy of the rotary table larger equal to CNC802 for vertical use.

<sup>★</sup> Center socket is provided at the center bore for the table marked \*1. Concentricity of the internal center socket is shown.

# **Accuracy Standard**



## ■ CNC Rotary Table for both of Vertival and Horizontal Use

No.	Measuring Item	Measuring Method	CNC105	CNC180•202 NCT200	CNC <sup>260</sup> , 260P	CNC321	СNСВ <sup>350</sup>	CNC <sup>501</sup>	CNC <sub>1003</sub>
1	Parallelism between table surface and frame bottom surface (Concave)		0.015mm	0.015mm	0.02mm	0.02mm	0.02mm	0.02mm	0.03mm
2	Runout of table surface		0.01mm	0.01mm	0.015mm	0.015mm	0.015mm	0.02mm	0.03mm
3	Concentricity of center bore		0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	0.01mm
4	Squareness of table surface (Minus deviation at upper part is not permitted.)		0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.03mm	0.04mm
5	Parallelism between center line of test bar and key way		At 150mm 0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.02mm
6	Parallelism between frame bottom surface and table center line		At 150mm 0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.03mm	0.03mm
7	Indexing accuracy		±30"	±20"	20"	15″	15"	15″	15"
8	Repeatability		4"	4"	4"	4"	4"	4"	4"

<sup>★</sup> For ultra precision option: One rank higher accuracies than the above figures are inspected.

## NST, 5AX- Tilting Rotary Table

No.	Measuring Item	Measuring Method	NST <sup>250</sup>	NST500	5AX <sub>130</sub>	5AX-201	5AX-250	5AX-230 350	5AX-500	5AX-800	5AX-1200
1	Parallelism between table surface and frame bottom at tilting angle 0° (Concave)		0.02mm	0.02mm	0.015mm	0.015mm	0.02mm	0.02mm	0.03mm	0.04mm	0.05mm
2	Deviation of table surface at tilting angle 0°		0.02mm	0.02mm	0.01mm	0.01mm	0.02mm	0.02mm	0.02mm	0.03mm	0.04mm
3	Deviation of table center hole at tilting angle 0°		0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	0.01mm	*1 0.01mm
4	Deviation of center line of rotary axis at tilting angle 90°		0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.02mm	0.03mm	0.04mm	0.05mm
5	Parallelism between table surface and center line of guide key at tilting angle 90°		0.02mm	0.02mm	0.015mm	0.015mm	0.02mm	0.02mm			_
6	Displacement of center when moving from 0° to 90° at tilting angle 90°	0	0.02mm	0.02mm	0.01mm	0.015mm	0.015mm	0.015mm			_
7	Indexing accuracy of rotary axis		Cumulative 20"	20"	±30″	±15"	Cumulative 20"	20"	20"	20"	20"
8	Repeatability of rotary axis		4"	4"	4"	4"	4"	4"	4"	4"	4"
9	Indexing accuracy of tilting axis	Cumulative	60″	60″	60″	60″	60″	60″	60″	60″	60"
10	Repeatability of tilting axis				±6"	±6"	±6"	±6"	±6"	±6"	±6"

- ★ For ultra precision option: One rank higher accuracies than the above figures are inspected.
   ★ Center socket is provided at the center bore for the table marked \*1. Concentricity of the internal center socket is shown.

No.	Measuring Item	Measuring Method	Accuracy
1	Pitch between Spindles		Within ±0.02mm from nominal pitch
2	Center Hight of Spindle	<b></b>	Within ±0.02mm

## Mulit-Spindle CNC Rotary Table ··· ☞ P.25 Mulit-Spindle Tilting Rotary Table ··· ☞ P.47

No.	Measuring Item	Measuring Method	Accuracy
1	Pitch between Spindles		Within ±0.02mm from nominal pitch
2	Center Hight of Spindle	<b>PIPIPI</b>	Within ±0.02mm

 $<sup>\</sup>bigstar$ How to mount the above tables on your M/C, please contact us.

<sup>★</sup> Please contact us for the accuracy of the rotary table larger equal to CNC802 for both of vertical and horizontal use.

# **Description of Specifications**



## Specification

CNC260 CNCZ260 Item / Code No. Diameter of Table 260  $\phi$ mm Diameter of Spindle Hole  $\phi$ mm ф80н7 Centre Height mm 170 12+0.018 Width of T Slot mm Air 0.5MPa Hyd. 3.5MPa Clamping System Air/Hyd. 588/1568 Clamping Torque N·m  $\left(\frac{\text{GD}^2}{4}\right) \text{ kg·m}^2 \times 10^{-3}$ Table Inertia at motor Shaft 0.33 Servo Motor  $\alpha$  iF4·3000 r/min MIN. Increment 0.001 **Rotation Speed** 16.6(33.3) r/min **Total Reduction Ratio** 1/120(1/60) Indexing Accuracy sec Net Weight 115 kg Vertical MAX. 175 Work Load Horizontal on the Table 350 kg 42480 Ν MAX. Thrust Load 1442 FXL applicable N·m on the Table 2320 FXL N·m Guide Line of MAX. 60 Unbalancing Load N·m Vertical MAX. 3.2(1.6) Work Inertia  $(\frac{GD^2}{4})$  kg·m<sup>2</sup> Driving 192 (153) **Torque**  $N \cdot m$ 

#### Code No.

CNC:Standard CNCZ:High Speed Z Series

The worm wheels and worm screws on CNC and **CNCZ** models are different and not interchangeable.

#### **Table Diameter**

Please make sure that the work inertia should be within the specified tolerance when the fixture or the work piece is larger than the rotary table diameter.

#### Through Hole Diameter

All model have MAX. through hole.

#### Clamping System

For the changing from the hydraulic brake system to the air brake system, please refer to 6-5) Supplying pneumatic or hydraulic pressure for brake and venting air.

The values are according to pneumatic 0.5 MPa / hydraulic 3.5 MPa

Nikken determine the MAX. table rotation speed with the best motor rotation from the motor acceleration characteristics and the practical load test. Normally, we select the motor rotation speed of 1,500r/min or 2,000r/min. It is possible to increase the rotary table rotation speed to increase the motor rotation speed dependant of each application. Please contact with us for the details. FÄNUC  $\alpha$ i series motor can be rotated faster speed than the recommended speed.

 $\alpha$ iF1,  $\alpha$ iF4: 3,000r/min  $\alpha$ iF12: 2,000r/min

#### MAX. Work Load

The figure becomes double when the rotary table is used with tail stock or support table.

#### MAX. Applicable Thrust Load

This is a applicable figure for the (dynamic) cutting thrust force with cutting tools, e.g. drill, at the rotary table horizontal use.

#### Worm Wheel Strength

This is the strength of the worm wheel without brake. It is applied against dynamic cutting thrust.

The figure shows the strength of the bearings on the rotary table spindle and the applicable (dynamic) cutting thrust with center support.

#### MAX. Unbalancing Load

The guide line of MAX unbalancing load means the unbalancing load, which the rotary table is used with support table in vertical application. The guide line figure will be different according to the servo motor, please refer P.57 for more detail.

#### Driving Torque

This figure shows the rotation torque at the MAX. rotation speed after acceleration.

#### SI Unit & Gravity Unit SI is the abbreviation of "Systeme International d'Unites".

Item	SI Unit	Gravity Unit	Conversion
Clamping torque	N∙m	kgf∙m	1kgf⋅m=9.8N⋅m
Table Inertia at Motor Shaft *	$\left(\frac{\text{GD}^2}{4}\right)$ kg·m <sup>2</sup> ×10 <sup>-3</sup>	kg cm sec <sup>2</sup>	1kg cm sec <sup>2</sup> =10.2×( GD <sup>2</sup> /4 )kg·m <sup>2</sup>
MAX. Motor Rotation Speed	r/min	rpm	1rpm=1r/min
MAX. Table Rotation Speed	r/min		
MAX. Thrust Load	N	kgf	1kgf=9.8N
applicable on the Table	N∙m	kgf∙m	1kgf⋅m=9.8N⋅m
MAX. Work Inertia*	$(\frac{GD^2}{4})$ kg·m <sup>2</sup>	kg cm sec <sup>2</sup>	1kg cm sec <sup>2</sup> =10.2×( GD <sup>2</sup> /4 )kg·m <sup>2</sup>
Driving Torque	N∙m	kgf∙m	1kgf·m=9.8N·m
Air/Hydraulic Pressure	MPa	kgf/cm <sup>2</sup>	1kgf/cm <sup>2</sup> =0.098MPa

<sup>\*</sup> The unit of inertia is expressed in GD2.

# **Recommended Iubricating Oil and Quantity**



Recommended oil

Oil Maker	Code No.
Idemistu Kosan	Super Multi Oil 100
JX Nippon Oil & Energy	SUPER MULPUS DX 100
Cosmo Oil Lubricants	Cosmo New Mighty Super 100
Showa Shell Sekiyu	Shell Morlina S2 BA100
EMG Marketing	Mobil DTE Heavy

Required oil quantity for CNC rotary table

Table Model	Main Body(cc)	Gear Box(cc)	
CNC(Z)105	110	Grease	
CNC(Z)180, 202	500	Grease	
NCT200(E)	400	Grease	
CNC205	200	Grease	
CNC(Z)260, 302, 260P, 302P	700	300	
CNCB350	1,300	600	
CNC(Z)321, 401	2,000	700	
CNC(Z)401H	2,000	_	
CNCB450	2,000	500	
CNC(Z)501, 601, CNC801	7,000	1,500	
CNC(Z)503	5,000	<del>-</del>	
CNCB630	6,000	1,500	
CNC802	14,500	2,500	
CNC803	15,000	2,000	
CNC1200	18,0	000	
CNC1201	26,000		
CNC1600	60,0	000	
CNC(Z)180B, 202B	500	Grease	
CNC(Z)260B, 302B	700	1,200	
CNC(Z)321B, 401B	2,000	1,000	
CNC180T, 202T	1,5	500	
CNC(Z)260T, 302T	1,5	500	
CNC(Z)321T, 401T	4,0	000	
CNCB450T	5,5	500	
CNC(Z)501T, 601T	8,0	000	
CNC100-2W	540	Grease	
CNC100-3W	720	Grease	
CNC100-4W	900	Grease	
NST250	1,300	Grease	
NST300	1,800	Grease	
NST450, 500	10,000	Grease	
NSVZ180	500	Grease	
NSVZ300	1,500	Grease	
NSVX400	3,0		
NSVX500	3,000		
NSVX400T	5,000		
TAT-105N,170N		0	
TAT-200N,250N		ase	
TAT-321N,401N	Gre		

■ Required oil quantity for 5AX rotary table

Table Model	Axis	Main Body(cc)	Gear Box(cc)	
5AX-100	Rotary	300	Grease	
3AX-100	Tilting	300	Grease	
5AX-130	Rotary	350	Grease	
5AX-130	Tilting	400	Grease	
5AX-150	Rotary	450	Grease	
JAA-130	Tilting	500	Grease	
5AX-201	Rotary	400	Grease	
3AX-201	Tilting	300	Grease	
5AX-250	Rotary	80	00	
JAA-230	Tilting	600	Grease	
5AX-230	Rotary	700	Grease	
JAX-230	Tilting	800	400	
5AX-350	Rotary	2,0	000	
JAX-330	Tilting	800	300	
5AX-T(N)400	Rotary	14,000		
3AA-1 (14) <del>1</del> 00	Tilting	4,000		
5AX-B450(T)	Rotary	7,000(9,000)*1		
JAX-D430(1)	Tilting	3,000(5,500)*2	1,000( - )*2	
5AX-550	Rotary	2,000	Grease	
JAA-330	Tilting	2,000	800	
5AX-800	Rotary	8,0	000	
JAX-000	Tilting	4,000	2,000	
5AX-2MT-105	Rotary	700	Grease	
3AX-2WH-103	Tilting	400	Grease	
5AX-2MT-170	Rotary	2,0	000	
JMA-21911-17U	Tilting	700	300	
5AX-2MT-200	Rotary	2,0	000	
3AA-2IVI I-2UU	Tilting	2,000	1,000	
5AX-4MT-120	Rotary	2,000	Grease	
3AA-4WH-12U	Tilting	700	300	

## **Assessment**

# **NIKKEN**

## Accessment for Reliability & Quality.

## Over Load Test

The wearing of the worm wheel is very small under very severe testing condition.







## ■ Brake Torque Test







## Cutting Stability Test

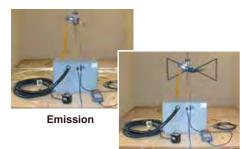
The micro vibration during machining or the surface finish are measured.





## **■ EMC Test**

Electromagnetic Compatibility Test



**Immunity** 

Water Proof Test





Declaration of Incorporation (EU)

## Accuracy Measurement



**Indexing Accuracy Measurement** by Laser



5AX-230 on 3 Dimensional Measuring Machine



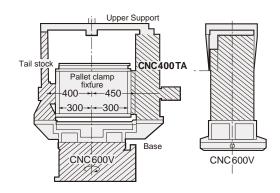
Accuracy measurement with large 3 Dimensional Measuring Machine

# Load Calculation / Indexing Time Comparison / Duraility **NIKKEN**

## Conditions of CNC Rotary Table when being used to CNC Special Purpose Machine

Not only indexing accuracy, the following conditions must be also filled for continuous operation of 24 hours. Namely, Load calculation, Indexing time, Durability etc.
And the overseas service branches and after service ability are also important.





## 1 Load Calculation

In case using conditions are beyond the specification of CNC rotary table, please inform us the work piece, jig fixtures, required indexing time etc. Then, we will calculate the load of your application, and select the suitable CNC rotary table. When such jig fixture and work as right hand are to be rotated on CNC rotary table, we analyze into 1~5 elements, and calculate as per the list shown at right hand side.

No.	Shape	Quantity	Approx. Weight (Kg)	Approx. GD <sup>2</sup> (GD <sup>2</sup> /4)Kgm <sup>2</sup>
1	CNC400T Eccentricity: 450mm	1	260	59
2	Tailstock Eccentricity: 120mm	1	80	14
3	Base	1	11	10
4	Upper Support Parts	1	30	2
5	Pallet Clamp Fixture Eccentricity: 120mm	1	80	6
Total			560	91

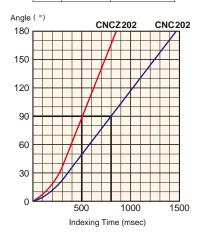
## 2 Indexing Time Comparison

Indexing Time = Acceleration Time + Rapid Positioning Time + Deceleration Time.

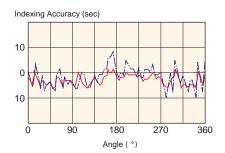
MAX. moving angle is 180°. Therefore, not only rapid positioning time, but also acceleration/deceleration characteristics is very important. The graph at right hand side shows that CNCZ202 (high speed), with it's excellent acceleration/deceleration capability, gives a very substantial time saving of approximately 300 msec. on this 90° movement comparing with CNC202 (standard).

**CNCZ202**: 500 msec. **CNC 202**: 800 msec.

Item	Rapid Positioning Speed	Acceleration/Deceleration Time Constant
_	44.4 min <sup>-1</sup>	150msec
_	22.2 min <sup>-1</sup>	100msec



Item	Using Years	Indexing accuracy
_	At installation	Cumulated 10sec
	After 7 years	Cumulated 17sec



## ③ Durability

In 24 hours continuous operation, durability is one of the most important conditions.

Thanks to Carbide Worm System, NIKKEN CNC rotary table ensures highest anti wearing nature even at the severest load conditions with high speed indexing. The graph at right hand side shows the worm wheel & worm screw and accuracy inspection of the table having been used for 7 years on CNC special purpose machine in production line of automobile parts plant.



Worm System after 7 years used.

## **Technical Information**



#### Specification of the rotary table to be used on the special purpose machines.

- 1. Custom made on the Table Face Plate
- · Drilled hole, tapped hole, or dwell pin hole etc.
- ·Without T-slot or with T-slot
- · Additional process at center hole
- 2. The location of the Oil Sight Grass, Oil Supply Port and Drain Port can be changed.
- 3. How to be mounted on the Machine
  - U-groove
- · Additional tapped holes on the backside
- · Shift the guide key position
- 4. Modification of the Motor Cover
- 5. Rotary Joint P.89
- 6. Built-In Pallet Clamping System P.96
- 7. Special Color P.96
  - ·Please order with the color sample or Munsell Color No.

When rotary table is used for horizontal use, there is no portion of the table body to be clamped for vertical use







CNC401 without T slot for horizontal use

CNC302T without T slot

CNC202L without T slot

## Selection of the CNC rotary table

- The support table is basically used in case of vertical application.
- The machining operation is generally light cut on aluminium materials, however, if the fixture or the component is large size, please make sure that the fixture inertia is within the MAX. work inertia.
- If the unbalance load is too big, it will affect on not only the indexing accuracy but also the durability. Please make sure the unbalance load will be within the following figures. P.57
- In case of the unbalance load is large,
  - -The high speed Z series rotary table is not suitable, please use standard rotary table.
  - -Please installing the balance cylinder or counter balance.
- -Please advise us the details of the component, fig fixture, indexing time etc. prior to your order, and we will make a calculation of the load and select the best suitable rotary table for your application.
- If the huge amount of coolant has to be applied, we could prepare air purge (with pneumatic pressure of 0.03MPa) on the CNC rotary table body as an option. Please contact us the details.





# Check point for trunnion fixture

When installing the table onto the sub-base, measure and check as follows.

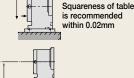


between table & sub-base is recommended within 0.01mm

Center lines are recommended



Difference betwee table center and sub-base center is recommended within 0.02mm



Difference of center height

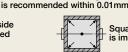
3Trunion fixture is recommended to be aligned as follows.

②Install the table & support table onto the M/C as follows.

Squareness between center line & these

within 0.02mm

Center of both side are recommended within 0.01mm



is important



#### Caution

- Always be careful not to inflict personal injury on any shop objects when unpacking this equipment.
- Caution should always be used when lifting this product. Especially when using lifting equipment. Manual lifting of this product may cause serious back injury. Always use safe lifting techniques.
- Install the rotary table on a well ventilated place hidden from direct sunlight, on a place not exposed to corrosive gas such as sulfuric acid and hydrochloric acid. Do not install the rotary table on a place with excessive high/low temperature. (Normal operating temperature: 5°C~40°C)
- Under the lower temperature condition, please warm the rotary table up just after power on. Or, please use lighter lubrication oil as another solution.
  Only the specified power voltage should be used. Incorrect power
- supply may result in fire.
- Always power off the machine before attempting any installation and wiring work. Failure to do this may result in serious personal injury or electric shock.
- The machine on which CNC rotary table is installed should have a complete cover or splash guard.
- When installing this product onto a machine tool, always pay special attention to the location of cables, hoses and hydraulic tanks (if used), to check for interference.
- Please make sure that all cables and hoses are sufficiently long to allow full axis travel.
- Always ensure that there is no interference with the CNC rotary table or tailstock unit of the ATC (Automatic Tool Change) position.
- Always ensure safe cable runs according to the instruction manual in order not to interfere with the machine operation. It is dangerous if the cables become entangled with the machine table or spindle unit.
- Always check the parallelism and squareness of the table to the machine axes and fix to the machine table using the fixings provided.

- Please follow the instruction manual for installation, wiring of cables and hoses. Failure to connect wiring correctly may cause fire or a serious accident.
- This table has been given a waterproof treatment, however if ingress of coolant should occur, stop using the table immediately. Failure to do so may result in the unit catching fire or causing serious electric malfunction.
- Always ensure that pneumatic or hydraulic hoses are connected correctly. Always keep the air filter clean to prevent water and dirt ingress from the air supply
- Please ensure that the hydraulic pressure flows constantly on the pump line at brake clamp in the save energy type hydraulic circuit.

  Please use CNC rotary table within the specification. Exceeding
- the specification may cause defective components and irreparable damage. Please contact us in case of the beyond the specification before ordering. P.104
- Never modify the table by yourself without previous agreement of NIKKEN
- Never to touch any moving parts. Failure to follow this instruction may result in serious personal injury
- For the rotary table with the NIKKEN controller, firstly turn the power of NIKKEN controller off, then turn the power of main M/C off at the end of operation. Always remove swarf from the table after use. Long term operation
- without cleaning may cause damage to the internal mechanism.

   Always change the lubrication oil annually to prevent the gear wear.

- If a collision occurs with the table, power off the machine controller immediately and contact your distributor for repair.
   Always stop using the table if unusual noises are heard or the slackness or defection of work piece and jig fixture are found. Irrepanable damage may be happened. Please contact with your distributor for repair.

# Headquarter





Turning Machining Grinding Assembling Inspection

## **Technical Center**

Technical Development Office Production Engineering Room Seminar Room

## Factory No.2

Grinding Assembling Inspection Warehouse



## Carbonizing & Sub-Zero Treatment

**NIKKEN** is the only tooling product manufacturer which performs sub-zero treatment for tooling. This refers to a technique where -90 deg. ultra-low-temperature processing is performed after carbonizing and quenching in order to eliminate the residual austenite and to form 100% martensite compositions to prevent deterioration over time. This technique has been applied for block gauges and for bearings of the highest grade in the past. It is an example of how **NIKKEN** pays attention to those aspects which are often hidden from view and how we put our hearts and souls into each and every tooling product.



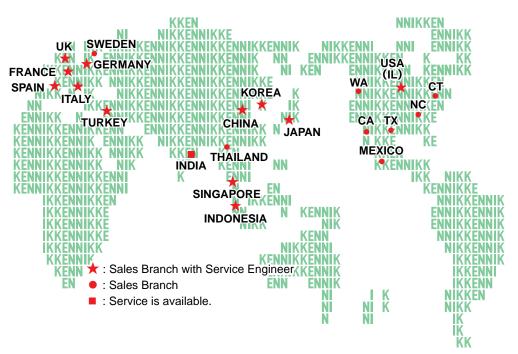
## Ion Nitriding

Ion nitriding refers to a nitriding process where glow discharges are generated in a vacuum of a nitrogen-mixed gas atmosphere to heat the workpieces at a low temperature of 450 deg. while at the same time nitriding them by a sputtering action. This processing improves both the wear resistance and sliding performance. (It reduces the surface friction coefficient.) The experience and know-how of ion nitriding have been utilized in a large number of NIKKEN's products, including worm wheels for CNC Rotary Tables and Tough-Cut Skill Reamers.

## **NIKKEN SERVICE NET WORK**



There are overseas Sales Branches in 14 countries. Each sales branch has stocks for toolings and CNC Rotary Tables, and service engineers look after the maintenance and service operation of our products. In the other region, e.g. East-South Asia, Ozaena, South America, Africa, etc., there are some distributors. At the production line in abroad, as there are many requirements for special tools and CNC Rotary Table to suit the special specifications, please ask us or distributors for spare tools and maintenance parts in advance.





LYNDEX-NIKKEN (U.S.A.)



**NIKKEN EUROPE & NIKKEN U.K (UK)** 



**NIKKEN DEUTSCHLAND (GERMANY)** 



HERRAMIENTAS LYNDEX-NIKKEN (MEXICO)



PROCOMO-NIKKEN (FRANCE)



KOREA NIKKEN (KOREA)



**NIKKEN SCANDINAVIA (SWEDEN)** 



**VEGA INTERNATIONAL (ITALY)** 



OLASA(SPAIN)



**CUTTING TOOLS (SPAIN)** 



**NIKKEN CHINA (CHINA)** 



NIKKEN TURKEY (TURKEY)



SIAM NIKKEN (THAILAND)



**NIKKEN ASIA (SINGAPORE)** 



**NIKKEN INDONESIA (INDONESIA)** 

## Discontinuation of CNC rotary table repair work

We have been repairing our CNC rotary tables that are no longer manufactured. However, more than 20 years have passed since the discontinuation of the following models, and it has become difficult to obtain maintenance parts. Therefore, we will basically discontinue repair work as of April 2022 These CNC rotary tables are also out of date in terms of repid positioning speed and other mechanical specifications. As a replacement, please select a CNC rotary table with the latest functions from this catalogue.

# NIKKEN CHINA

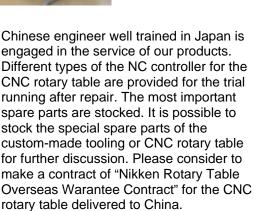
**NIKKEN** 

New Nikken China facility was moved to Qinzhou Road, Shanghai on 2014. JAN due to the business expansion in China. The standard items of NC tooling & CNC rotary table and each important spare parts are stocked for quick delivery.

You can access to Nikken China with Chinese, Japanese or English. Not only Chinese catalogue but also Chinese instruction manual are provided for Chinese domestic market. Our office has the show room to see and touch our products, and our presentation will be done more practically. Technical seminar of Nikken is also opened at user factory side.







The sales of nikken products through Internet is not started in China. For after service and the further maintenance, please purchase Nikken products through authorized distributors.



# LYNDEX-NIKKEN (NIKKEN USA)



As North America's leading supplier of machine tool accessories, LYNDEX-NIKKEN is a wholly-owned subsidiary of NIKKEN Kosakusho Works., Ltd. - Japan. Backed by over a half century of experience, LYNDEX-NIKKEN sets the standard for high quality and high technology with a complete line of superior toolholders and machine tool accessories. From one source you can expect the best of both worlds: Extreme Quality and Advanced Technology.

LYNDEX-NIKKEN has a team of dedicated application and engineering staff available to advise you on your machining applications and to support our entire product line throughout the U.S., Canada, Mexico and South America. Our regional managers in Chicago, Los Angeles, Boston, Charlotte, Dallas and Seattle support our 1,000 plus distributors with machine tool accessories expertise.

LYNDEX-NIKKEN provides expert process and product consultation for even the most demanding applications with full on-demand field support and ongoing training.



The LYNDEX-NIKKEN North America headquarters is centrally located near Chicago, Illinois. Our 50,000 sq ft. facility houses an inventory of over 12,000 machine tool accessories stocked for fast delivery. Over 95% of orders are shipped out same day. Our extensive inventory of products includes:







#### **Products**

- Rotary Tables NIKKEN's complete line of CNC Rotary Tables are known worldwide for their wear-resistance, rigidity and high-speed rotation. NIKKEN rotary tables are built to provide high accuracy, increased production and a trouble-free long life.
- Advanced Toolholders Maximize the potential of your machine tools with LYNDEX-NIKKEN's advanced toolholders.
- **Standard Toolholders** LYNDEX-NIKKEN's complete range of quality-driven toolholding solutions are designed to meet your strictest requirements.



## **Service & Support**

- Dedicated application and engineering support staff
- Support for entire product line covering the U.S., Canada, Mexico and South America
- On-demand field support and ongoing training
- Customer service and technical support staff
- Expert process and product consultation for even the most demanding applications
- Cutting trials and testing
- Service, repair and custom configuration completed on-site
- Attention to high-tech application demands, including high-speed and balanced toolholding solutions



# **NIKKEN EUROPE (NIKKEN UK)**

**NIKKEN** 

The NIKKEN Euro Centre based in the UK was opened in 1999; from here we sell, distribute and support all products to our subsidiaries and dealers in over 20 countries around Europe.

In addition to carrying out the functions of NIKKEN UK in the United Kingdom (UK), we employ forty staff members and engineers. At the end of 2015, NICE (NIKKEN Innovation Centre Europe) opened in the AMRC manufacturing technology park, where it provides support to customers working with difficult-to-machine materials, particularly in the aviation and energy industries.





#### **Product Inventory**

NIKKEN Euro Centre facilities has a warehouse space of 13,000m<sup>2</sup>. which holds over 50,000 individual items covering a range of some 4,000 product lines, including the latest generation of Single & Multi Axis CNC Rotary tables, thus making it the largest stock of NIKKEN products in Europe.

# Our Technical Support and Training Section provides our existing customers and potential customers access to:

- A Multimedia based training facility that ensures our customers, through comprehensive training, will realize the full productivity potential of their application.
- A wealth of engineering expertise covering all aspects of application set-up, optimization and implementation that is available for the full life of the NIKKEN product.





# Our machining centre equipped with Testing Facilities enables us to:

- Research, develop and optimize all of our tooling systems.
- Demonstrate to our potential customers the advantages of using both NIKKEN Tooling and CNC Rotary Tables in their applications.

#### Our Service Department specializes in:

- Providing on-site inspections prior to rotary table repairs and refurbishment by our own NIKKEN trained service engineers.
- Providing tooling and rotary tables optimized to seamlessly integrate into any application.



# **NIKKEN DEUTSCHLAND (NIKKEN GERMANY)**



Nikken Deutschland GmbH, a wholly owned subsidiary in Germany of NIKKEN Kosakusho Works, was established in 2003 to take over the sales activities of the previous distributor. In the beginning based in Russelsheim, which is a town made famous by the manufacturing complex of Opel, the company was located about 15 minutes away by car from Frankfurt airport. Germany has ranked at the top of the machine tool industry for many years, and is also the supply source of machine tools that are fuelling the significant expansion now taking place in Eastern Europe. Nikken Deutschland GmbH had its base at the centre of the huge market of Germany and Eastern Europe, and continues to broaden the range of the company's sales operations from NEU-ULM naw.

NIKKEN has achieved some impressive successes in Germany with its CNC rotary tables and tool holders thanks to a long sales history of the company's sales activities. A sales force consisting mainly of German personnel stands on the front line of this activity to address the sales and servicing needs of the entire country. More specifically, the company provides technical advice, repairs, aftersales support and other services to end users, distributors and machine dealers.



To enable speedy delivery of standard items in the German market and of popular products compliant with European standards, Nikken Deutschland GmbH works closely Nikken Euro Centre to keep a full stock at its disposal. The company uses the most appropriate type of delivery in each case, including parcel post, DHL, door-to-door service and flash shipment, to meet the demands of customers.

The sales territory of Nikken Deutschland GmbH spans the vast area of eastern Europe and covers such countries as the Czech Republic, Slovakia, Austria, Russia, Poland, Hungary, Romania and Bulgaria, all countries in which Japanese companies are rapidly expanding their business. The service is not limited to sales, but engineers make on-site adjustments, repairs and service calls as well.



Nikken Deutschland GmbH has participated in and contributed to many trade shows and exhibitions held in Germany, including the EMO show, METAF, AMB and EURO MOULD. The company's fully furnished showroom is a Mecca of information to the constant stream of visitors who can inspect products and examples of machining, as well as receive application advice and technical training. They can handle NIKKEN's products for themselves, learn about the construction and capability of the CNC rotary tables, and learn about the accuracy and other features of NIKKEN's products.

A complete support organisation is in place to ensure that advice is relayed promptly by telephone and other rapid communication media, that repairs or delivery of tool holders and CNC rotary tables are carried out promptly with all due diligence, and that emergency service calls are responded to rapidly.

To make it possible to support all types of motors and controllers for NIKKEN's CNC rotary tables, the company has set up trial run equipment that accommodates many different motors, and offers a full range of accessories including tailstocks, support tables, scroll chucks and collet chucks adapted to the CNC rotary tables. The fact that NIKKEN's CNC rotary tables are endowed with outstanding durability and that a complete support service is provided instil confidence in users that the equipment will give outstanding service in the years ahead.

# SERV

# PROCOMO-NIKKEN (NIKKEN FRANCE)



Procomo France S.A.S was established 30 years ago with the avowed intent to deliver the high-accuracy and high-quality tool holders and CNC rotary tables as well as related services, applications and after-sales servicing, into the hands of engineers in France. A major milestone in the company's history was marked in 2006 with the change of the company name to PROCOMO-NIKKEN, and the company took on a new lease of life as NIKKEN's wholly owned subsidiary in France.





In 2005, PROCOMO-NIKKEN embarked on a complete renovation of its buildings and facilities in order to make it possible for users to gain hands-on experience of NIKKEN's products in a bright and comfortable environment.



In the meeting room, which is fitted out with all the latest multimedia technology, technical seminars are regularly held so that attendees will come away with a clear understanding of NIKKEN's products and technology. The showroom is where videos of cutting operations are screened, and visitors can actually handle some of NIKKEN's products in this room as well. The machining center, which is used for cutting trials, enables visitors to

identify what makes NIKKEN's products different from those of other companies and to judge how impressive are the machining accuracy and advanced cutting capabilities of NIKKEN's products. As the top tool holder manufacturer, NIKKEN believes is that once customers have their own personal experience of the low machining noise, attractive-looking cut surfaces and uniform discharge of chips, they will be convinced that they can completely trust in and depend on the expertise and capabilities of the company.









The stocks of a large number of standard products are always on hand, enabling the products that customers need to be delivered in the shortest possible time. The NIKKEN Euro Centre and PROCOMO-NIKKEN retain constant and close contact; together they take on the challenge of how to machine products in a more rationalized manner, in a shorter time and to a higher accuracy so that France's engineers can meet every need of the French marketplace.

NIKKEN has already earned an enviable reputation in the global marketplace for the high accuracy and outstanding wear resistance of the company's CNC rotary tables. PROCOMO-NIKKEN has a team of five engineers dedicated full-time to providing users with application support prior to placing orders for tool holders and CNC rotary tables and to carrying out the preparation for shipment, education and training programs, maintenance and repairs, and servicing. This support network delivers a wide range of services, while willingly taking up the challenge of coming to grips with new applications.

Independent optimization system for Industry - 4.0

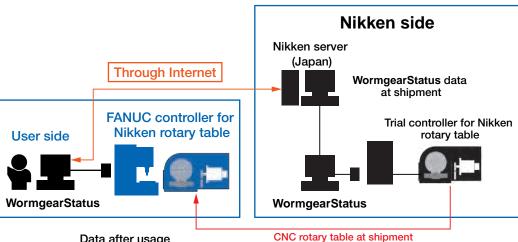
# WormgearStatus / BacklashStatus



From March 2020, the WormgearStatus data are collected at shipment for all CNC rotary tables with FANUC motor. As a result, the WormgearStatus service and BacklashStatus service are available as optional paid services. Please refer the contents of these services below.

If you would like these service, please contact us. The actual expenses for transportation and accommodation are required separately.

The key items are the CNC rotary table type and serial number. It is necessary to write the control program for WormgearStatus / BacklashStatus to the user's FANUC NC controllers.



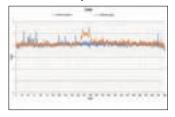


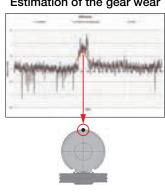
Data after usage

Table type and serial number

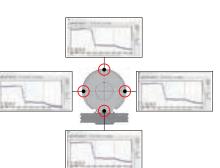


Comparison





#### Estimation of the gear wear



#### ■WormgearStatus service JAPAN, USA, EU, China: PAT.P.

WormgearStatus data is the torque data, when the full stroke of a CNC rotary table (example: rotary axis: 0 ° to 360 °, tilting axis: 0 ° to 105°) is rotated at 360 deg/min. **WormgearStatus** data at shipment is collected and stored according to the CNC rotary table type and serial number in the Nikken server in Japan. WormgearStatus data after usage will be collected locally and compared with the data at shipment, then estimate the gear wear position.

#### ■BacklashStatus service JAPAN: PAT, USA, EU, China: PAT.P.

BacklashStatus will be checked the backlash amount without manual intervention to the position, where gear wear is estimated;

- 1) The angles, that is estimated as the gear wear position by WormgearStatus, will be checked.
- 2) For the CNC rotary tables on NC single purpose machine, the angles to be positioned are fixed and always same positions. In this case, enter these angles to be checked, and activate BacklashStatus.
- 3) If required, backlash compensation function and pitch error compensation function can be utilized without manual intervention for better positioning accuracy.

WormgearStatus / BacklashStatus uses FANUC Servo Guide. WormgearStatus / BacklashStatus is a registered trademark in Japan.

# SERV

# Check Sheet for the Technical Specifications of CNC ROTARY TABLE **NIKKEN**

Last user name () Destination country ()	
CE mark ☐ Necessary ☐ Not Necessary	
1. Machine tool builder (	
2. Machine model (	
3. T-slot width ( ) / pitch ( ) / number of slots ( )	
4. How to install the rotary table    Vertical and Horizontal    Vertical only    Horizontal only	
5. Control method ☐Additional axis ☐AR21 or EZ controller (use M-signal)	
Rotary axis ( W) Tilting axis ( W)(5AX only)	
6. Numerical Control (Manufacturer: ) (Model: )	
7. Servomotor  Servomotor included  Servomotor supplied (expected date to be supplied: MM/DD)  Servomotor not included	ded
8. Servomotor model : (	
9. Clamping System ☐ Pneumatic〔 MPa〕 ☐Hydraulic〔 MPa〕 ☐Booster	
10. Voltage of the solenoid   AC100V   DC24V   Unidentified (confirmed with the drawing for approve	/al)
11. Clamping circuit of the solenoid OFF:Clamp ON:Clamp Unidentified (confirmed with the drawing for appro	oval)
12. Direction of the cable comes out Side Back Top Other (	  -
13. Cable connection method	ļ
14. External wiring cable □Necessary □Not necessary	
15. Specified color   NIKKEN yellow   Others (Munsell Symbol number: )	
16. T-slots of table plate □Necessary □Not necessary	
17. Language of instruction Manual □Japanese □English	
18. Accessories □Tailstock □Scroll chuck □Power chuck	
19. Option ☐ High precise indexing ☐ Rotary joint ☐ AWC SYSTEM	
Notices [	